

LiDAR = Light Detection And Ranging ...also known as LASER altimetry
An increasingly common form of active remote sensing since ~2000

- contrast with Radio Detection and Ranging (RADAR) in the microwave

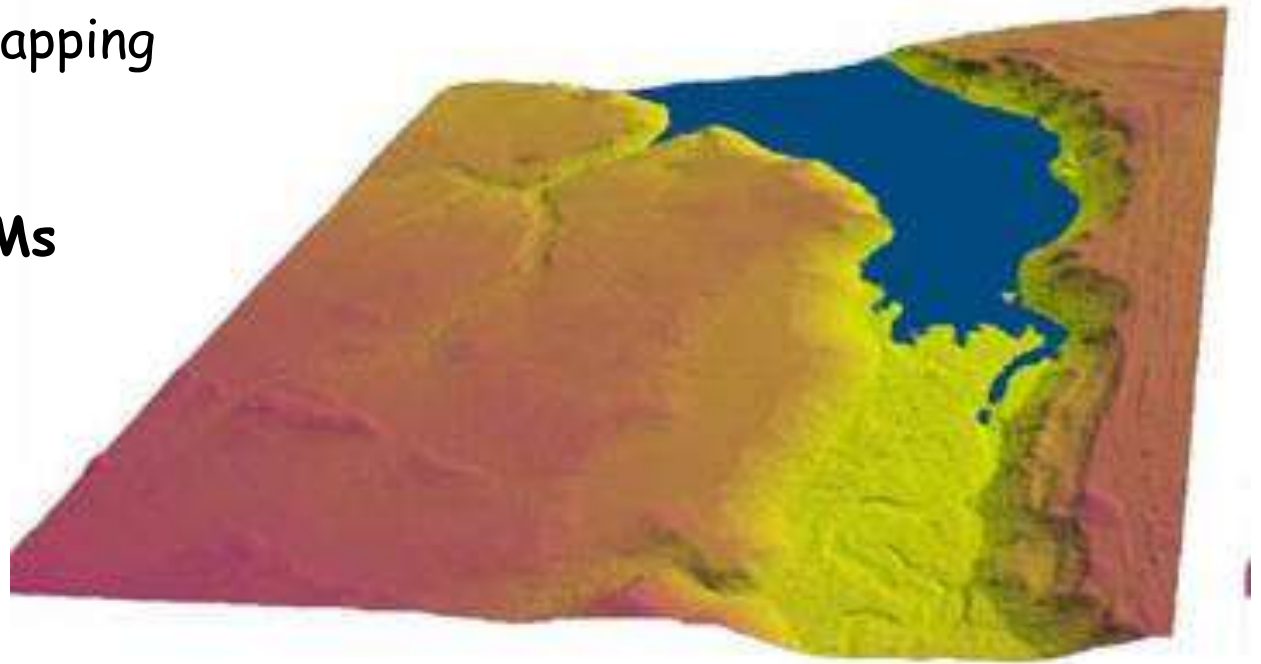
Objects reflect more in UV/visible/NIR (than radar microwaves)
= higher resolution mapping

- **high resolution DEMs**

e.g. for flood control

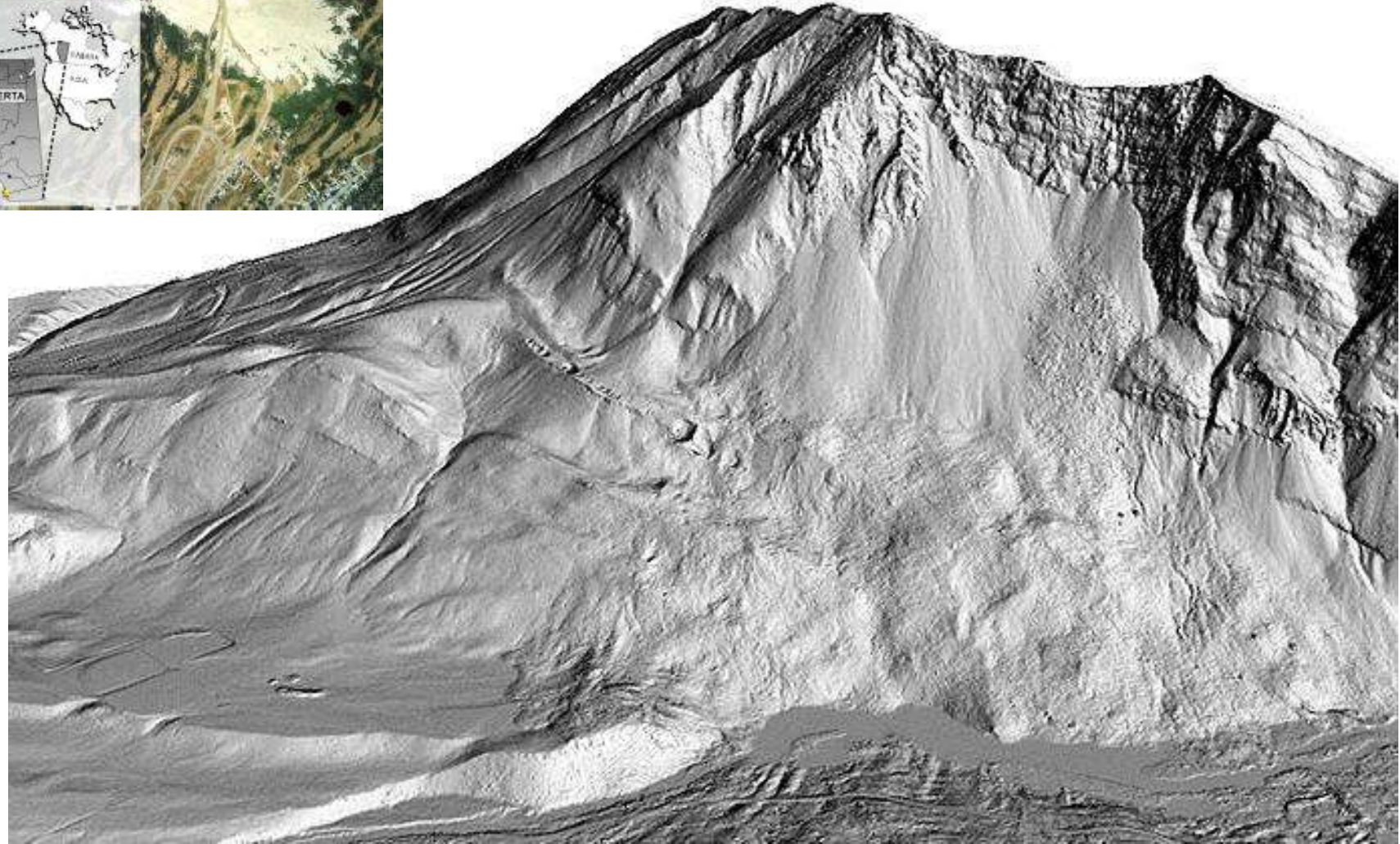
~1 foot or <1 m

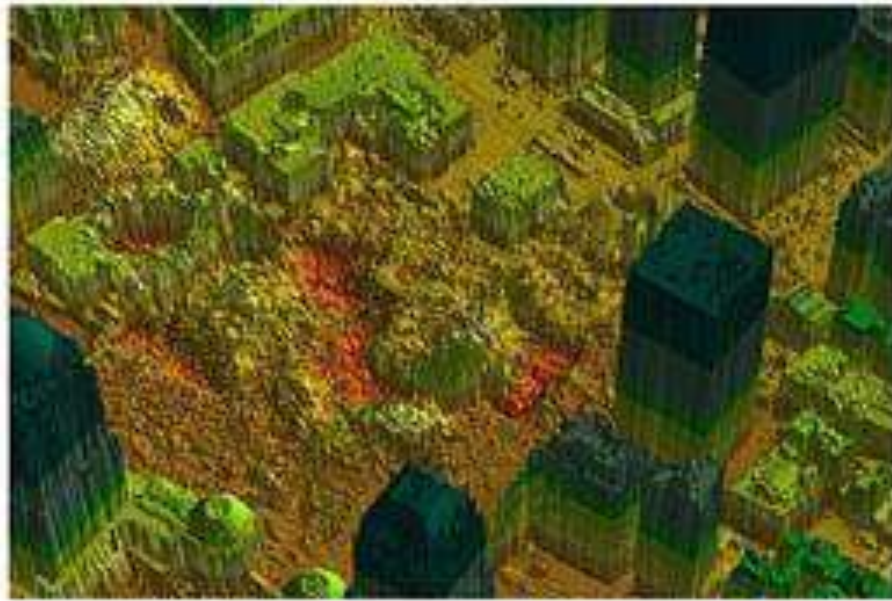
(mostly airborne)





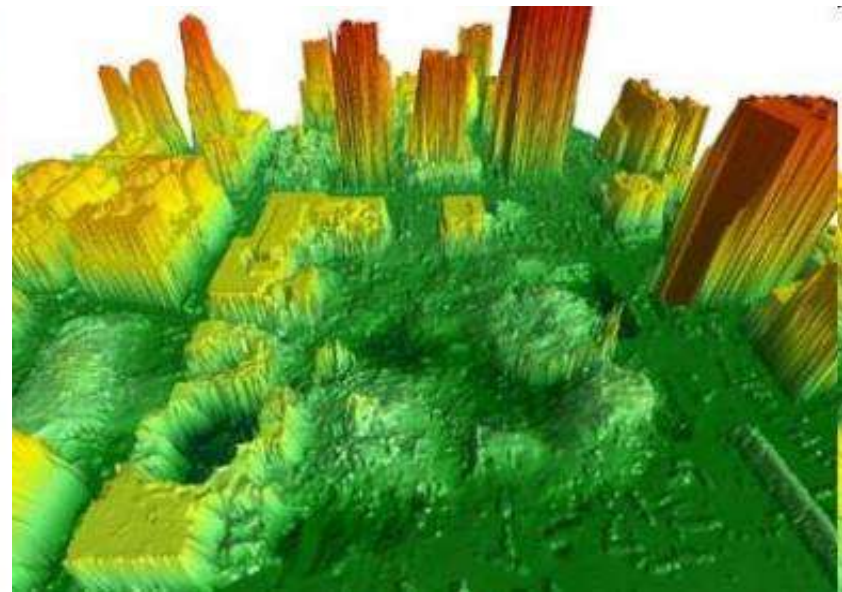
Turtle Mountain, AB (Frank slide, 1903) LiDAR DEM





**LiDAR Volume estimation:
Ground Zero, World Trade
Centre site, New York
post-September 2001**

<http://www.volker-goebel.de/Lidar.html>



What is LiDAR ?

Controlled bursts of LASER
(Light Amplification by Stimulated
Emission of Radiation)

Distance to object given by TIME

-requires 3 units:

-laser emitter/receiver

-GPS

-IMU (Inertial measurement unit)

