

Computers have linked mapping technologies under the umbrella term:
Geomatics includes the following geospatial technologies:
for data collection, analysis and output

a. Cartography

"The art, science and technology of making maps"

b. Geographic Information Systems (GIS)

"Automated systems for management, analysis, input and output of spatial data"

c. Global Positioning Systems (GPS)

"determination of ground locations using measurements from satellites"

d. Surveying

"science of determination of accurate coordinates of terrestrial locations"

e. Photogrammetry

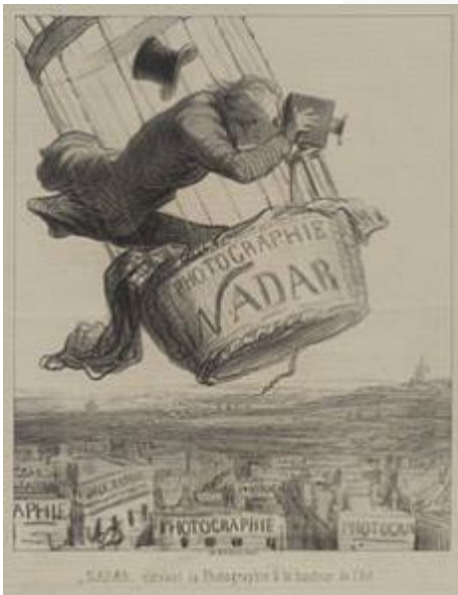
"derivation of 2D or 3D locations from stereo pairs of aerial photography"

f. Remote Sensing

"Acquisition of information about a planetary surface from a distance"

Aerial photography / early Remote Sensing

Early years 1850->
Birds, Kites, Balloons,
later Planes with camera
(and now UAVs)

