

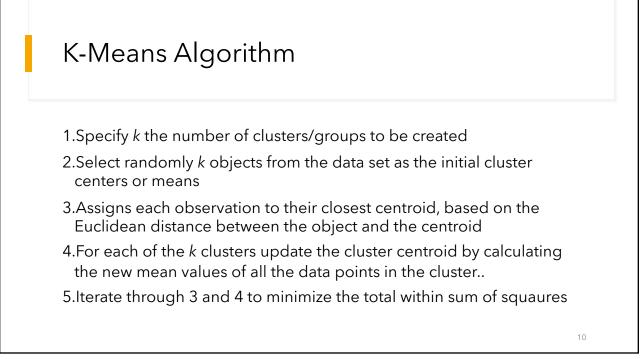
K-Means

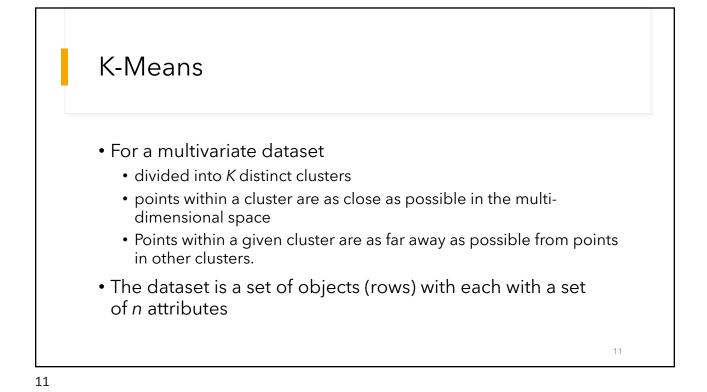
$$vc_k = \sum_{x_i \in c_k} (x_i - \mu_k)^2$$

Where:

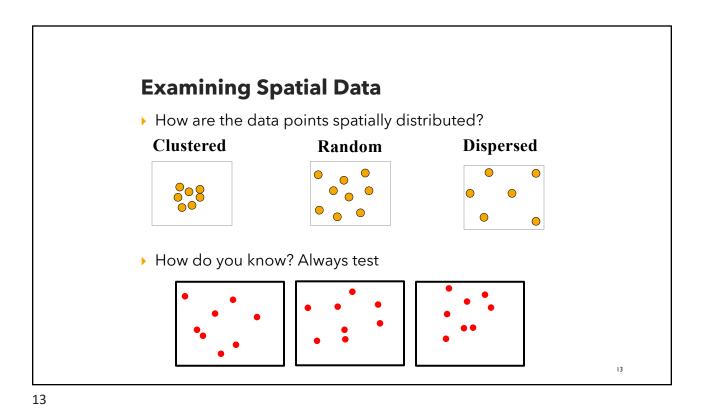
- vc_k is the sum of the within cluster variation
- x_i is the data point belonging to the cluster c_k
- μ_k the mean value of the points assigned to cluster c_k