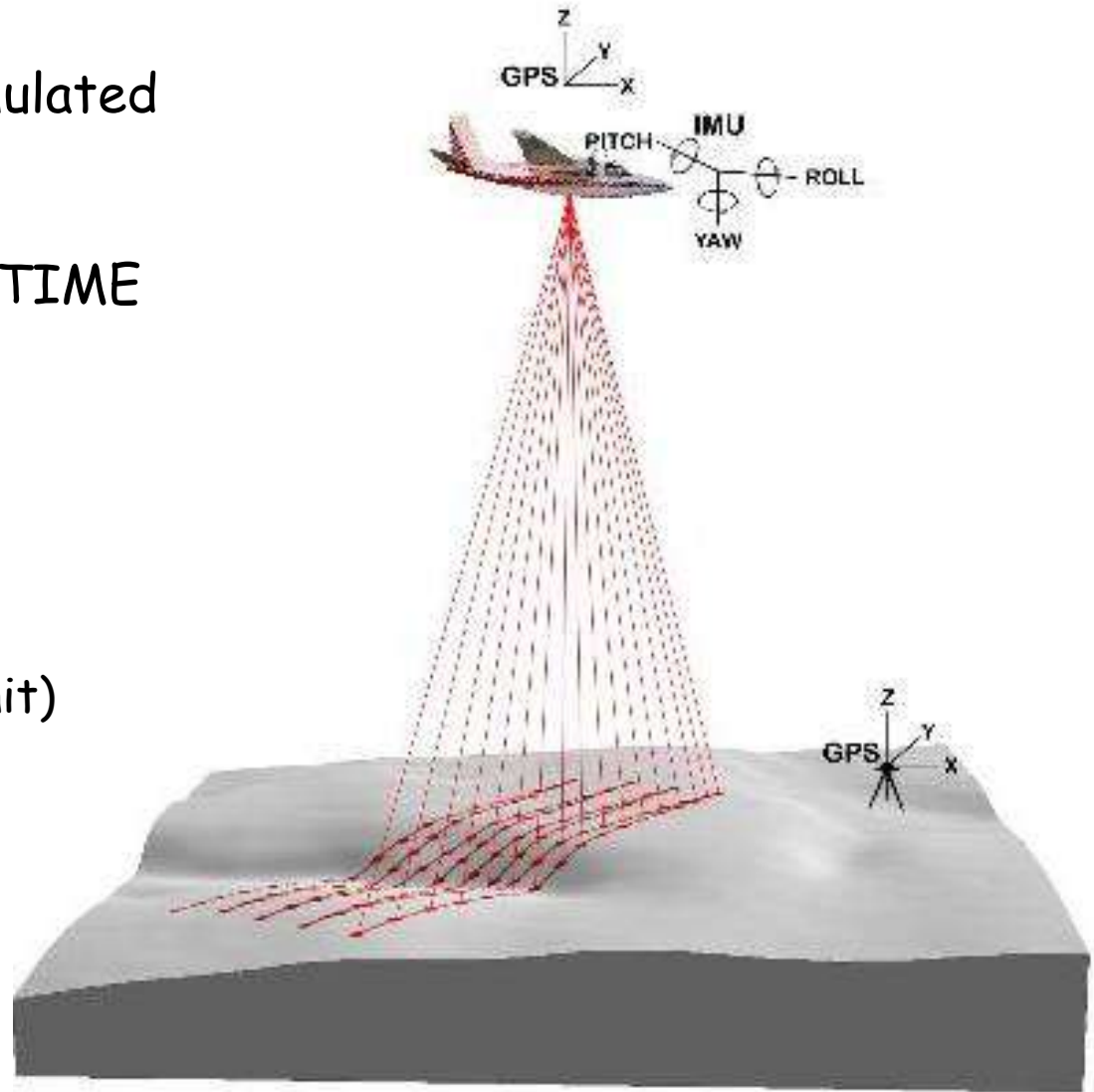
First developed in 1960s but

needed GPS technology for

detailed mapping -1980s

Expansion since 2000s,

Drone 2015, iPhones 2020

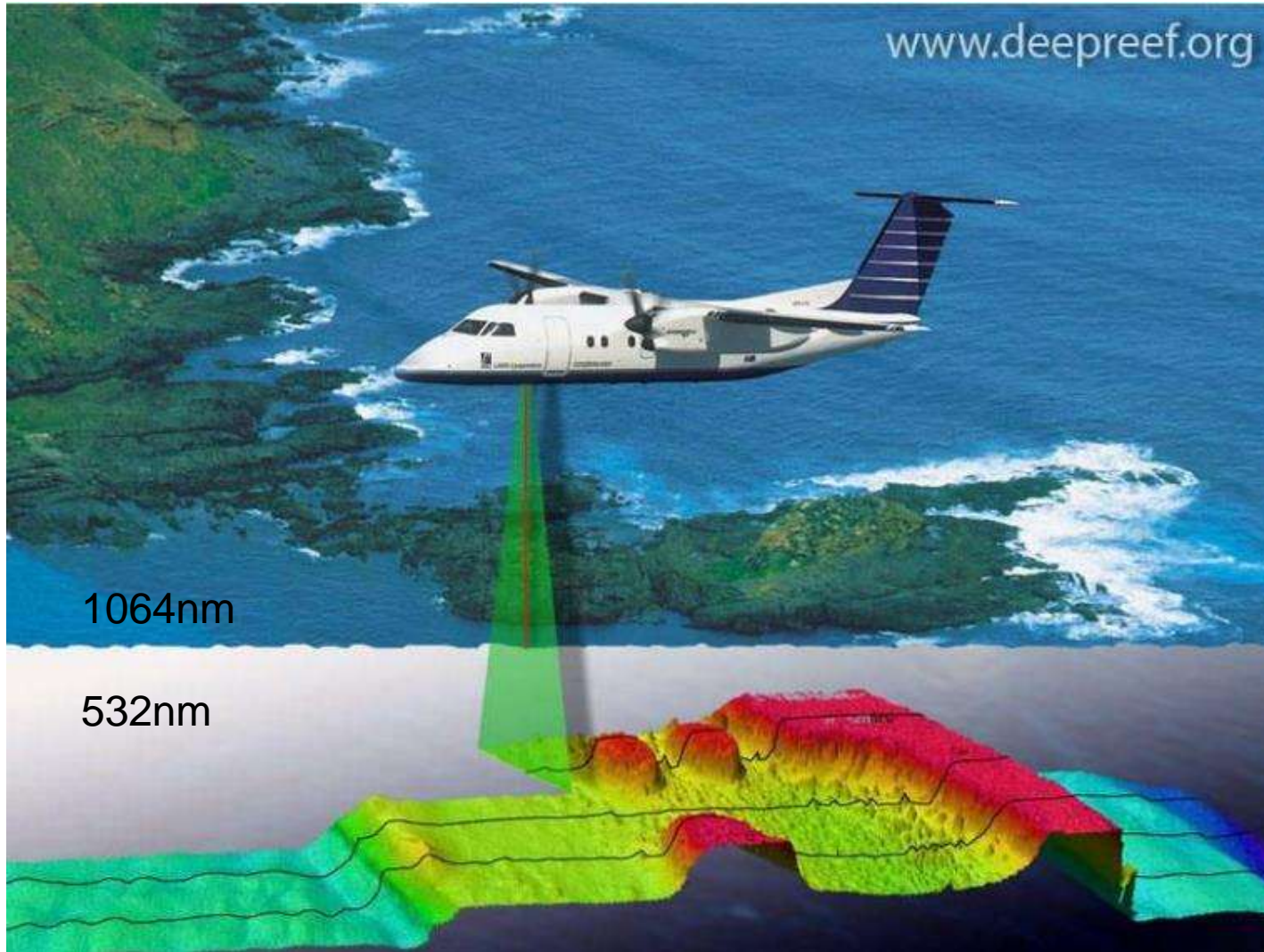


Related technologies:

SONAR: SOund Navigation and Ranging : sound propagation for communication/navigation

SODAR: SOnic Detection And Ranging : sound propagation upwards (atmospheric)

Laser Airborne Depth Sounder (LADS): Bathymetry



<http://www.navy.gov.au/laser-airborne-depth-sounder-lads>

Range finding LiDAR for topographic mapping

Unaffected by clouds above (unlike air photos) .. why?

Laser bursts are emitted usually at one of these wavelengths:

- 355 nm (UV): wind, water vapour
- 532 nm (green): bathymetry
- 1064 nm (Near IR): surface mapping

.... (why these ??? *) This was not solved by googling or LiDAR vendors

* I asked this every class and offered a 6-pack to who could solve this

Trivia: taser guns are at 650 nm; phasers (Star Trek) at 350nm

LiDAR - 1064 nm, 532nm, 355nm - why those wavelengths?

Lasers produce light the same way as a neon sign - a substance is stimulated to an excited state, causing the release of extra energy as a photon of light.

Nd:YAG (*neodymium-doped yttrium aluminium garnet*) is a crystal that is used as a lasing medium for solid-state lasers. It emits at a wavelength of 1064 nm.

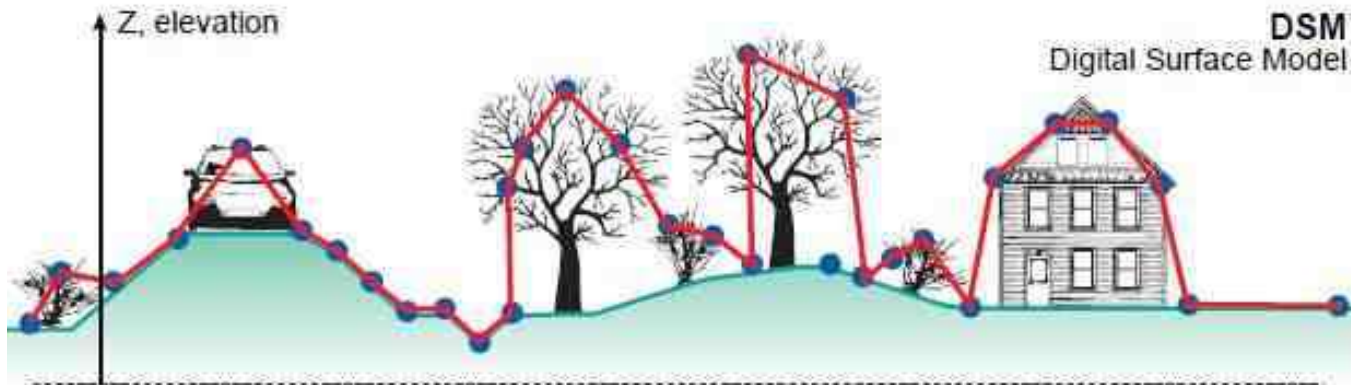
According to the Planck-Einstein equation:

$$E = \frac{hc}{\lambda}$$

Where h = Planck's constant, and c = the speed of light; halving the wavelength, has the effect of doubling the energy released, and one-third the wavelength (355) triples the energy (= the second and third harmonics)

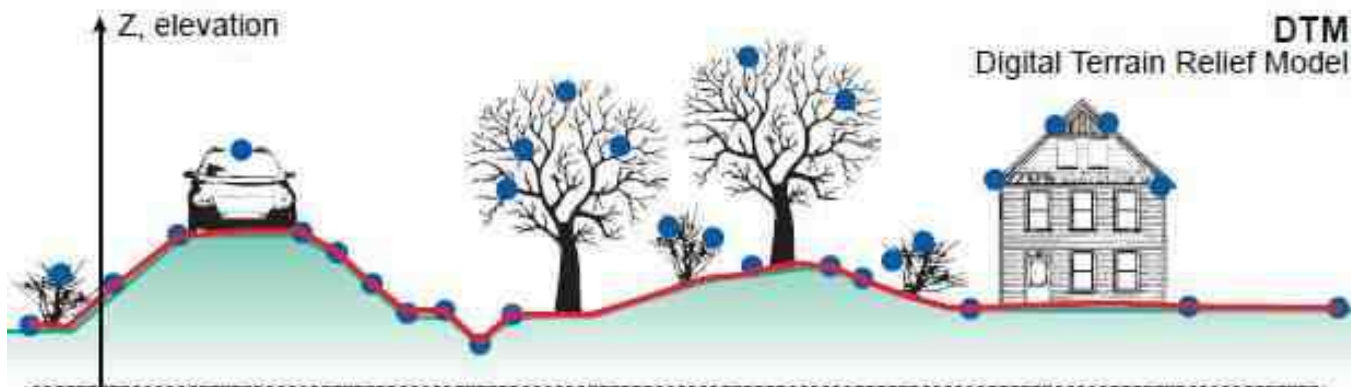
Solved by Patrick Daley, (Fall 2009) - won a 6-pack of Guinness

DEMs: DTM and DSM



Digital Surface Models

Spaceborne /
LiDAR



Digital Terrain Models

Photogrammetric /
LiDAR

'Bare Earth'

LiDAR is the only remote sensing system that can do both
- and thus give a measure of tree heights (and buildings)

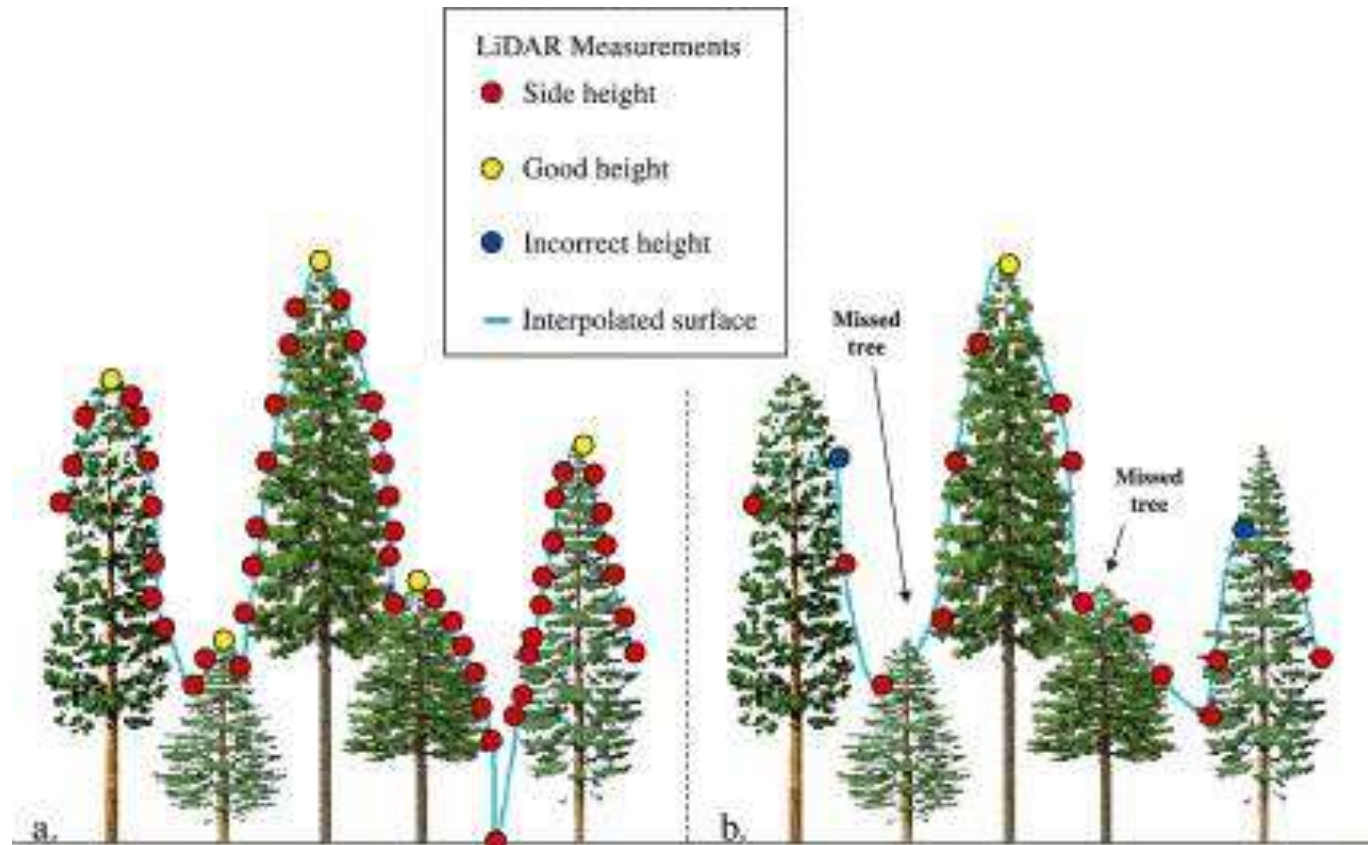
Laser pulses at up to 50,000 - 200,000 / second