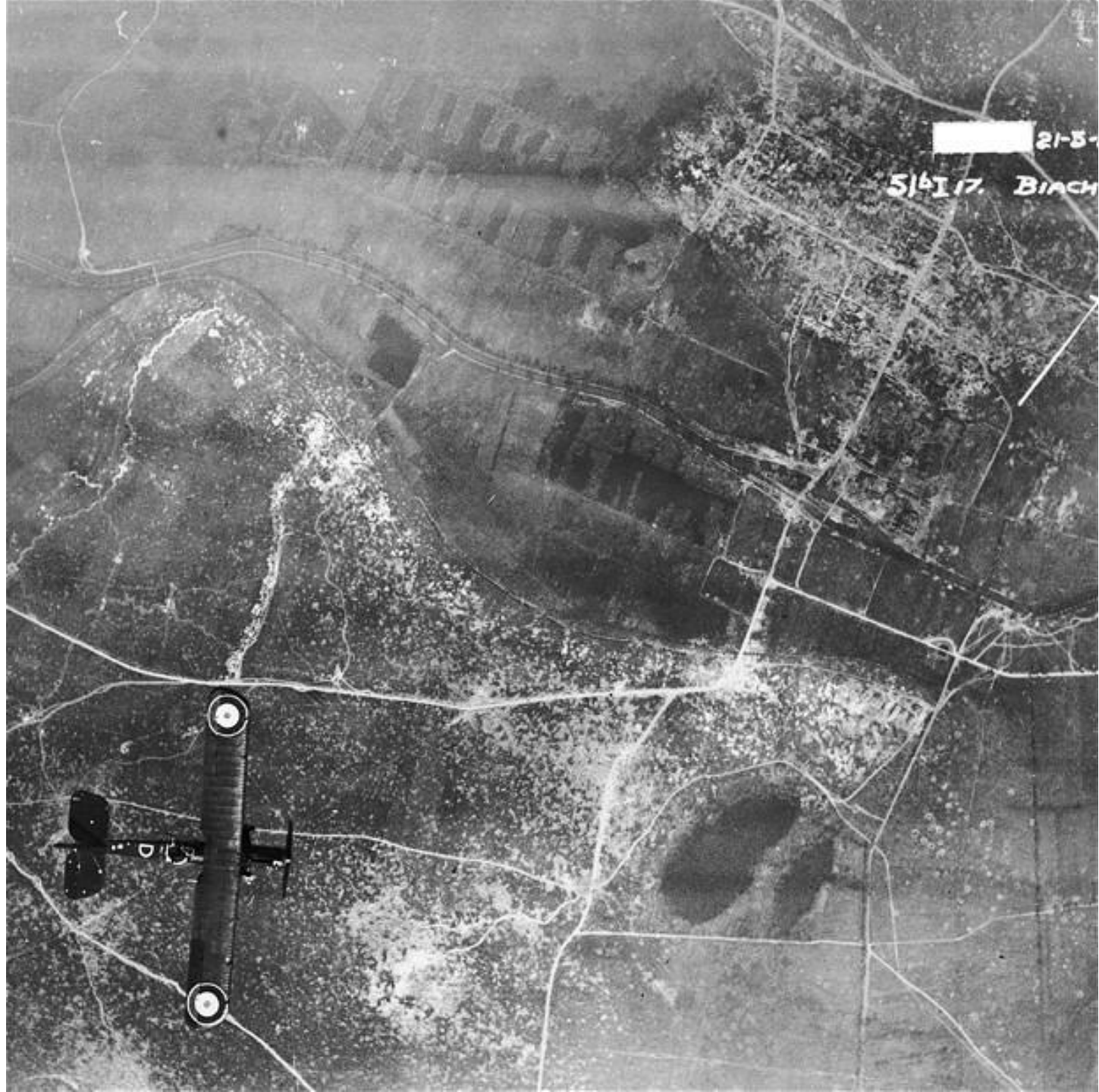


**Air photos,
World War 1
Reconnaissance
and analysis**

**Postwar use:
1919-1938
limited by
resources and
the depression**