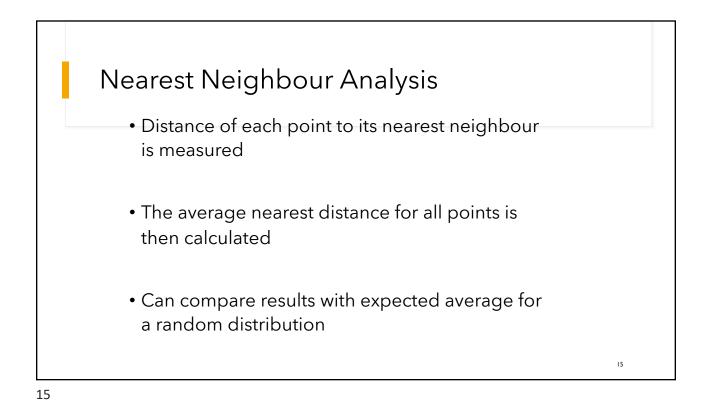


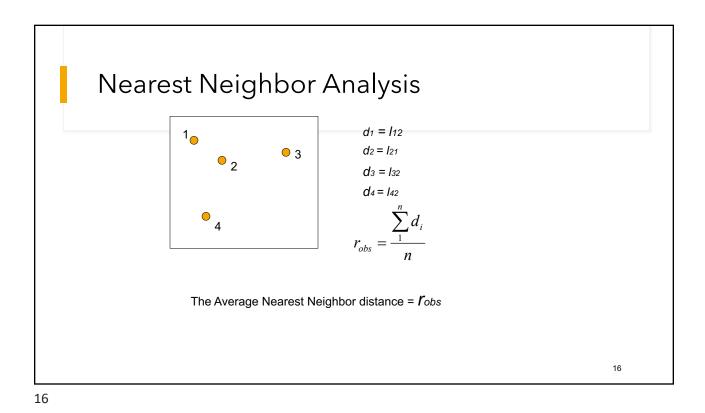


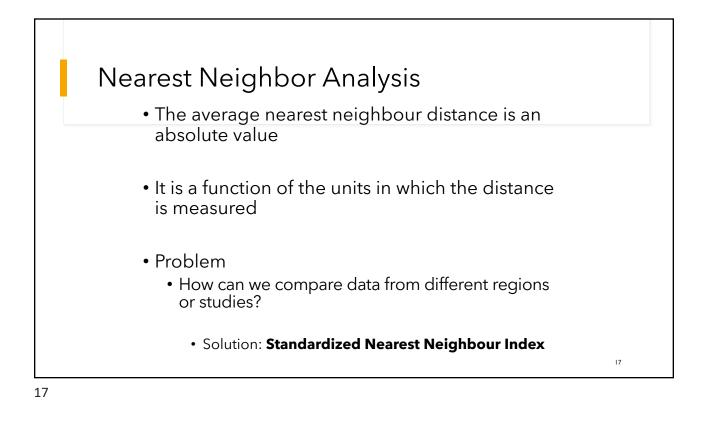
Point Pattern Analysis

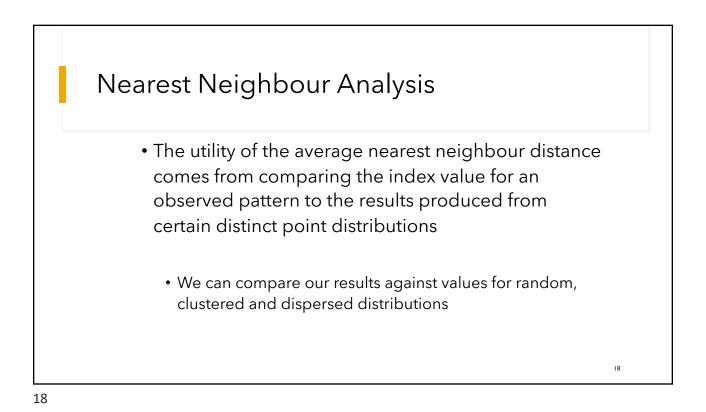


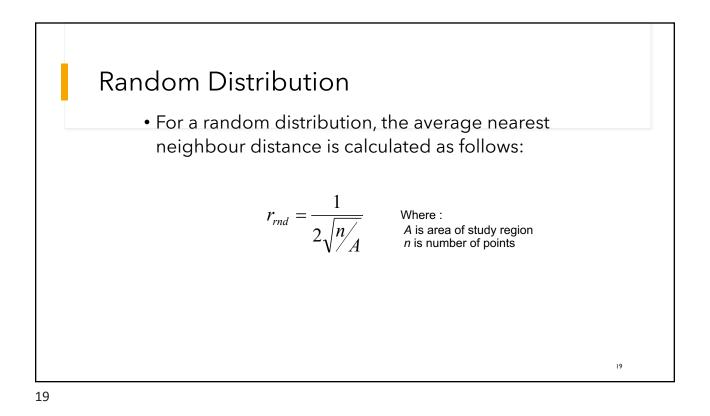
Point Pattern Analysis
A set of quantitative tools for examining the spatial arrangement of point locations on the landscape as represented by a conventional map.
Two methods are *nearest neighbour analysis* and *quadrat analysis*.