Resulting cloud of points: up to 20 points / square metre

~10/m² needed for forestry 1/m² for glaciers (no trees)

Horizontal accuracy 50cm - 1m, vertical ~20cm

Cloud of points is converted to raster grid ~1 metre 'LAS tools'



Vegetation: Tree Canopy Height

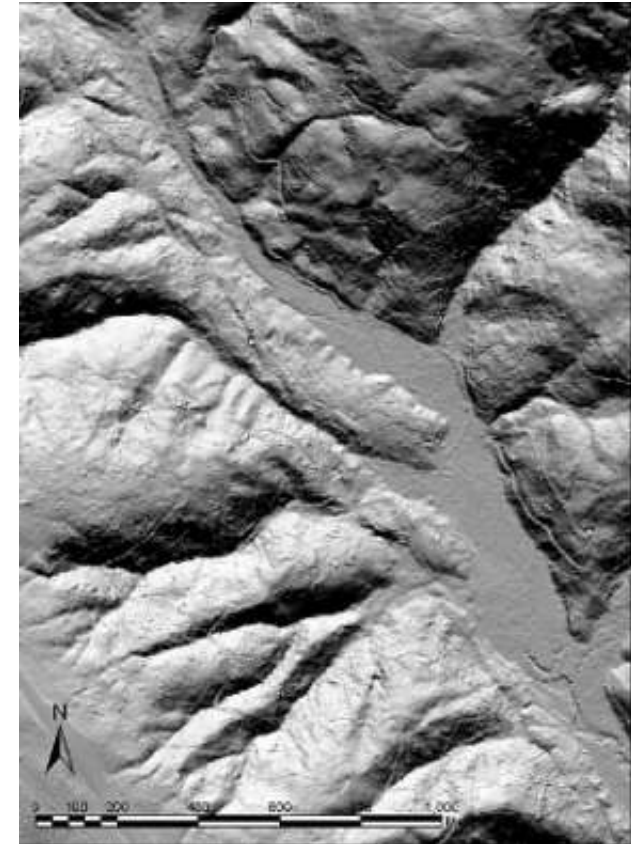
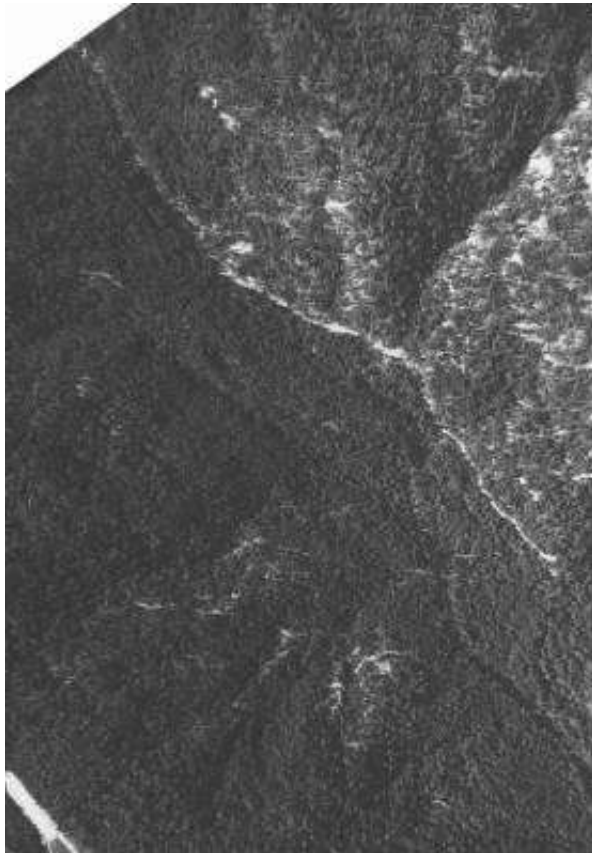
<http://quake.wr.usgs.gov/research/geology/lidar/example2.html>

Air photo

Vegetation surface DSM

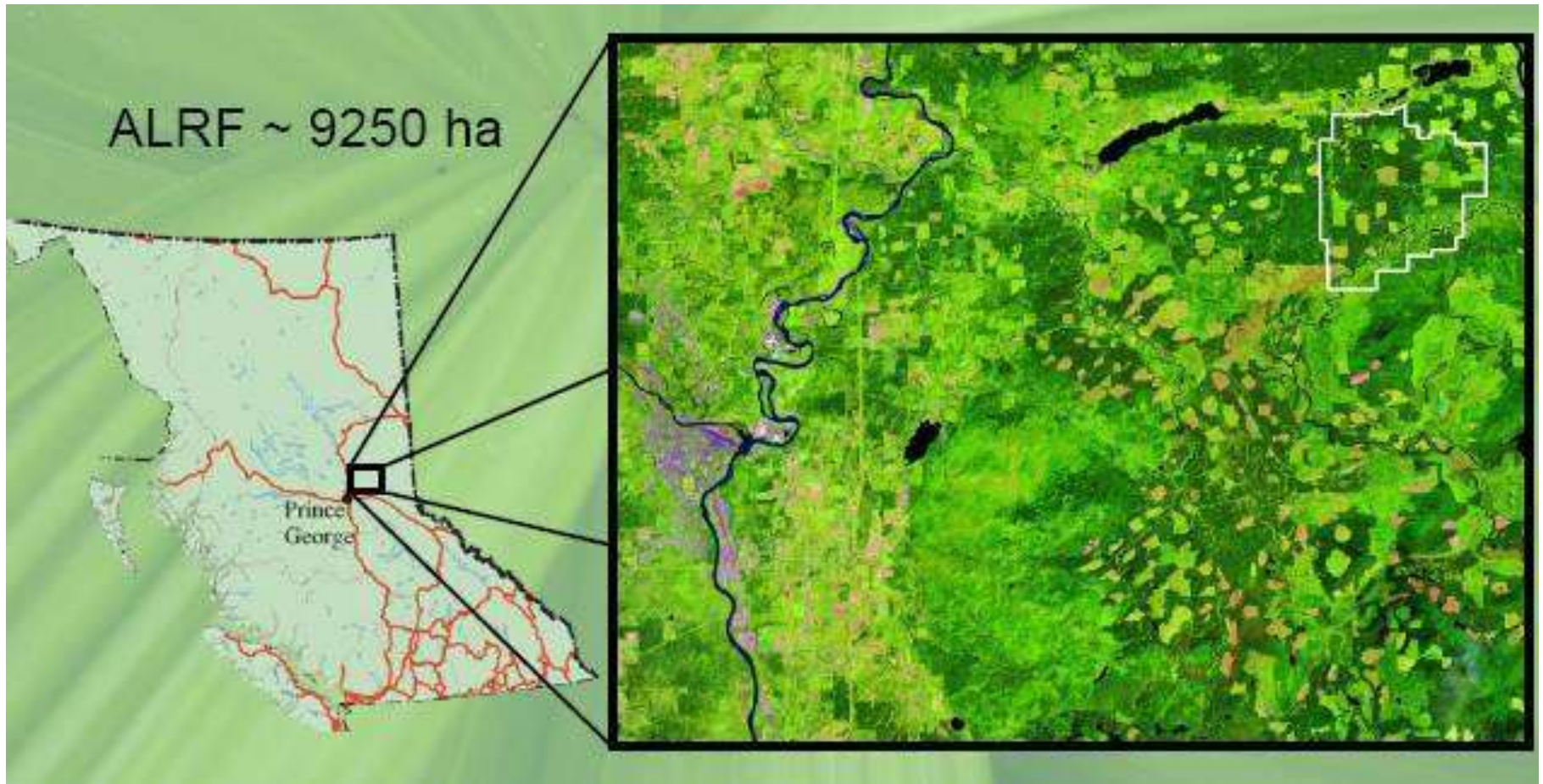
Bald Earth Model (BEM/ BEDEM)

Vegetation height = DSM minus BEM

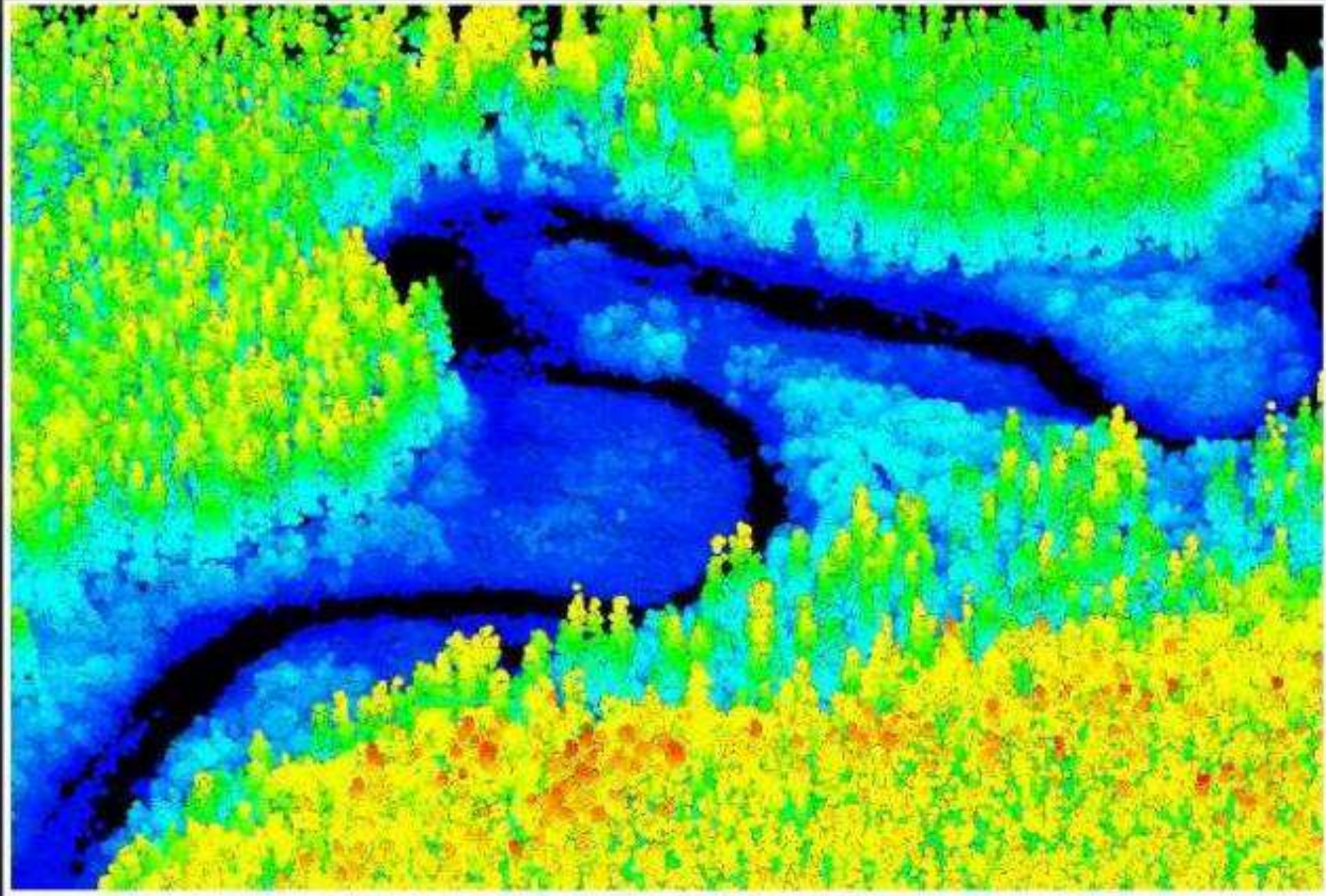


Aleza Lake Research Forest (ALRF)