**World War 2:
reconnaissance
and mapping**

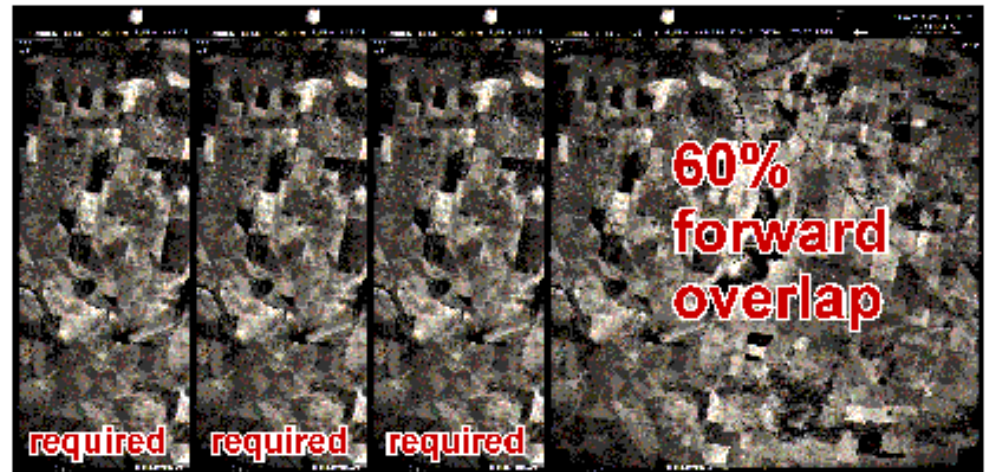
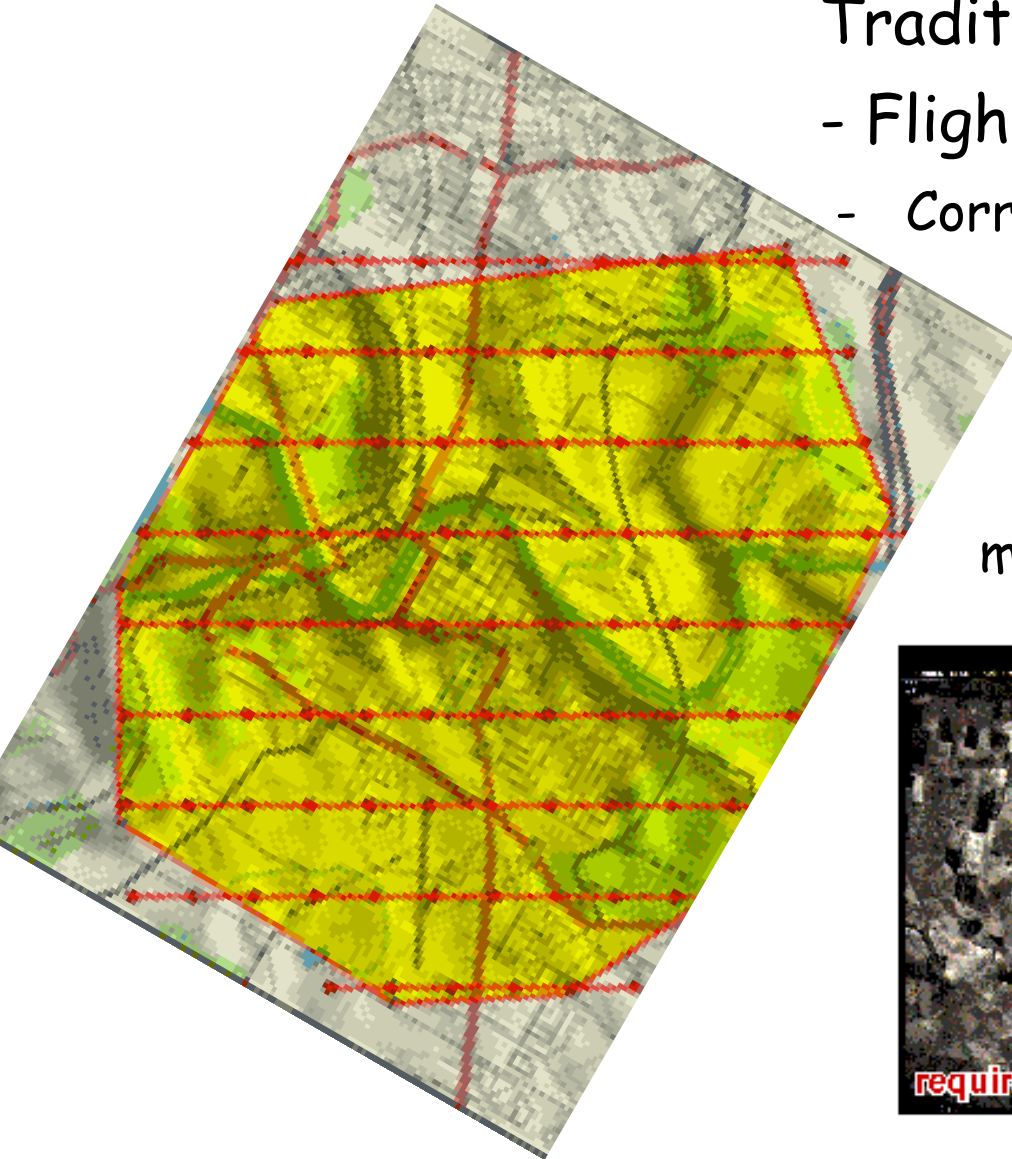
**Standard for
mapping after
World War 2
1946 ->**