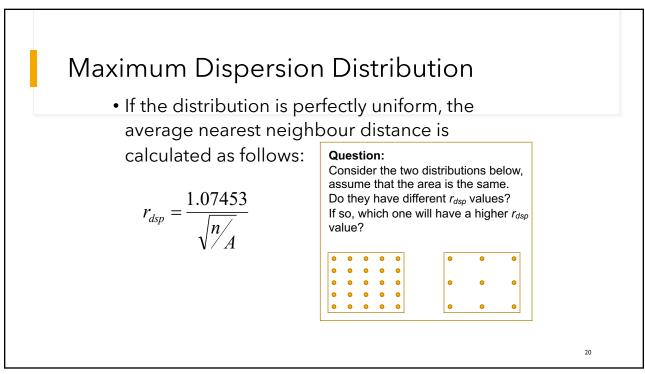


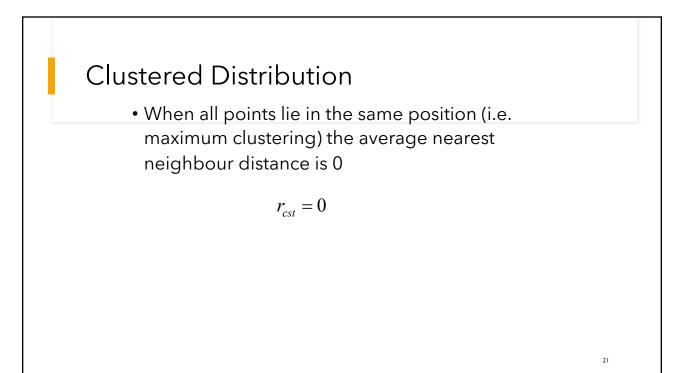


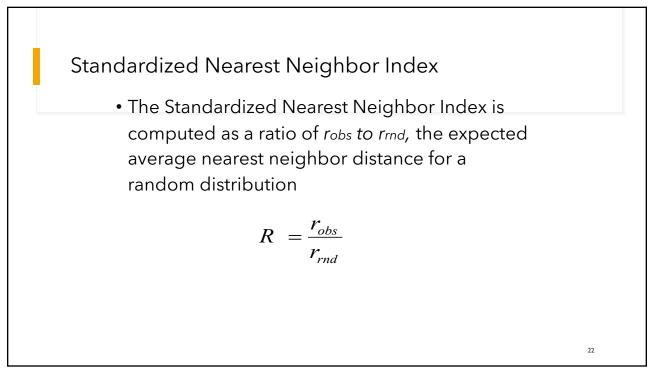


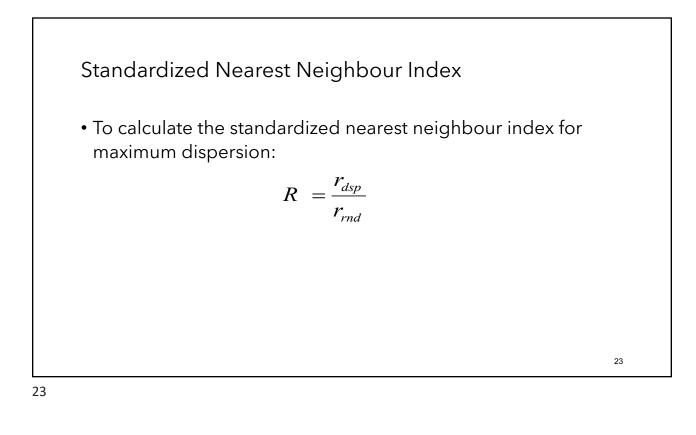


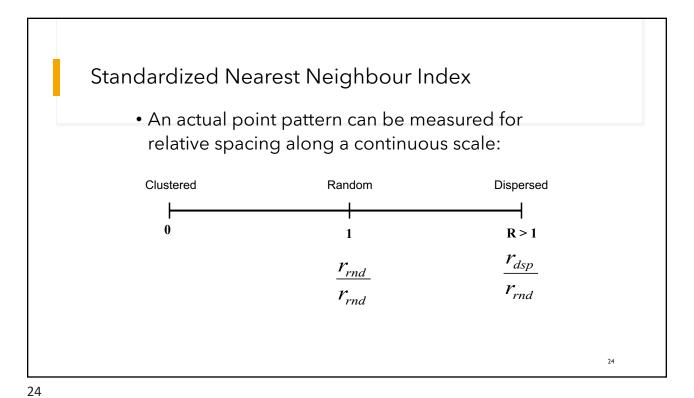












Test of Significance

• It is important to test whether a significant difference exists between the observed and random nearest neighbor values.

$$Z_r = \frac{r_{obs} - r_{rnd}}{\sigma_{obs}}$$
$$\sigma_{obs} = \frac{0.26136}{\sqrt{n(n/A)}}$$