Oldest research forest in BC, jointly operated by UBC and UNBC
60km north-east of Prince George, LiDAR mission 2005



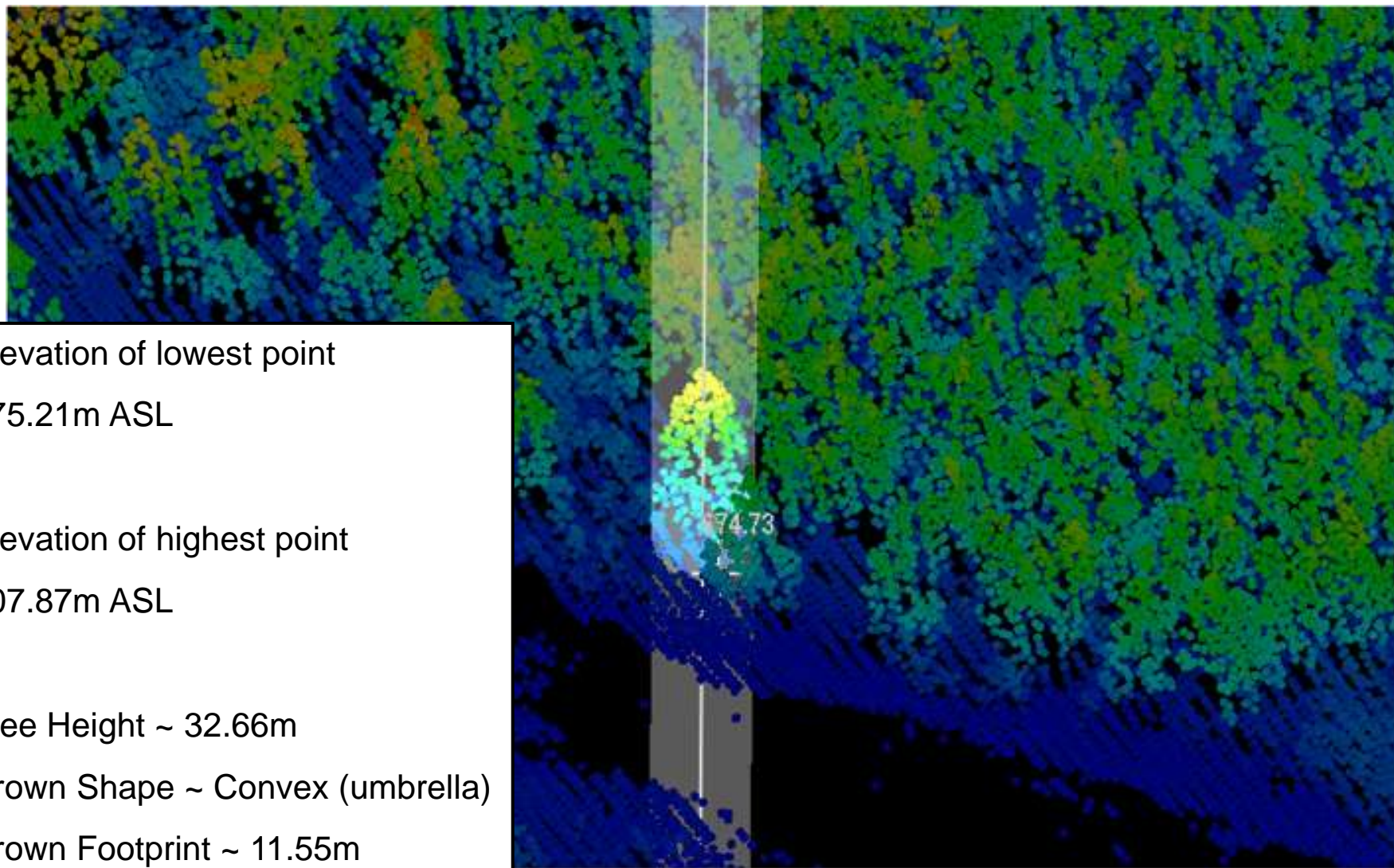
Mass Points



500m x 500m ~ 1,000,000 points

Cloud of points, colour coded by elevation, Bowron R. southern edge of ALRF

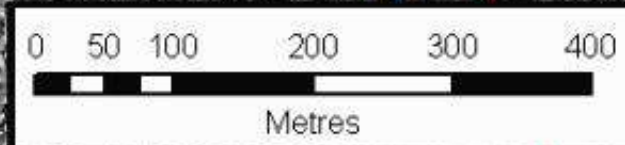
LiDAR reveals both 'bare earth' (ground) and canopy height ... and multiple vegetation layers - shrub layer, sub-canopy etc..



UNBC LiDAR datasets include UNBC campus, Aleza Lake RF, JPRF, Ancient Forest

Canopy Height Model

tree height = DN (brightness)



LiDAR Data Products

Mass points detailing elevation can be converted into:

- Bare Earth Model (BEM)
- Slope, Aspect, and Hillshade models
- Canopy Surface Model

Numerical models can be built to estimate:

- Species, volume, dbh, biomass

Canopy Surface Model

shaded relief draped on DEM, ALRF



Canopy Height = Canopy Surface – Bare Earth

Quantifying structural physical habitat attributes using LIDAR and hyperspectral imagery