Aerial Photography

Traditional setup for film / photos

- Flightlines and overlap
- Corrected, mosaicked -> orthophotos
= Photogrammetry
- Panchromatic, Colour, Infra-red
mostly panchromatic due to cost



Panchromatic air photo: 15th / University Way



Colour air photo: 15th / University Way; hardcopy cost = 2x



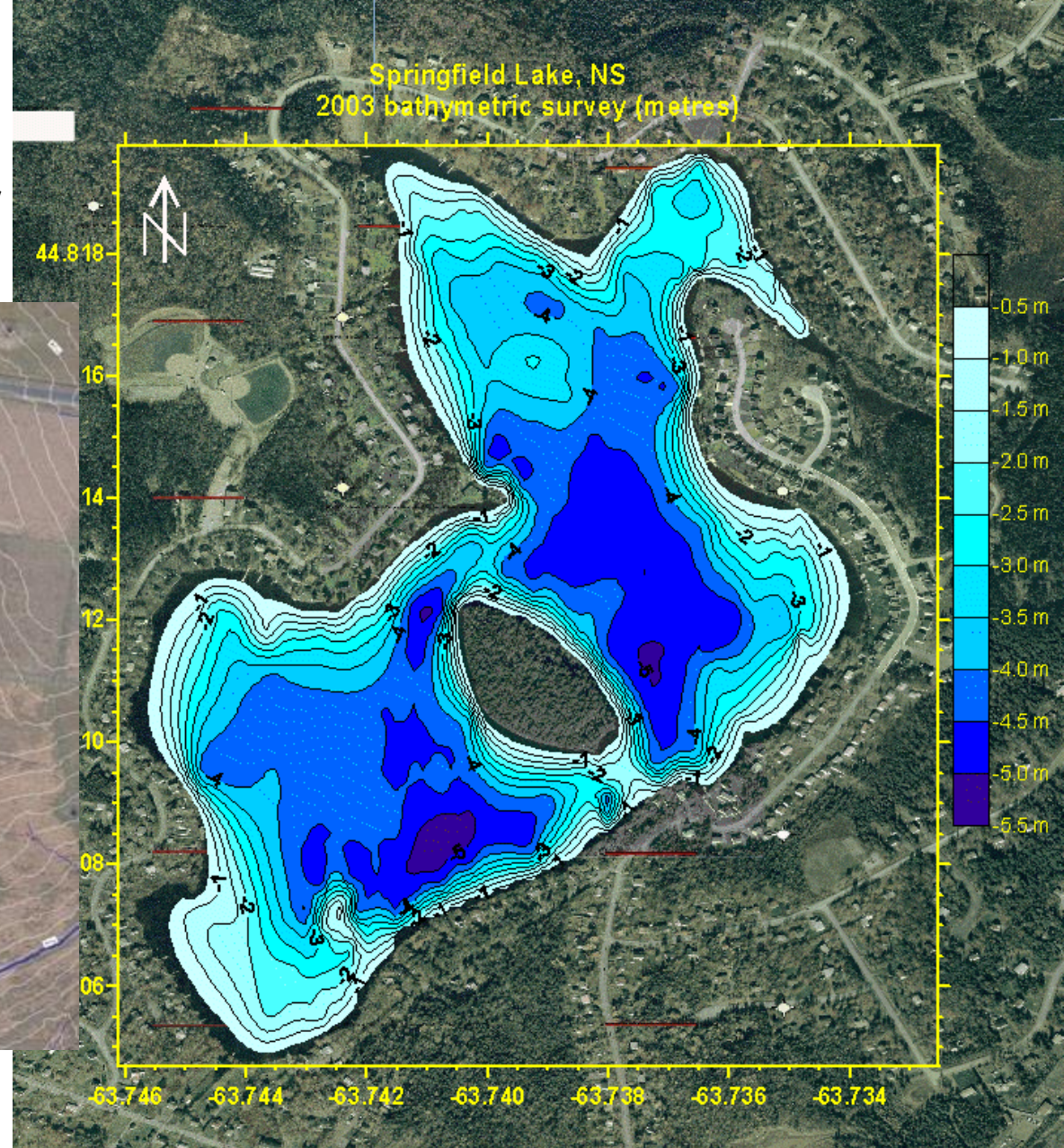
2000s Digital photogrammetry – no extra cost for colour Orthorectification done automatically with DEM



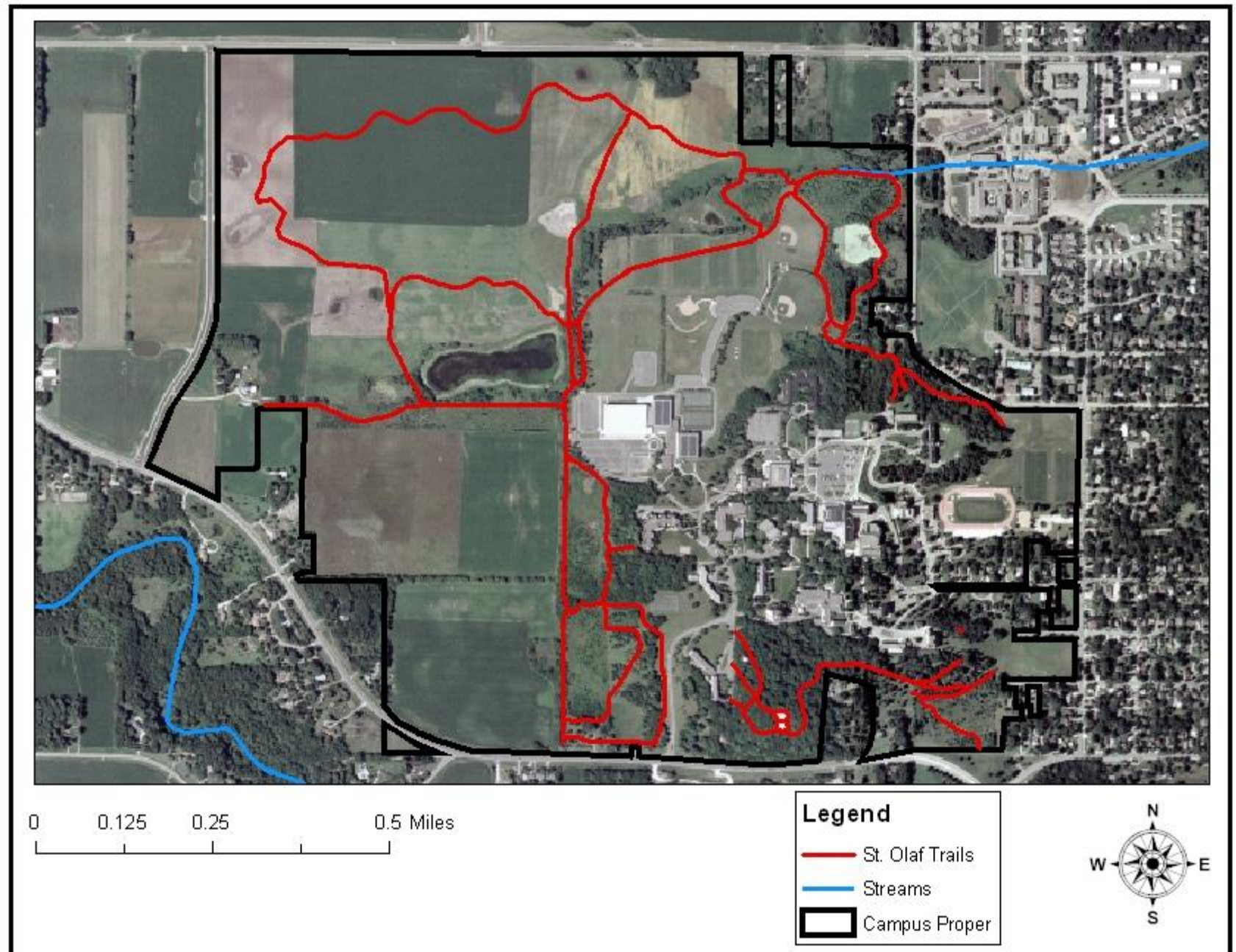
<https://www.terrasaurus.ca/imagery-examples>