LiDAR DEM / ISODATA classification

Environ Monit Assess (2009) 159:63–83



saltcedar



perennial pepperweed



Russian knapweed



Scotch thistle



hoary cress



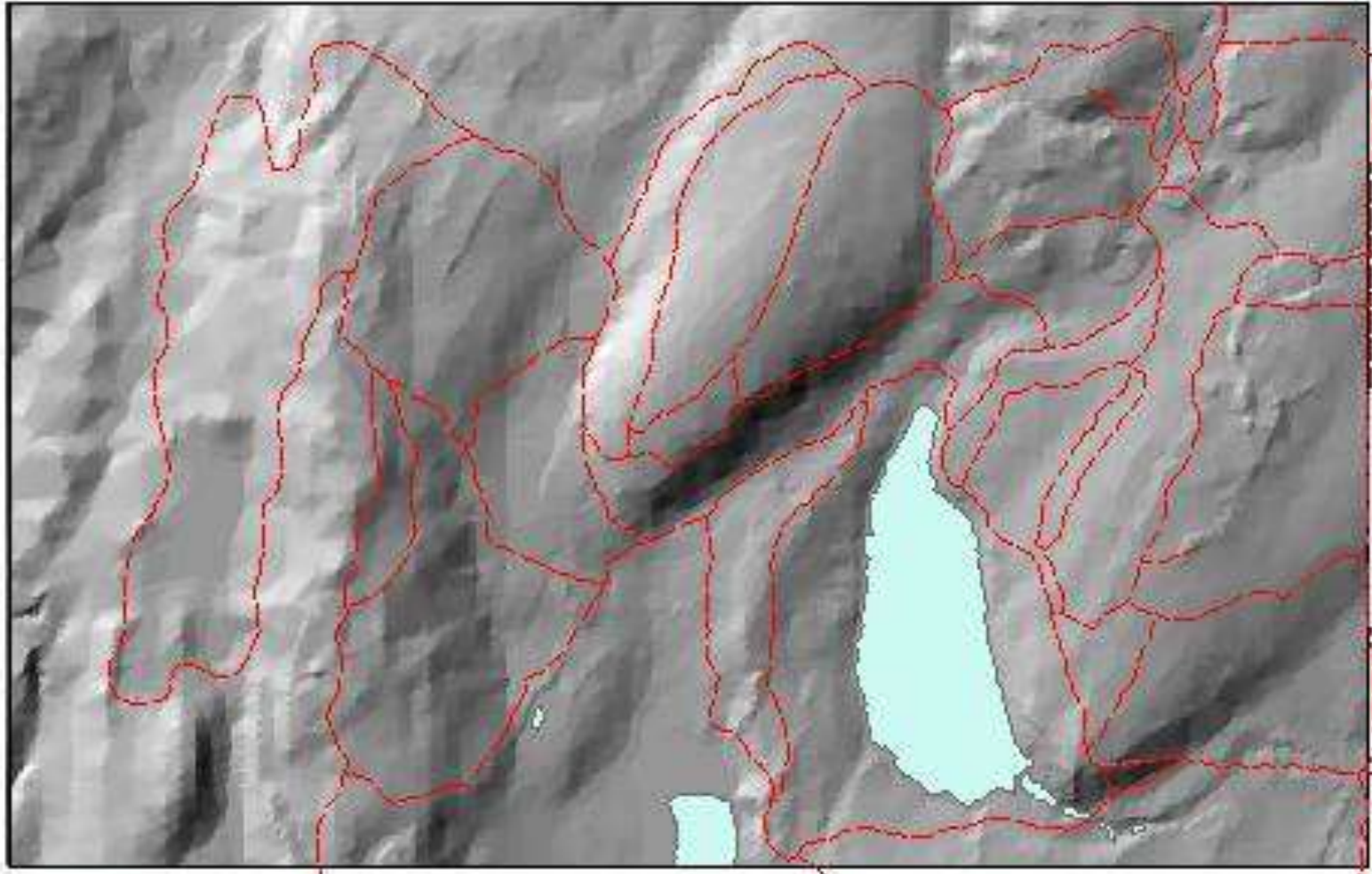
leafy spurge



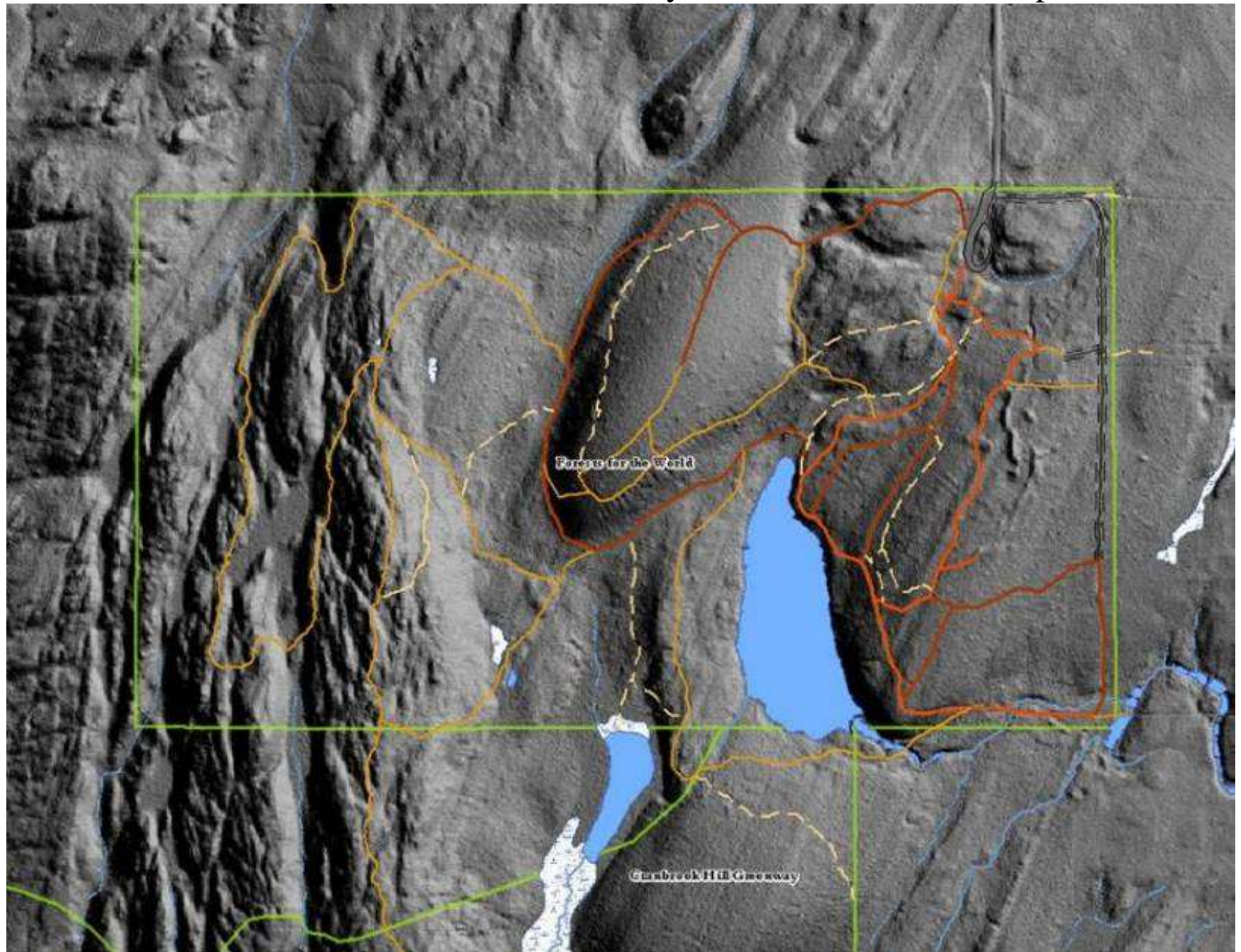
Forests for the World orthophoto



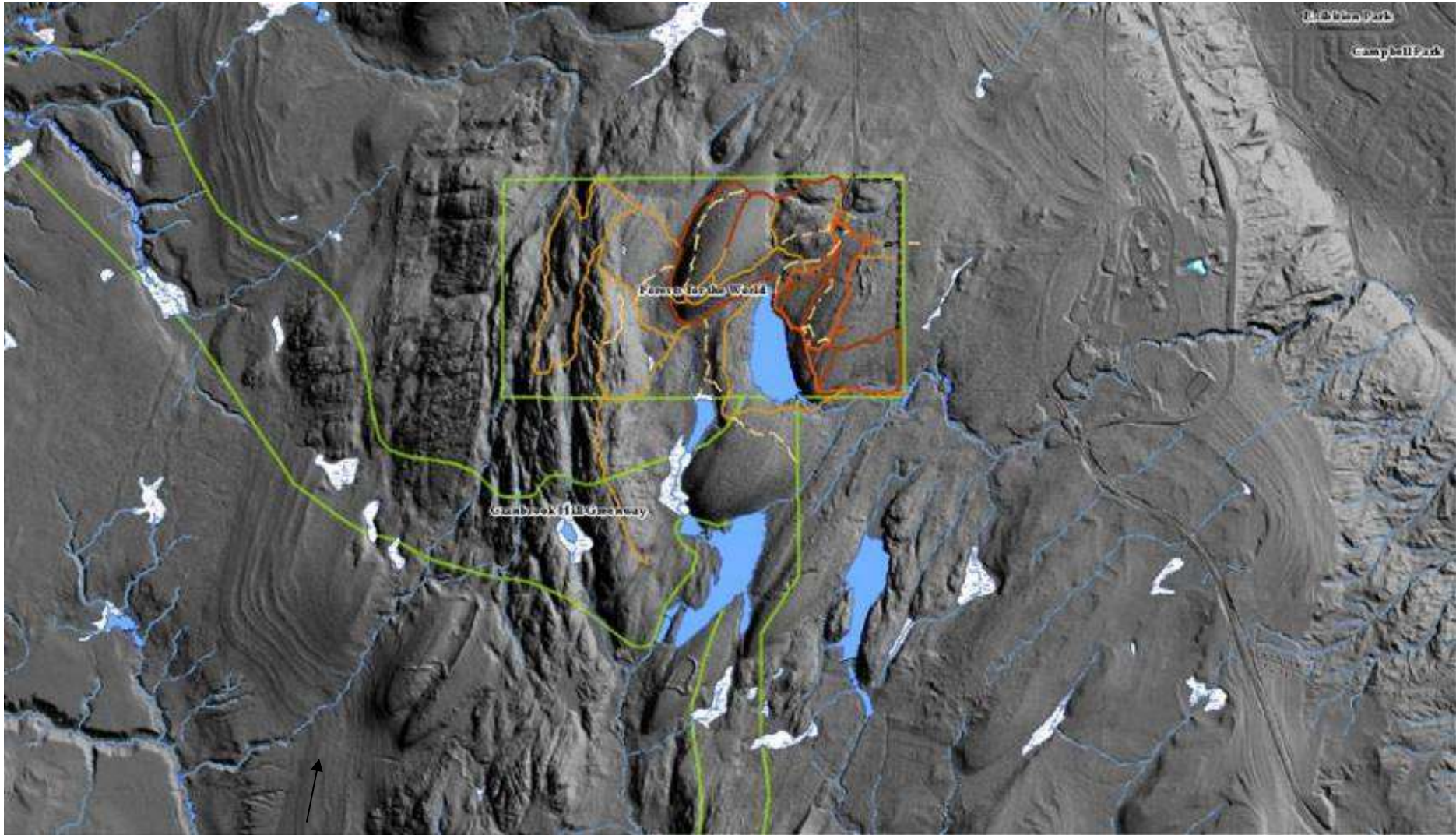
City 1 metre DEM (from 1m contours) 2000s



LiDAR Forests for the World, PG city DEM 2009 – see PGMap ?



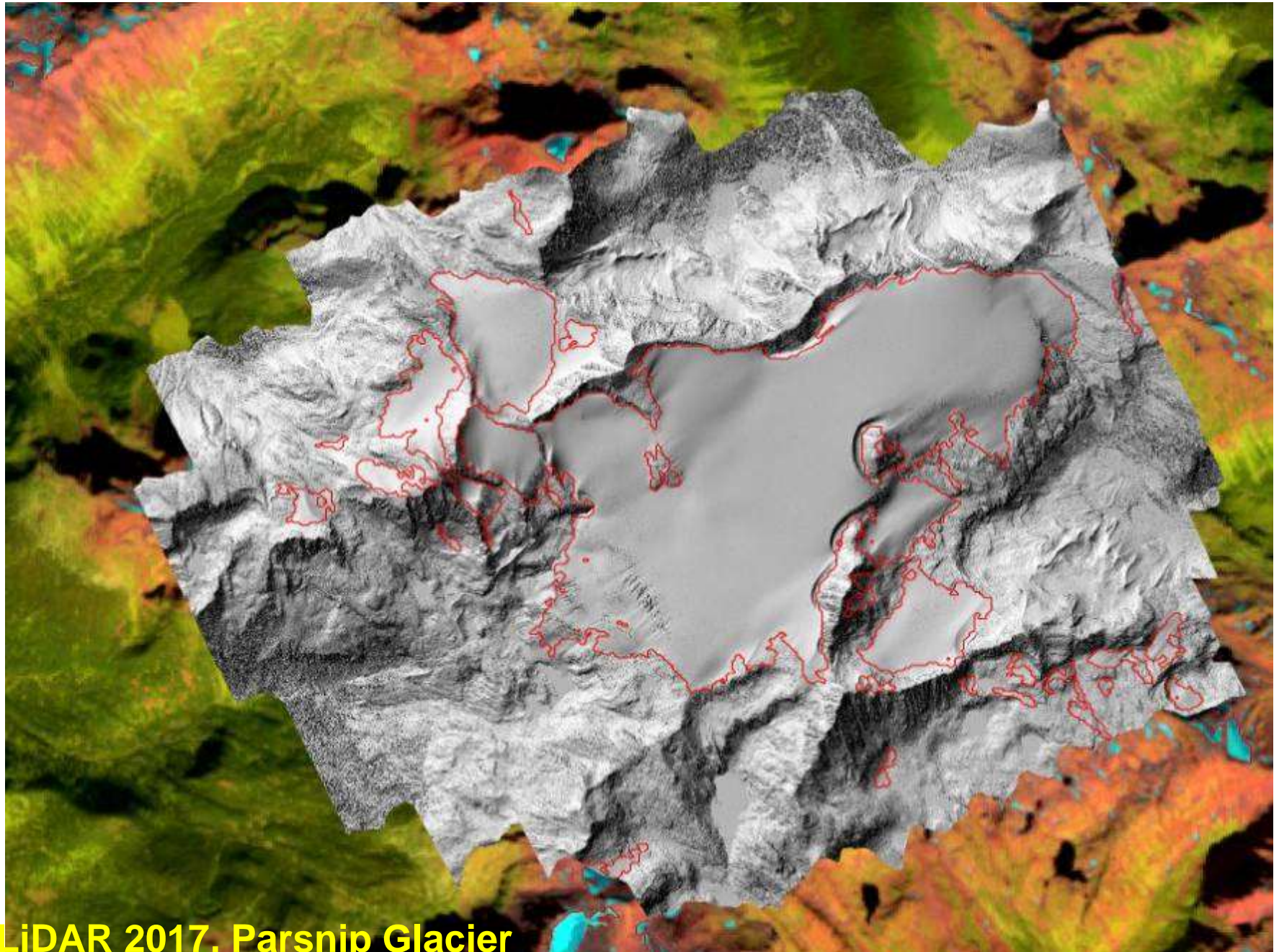
UNBC / Cranbrook Hill LiDAR 2009



<https://pgmap.princegeorge.ca/Html5Viewer/index.html?viewer=PGMap>

50cm beach lines

Monkman provincial parkthe closest glaciers to PG

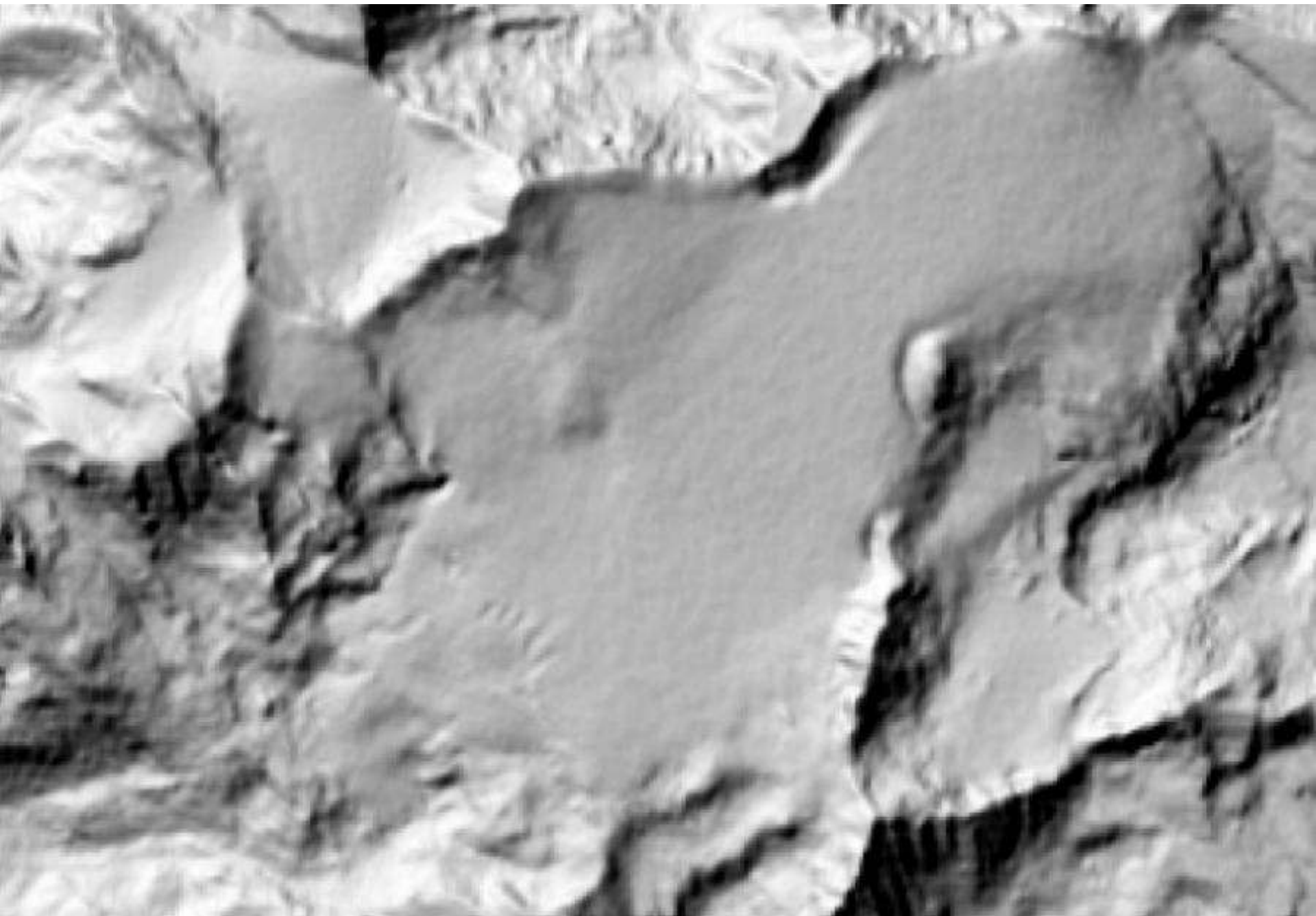


LiDAR 2017, Parsnip Glacier

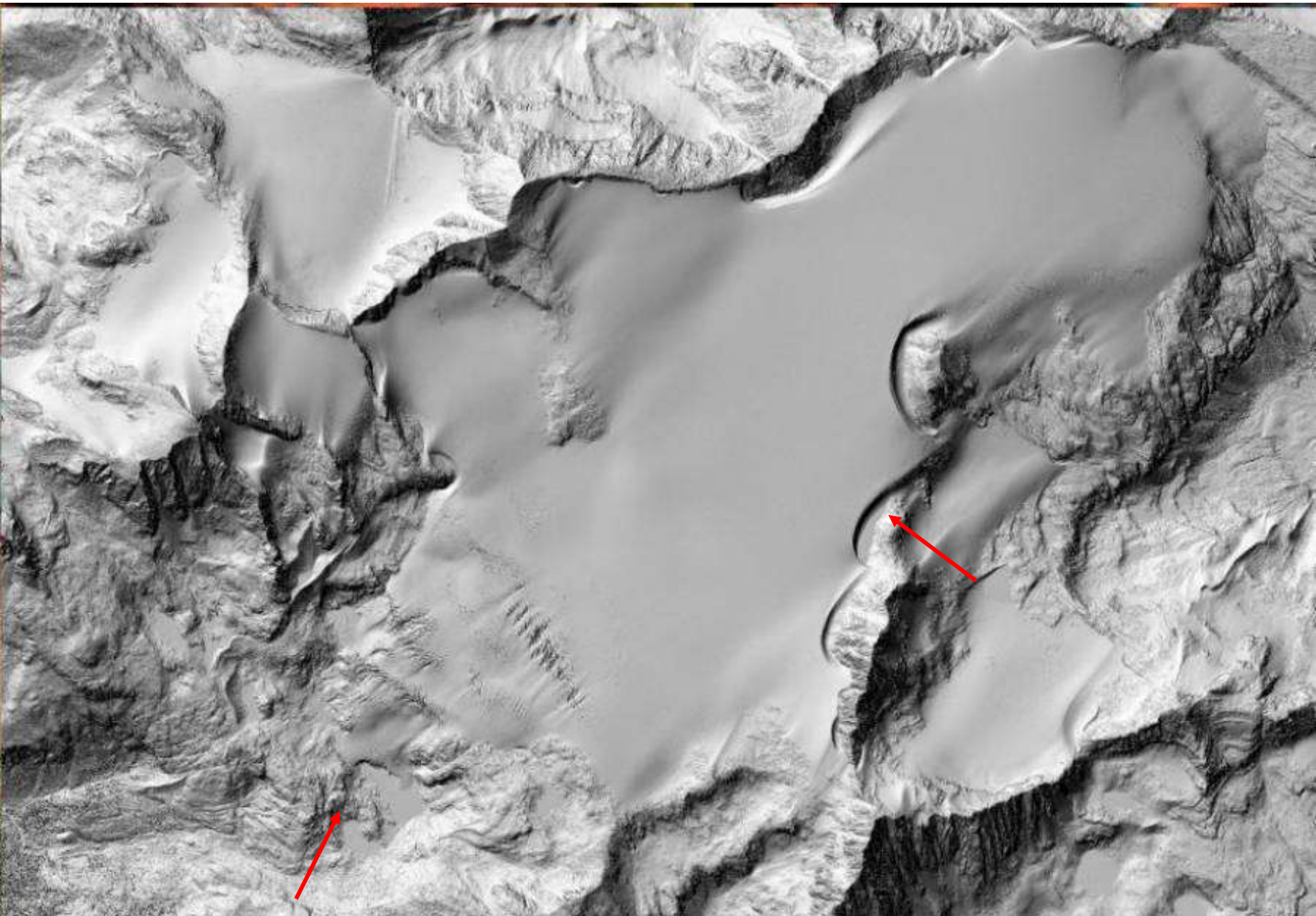
LiDAR data from Dr. Brian Menounos, UNBC



Parsnip Glacier snout - LiDAR resolution: 1 metre

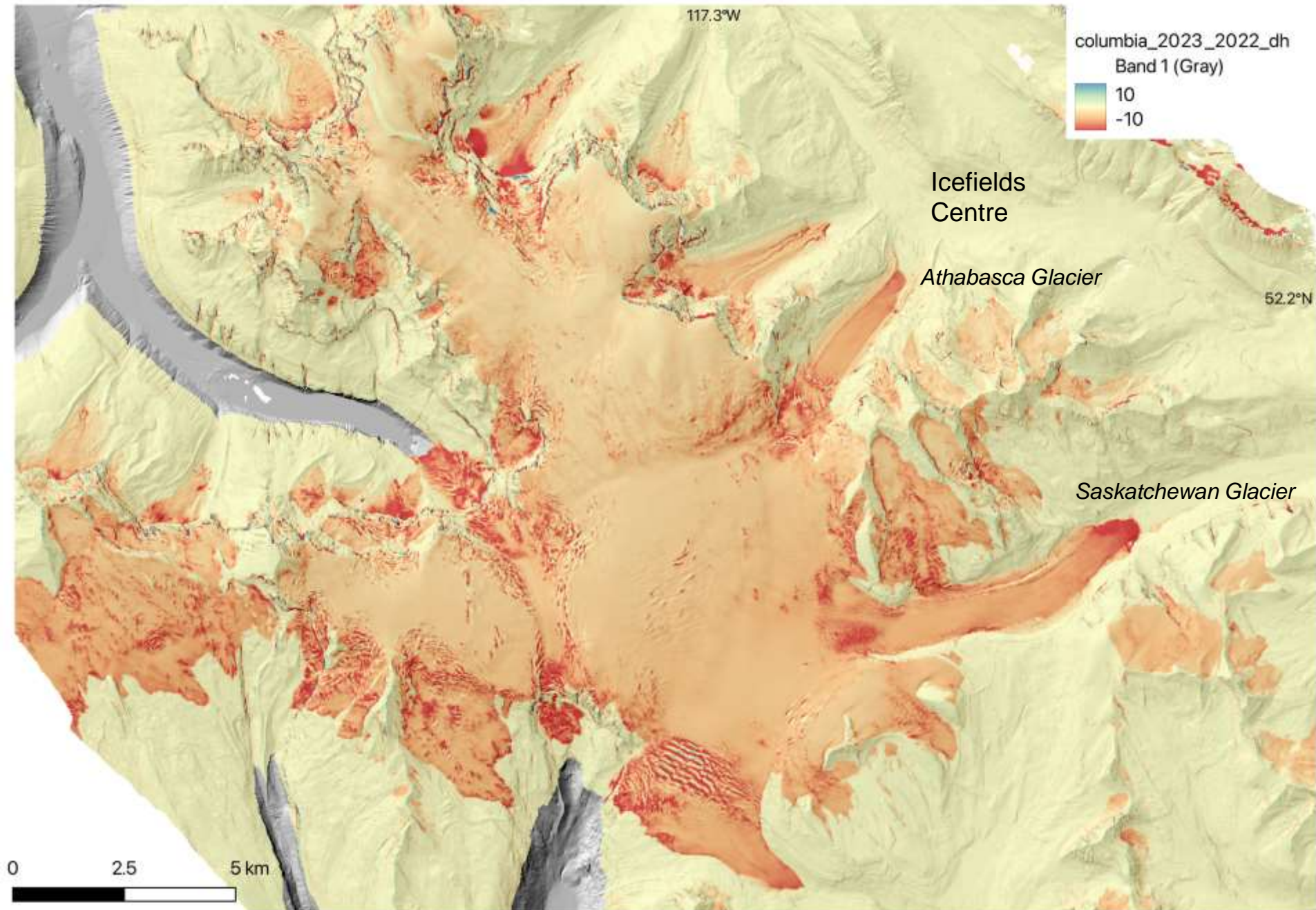


RADAR ALOS DEM ~2010 30m resolution



LIDAR DEM 2017 1m

Repeat LiDAR 2022-23 to show glacier elevation loss in one year – Brian Menounos

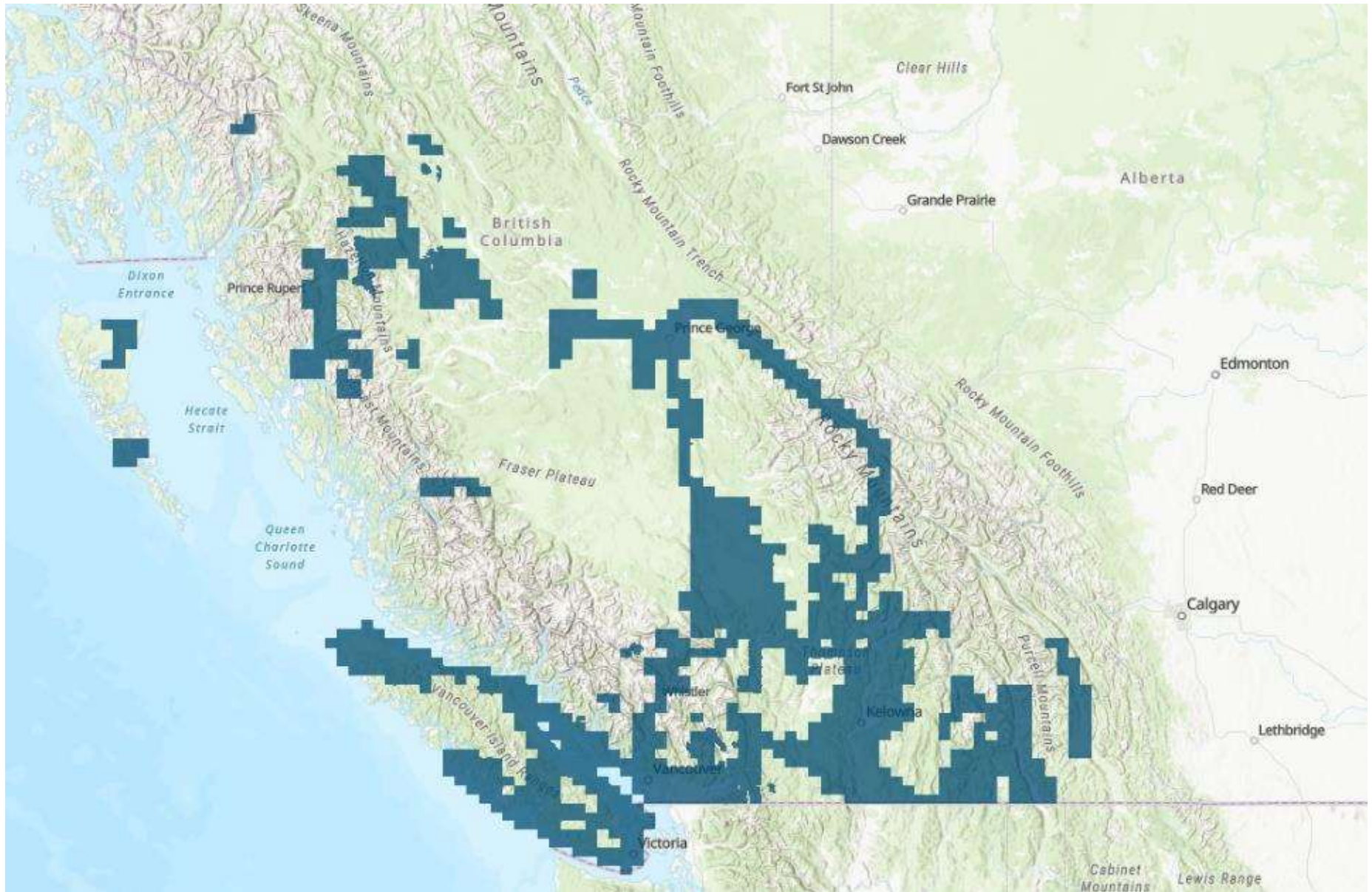


LiDAR summary

Previous drawbacks: (all reducing with technology increase)

- o The relative high cost of collecting LiDAR
- o High data volume - Terabytes
- o Steep learning curve in research and understanding
(involving utilizing the entire point cloud)

LidarBC - Open LiDAR Data Portal - Web Map 2022 (free download)



<https://www.arcgis.com/apps/mapviewer/index.html?webmap=c2967cee749b4bdbac5e7c62935ca167>

BC LiDAR data portal, 2023



LidarBC Data Availability

Click to filter the map by data availability 

Available

Data available for download through the LidarBC data download portal.