Photomap examples

No generalization of base layer



Digital orthophotomap



Most pre-digital aerial photography was panchromatic, not colour



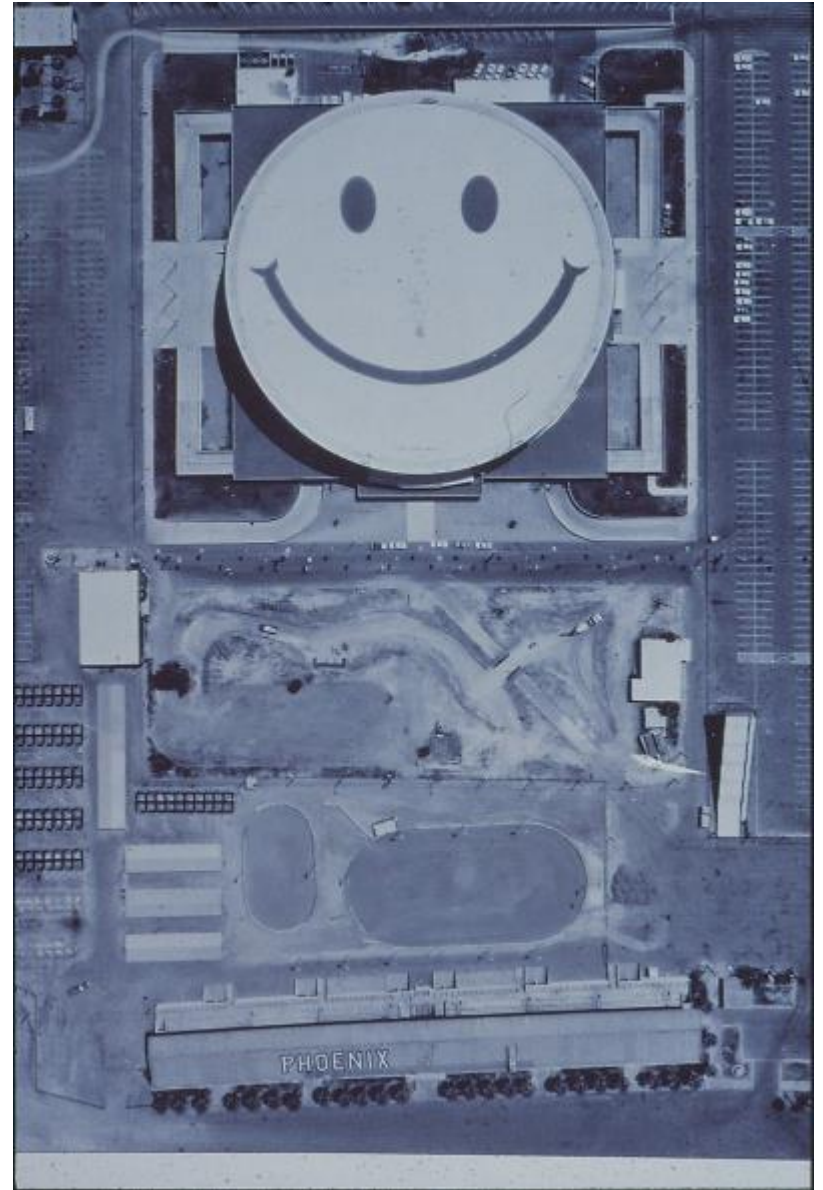
<https://pgmap.princegeorge.ca/Html5Viewer/index.html?viewer=PGMap>