-  Data collected 2023 onwards
-  Data collected prior to 2023

Being Processed

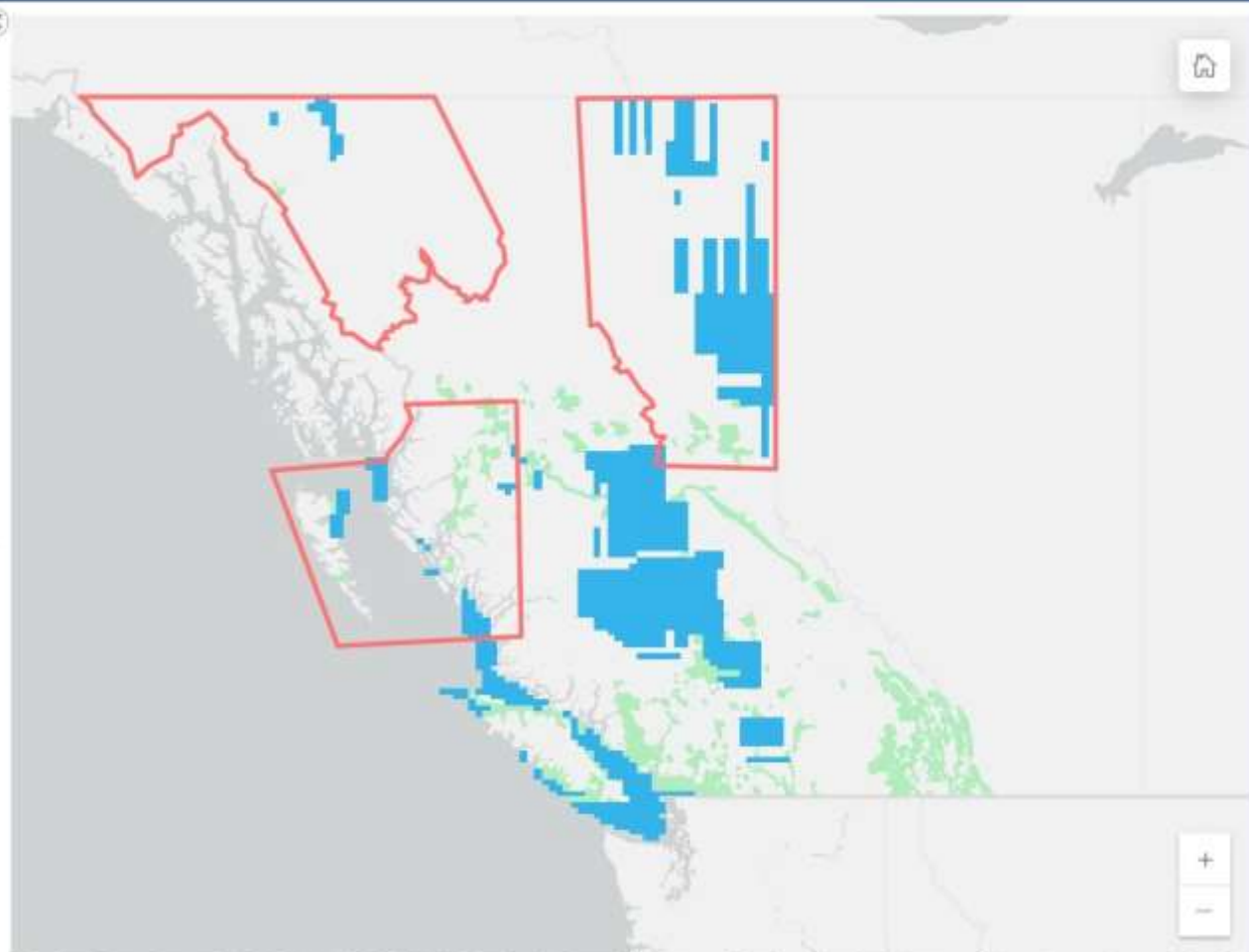
Data being processed for publication.

Actual Acquisition

Data flown and acquired.

Planned Acquisition

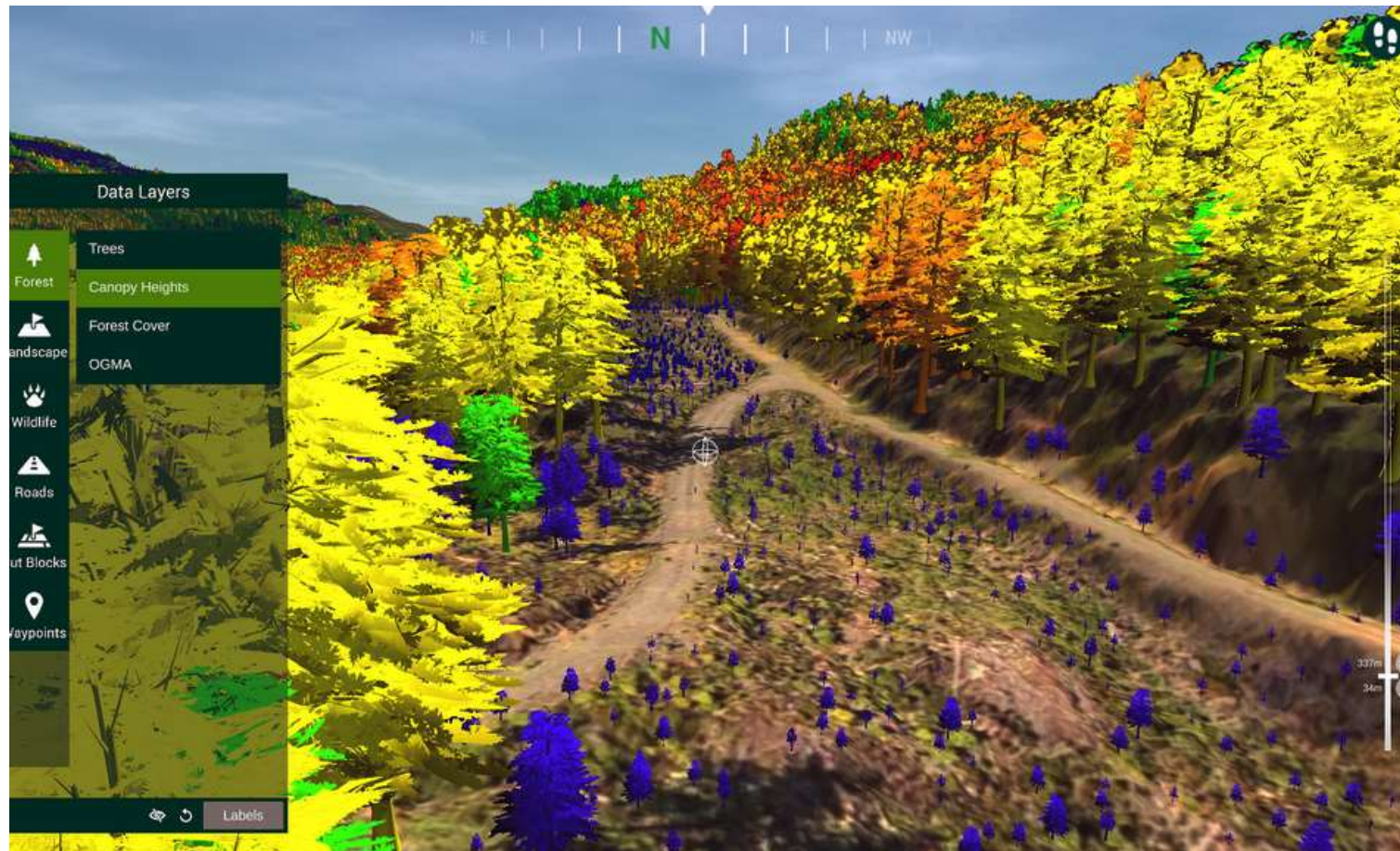
Planned data acquisition areas for 2024.



B.C. announces \$38 million aerial mapping project

Entire province will be eventually surveyed using Light Detection and Ranging (LiDAR) technology - complete by 2030

Ted Clarke Apr 14, 2023 7:07 AM

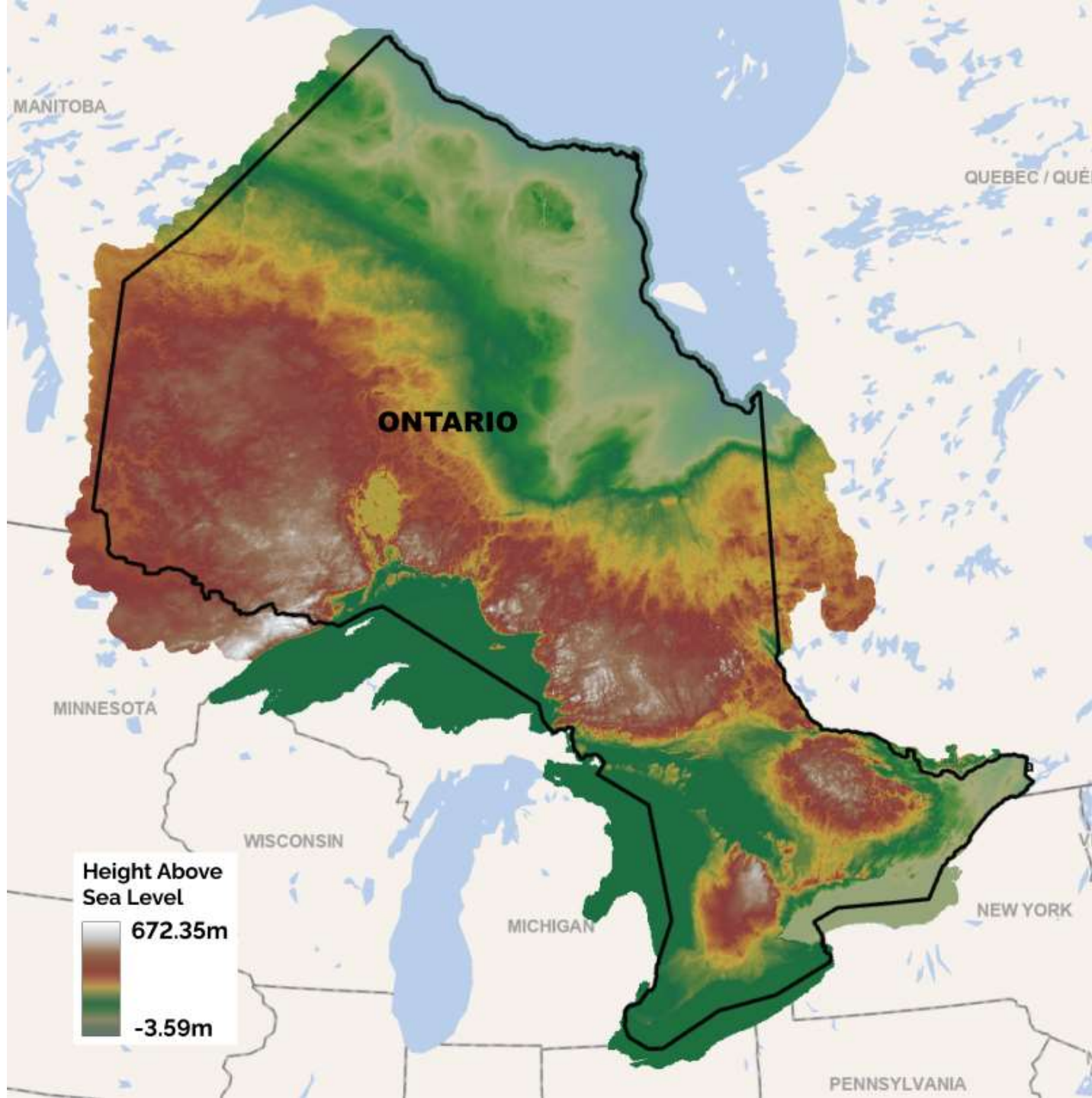


Ontario

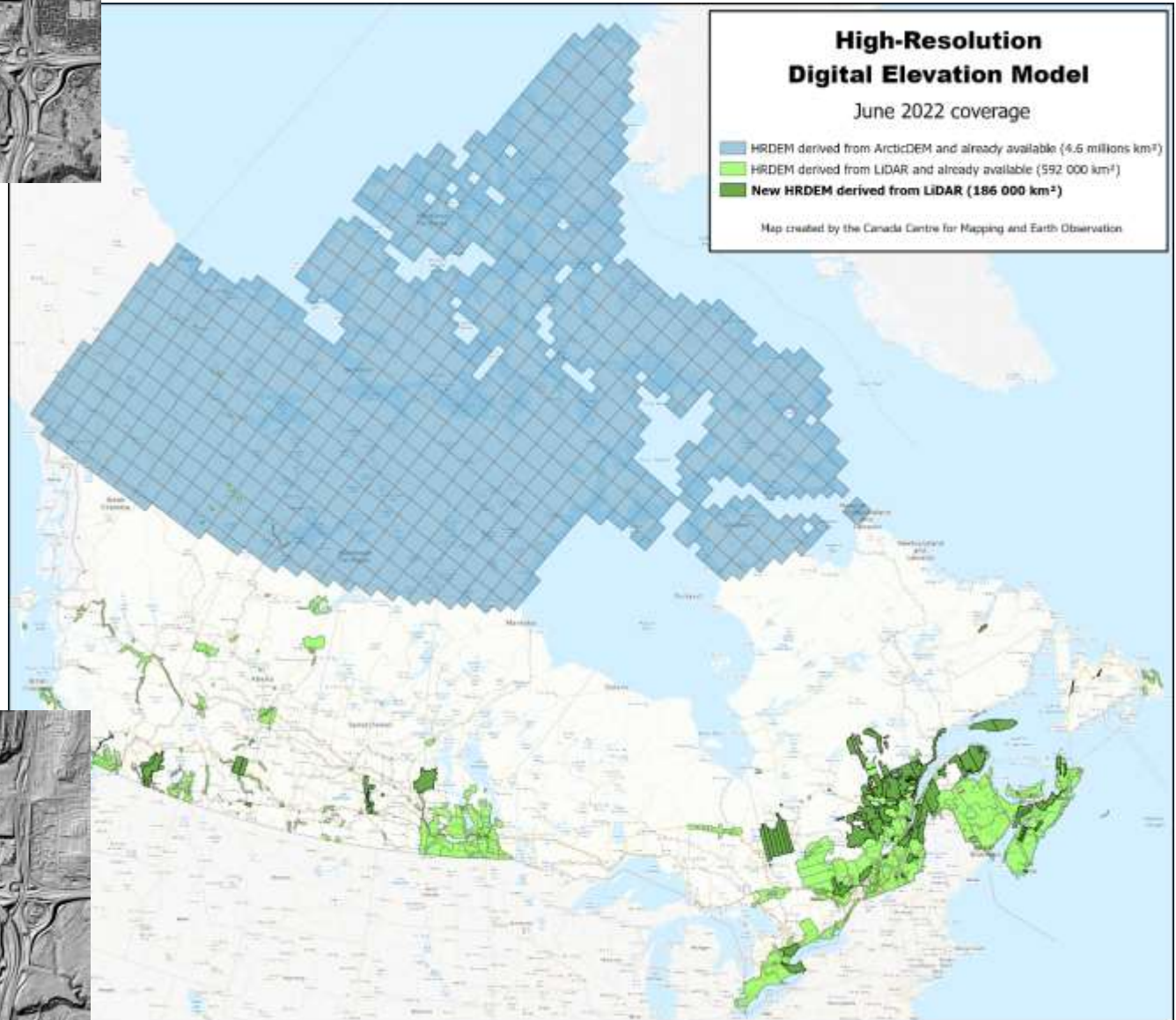
<https://geohub.lio.gov.on.ca/pages/ontario-elevation-mapping-program>