What is Remote Sensing?

"Obtaining information about a planetary surface from a distance"

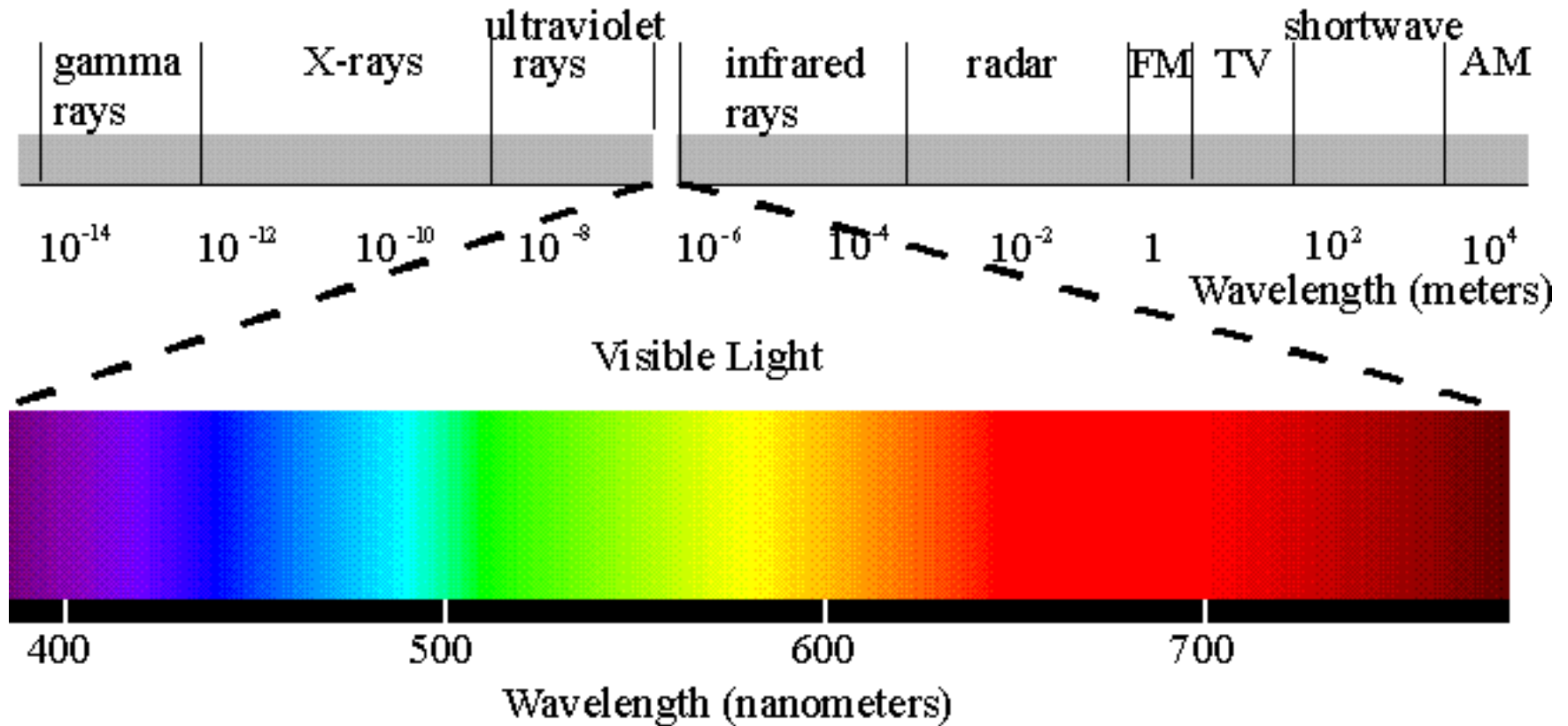
The term first appeared ~1965 with the first **satellite images** (previously there were only aerial photographs)