All provinces

<https://canadiangis.com/free-canada-lidar-data.php>



<https://natural-resources.canada.ca/science-and-data/science-and-research/geomatics/topographic-tools-and-data/whats-new/new-lidar-derived-data-available-on-open-maps/24414>

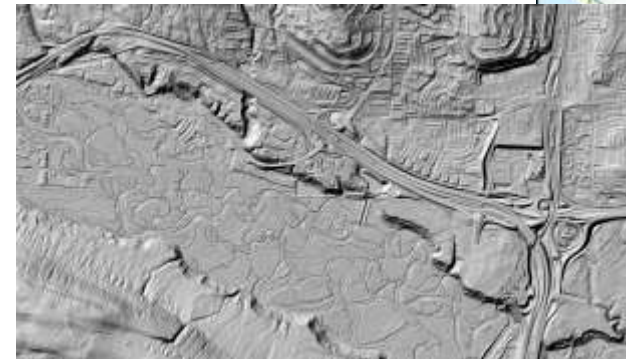


**High-Resolution
Digital Elevation Model**
June 2022 coverage

- HRDEM derived from ArcticDEM and already available (4.6 millions km²)
- HRDEM derived from LIDAR and already available (592 000 km²)
- New HRDEM derived from LIDAR (186 000 km²)**

Map created by the Canada Centre for Mapping and Earth Observation

Fish Creek Park
Calgary, DSM/BEM(DTM)



https://ftp.maps.canada.ca/pub/elevation/dem_mne/highresolution_hauteresolution/HRDEM_Download_Instructions.pdf

LiDAR summary

Advantages:

- ✓ Very high resolution DEM for many applications
- ✓ All urban areas with flooding potential
- ✓ Multi-layer data for forestry and ecosystems
- ✓ Increasing data supply - some free download e.g. PEI, NS, NB
- ✓ Increasing conference content in GIS/RS/Cartography/Forestry
- ✓ Many online resources e.g. :

USGS: <http://lidar.cr.usgs.gov/knowledge.php>

BC CARMS: <http://carms.geog.uvic.ca/carmslidarnew.html>

LiDAR Platforms

Airborne since 1970s e.g. [Optech](#) (Ottawa) [NorthWest Geo](#) (Calgary)

And many others ... including UNBC (Brian Menounos)
- LiDAR is mostly airborne, while RADAR is mostly spaceborne

Spaceborne

ICESat (Jan 2003-→2009): Geoscience Laser Altimeter System ([GLAS](#)):

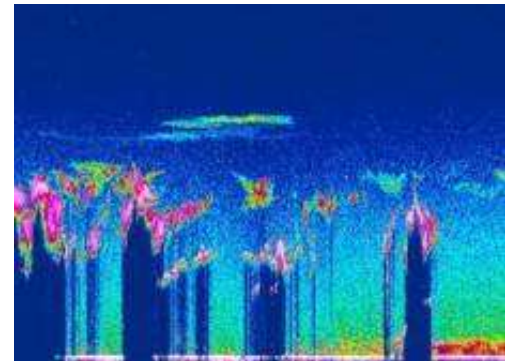
66m 'footprint' and 10cm vertical resolution, designed for polar icecaps

ICESat2 (Sept 2018): <https://icesat-2.gsfc.nasa.gov>

CALIPSO:

Cloud-Aerosol Lidar and Infrared Pathfinder Satellite Observation

<https://calipso.cnes.fr/en/CALIPSO/lidar.htm>



Ground based - 'terrestrial' Lidar

Lidar-based rockfall hazard characterization of cliffs

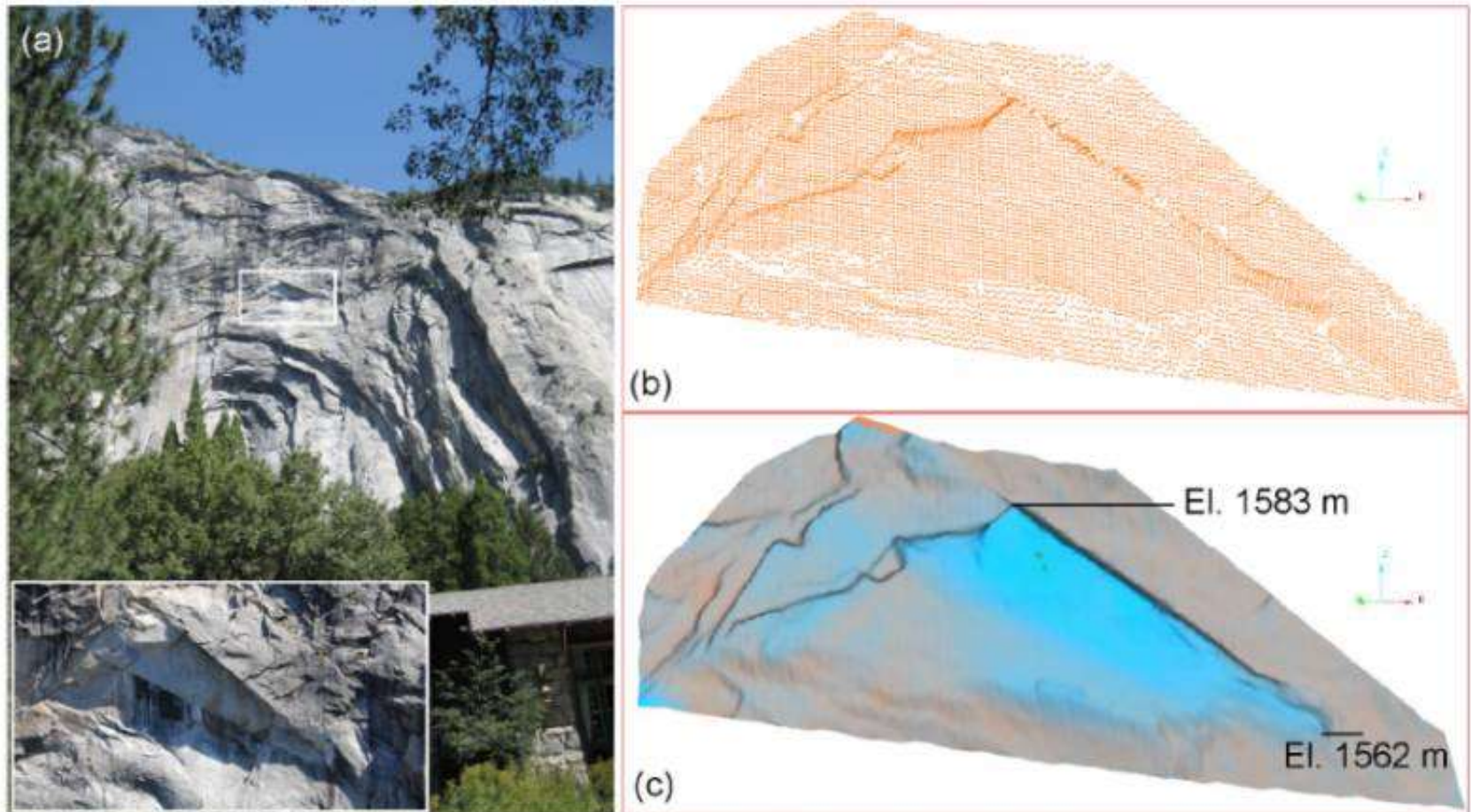


Figure 1. (a) Image of a 2009 rock-fall in Yosemite National Park with (b) point cloud and (c) surface model of the source area. Brightest-blue colored areas of surface model in (c) indicate areas of change following the rock fall.

LiDAR imagery of Gaping Gill - Britain's largest cavern

<http://www.eepublishers.co.za/images/upload/PositionIT-pages%2029-32.pdf>



Fig. 1: Gaping Gill Main Chamber LiDAR survey 2003. Vertex cloud looking west.



Fig. 2: Gaping Gill Main Chamber LiDAR survey 2003. Vertex cloud looking east.

Video: <http://www.youtube.com/watch?v=8HdgliagAds>

Heritage building scanning: <http://www.youtube.com/watch?v=4AGk01lms5k>

- building information modeling (BIM)

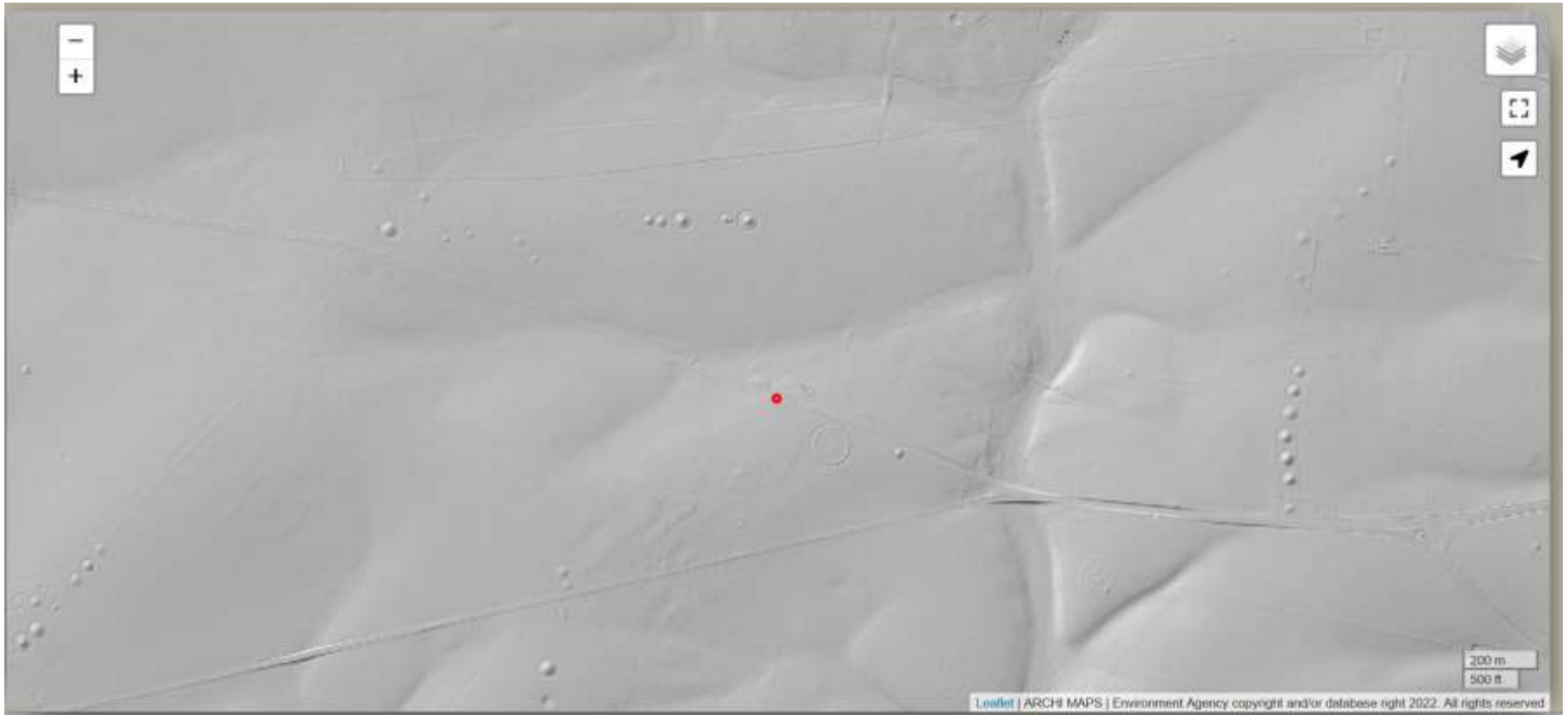


Conference group photo (RW in red jacket, front centre)



The same Conference group LiDAR scan image

Stonehenge mapping: Archaeology LiDAR



Stonehenge map https://www.archiuk.com/cgi-bin/build_lidar_map.pl?map_location=Stonehenge&point_title=Neolithic%20site%20of%20Stonehenge%2C%20Wiltshire&ngr=&is_sub=&pwd=&point_lat=51.179420&point_long=-1.826809

Stonehenge3D: <https://sketchfab.com/3d-models/stonehenge-lidar-archaeology-landscape-c15c247d4e6c462ca48b5276492c1b7c>

Flight: <https://www.wessexarch.co.uk/our-work/explore-stonehenge-landscape>