Also there was increasing use of non-visible parts of the **electromagnetic spectrum**, such as the **Infrared**



Shopping Center, Phoenix, AZ

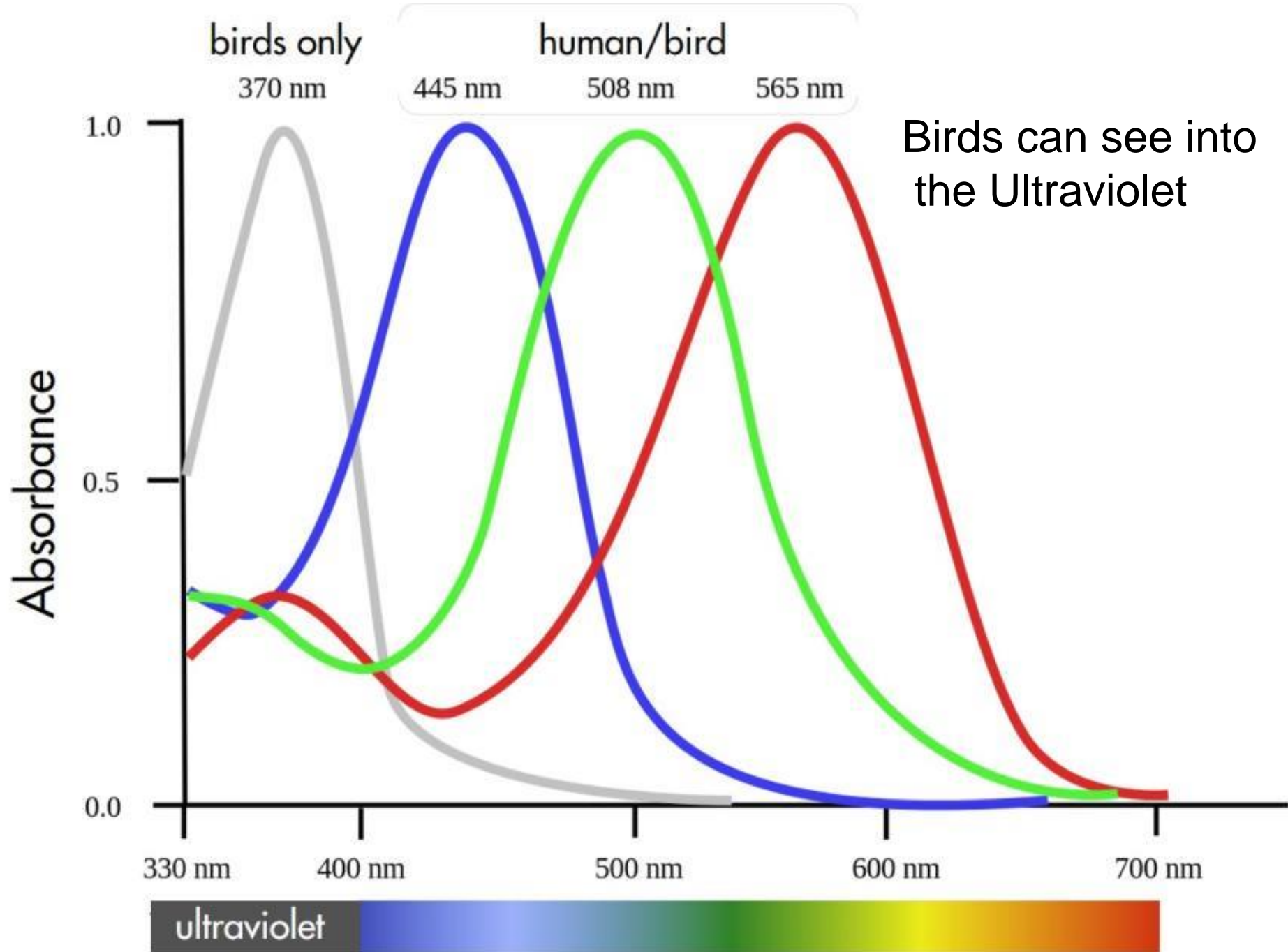
Remote sensing and the electromagnetic spectrum



Blue	0.4 - 0.5 μm (microns)	= 400 to 500 nm nanometres
Green	0.5 - 0.6 μm	= 500 to 600 nm
Red	0.6 - 0.7 μm	= 600 to 700 nm

micrometres: 'microns' : millionths of a metre

nanometers: billionths of a metre





Colors That Humans See



Colors The Dogs See

Most birds have 2 - 8 times the visual acuity of humans

Table 2 : Characteristics of normal colour and false colour film

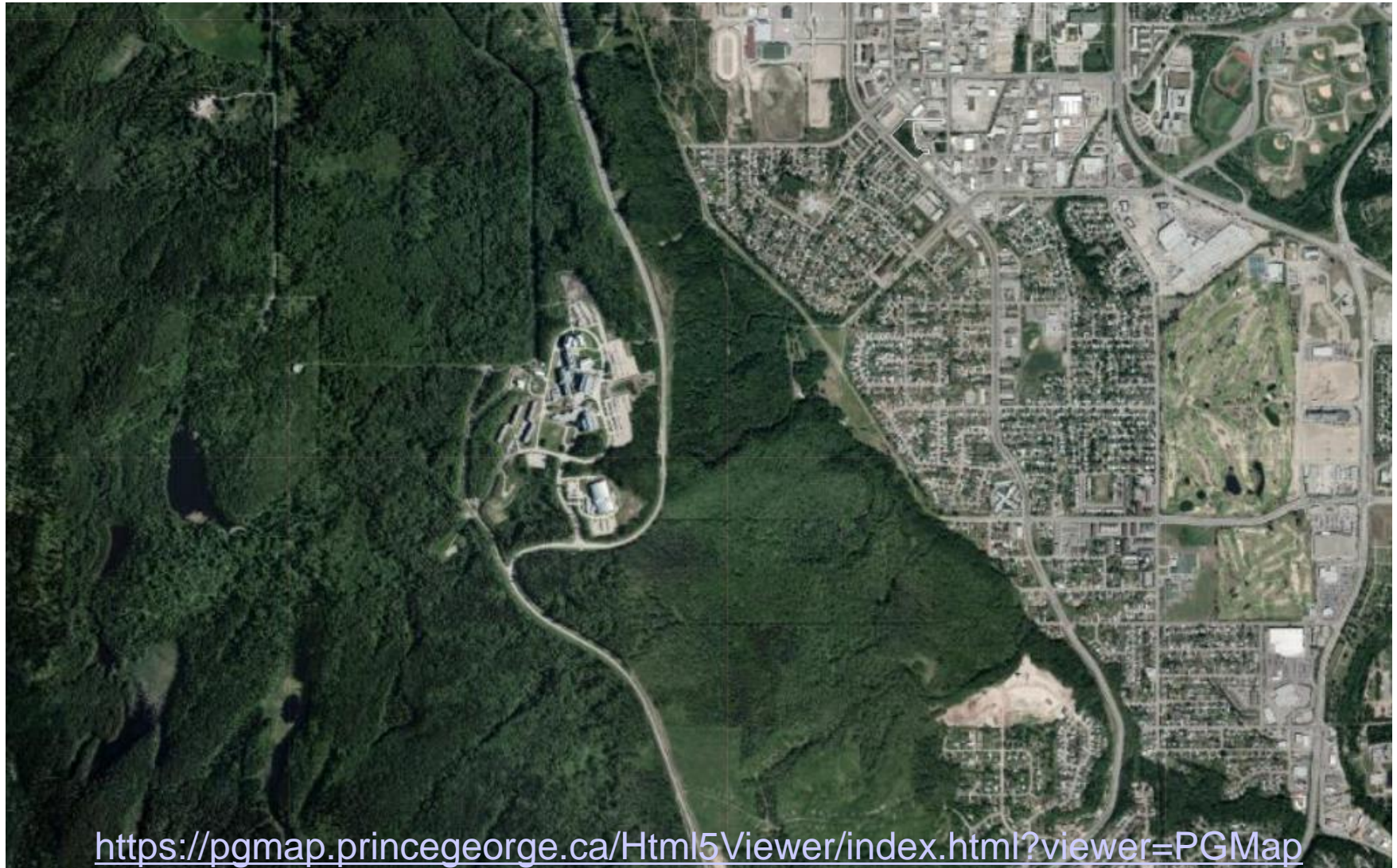
Normal colour film (Energy captured by film)	IR film (Energy captured by film)	Colour that results on film
B	G	Blue
G	R	Green
R	IR	Red

..the same with
digital photos



Film has three layers (RGB), a yellow filter removes blue wavelengths, the film is sensitive to infra-red, reflected by healthy vegetation, in the red (film) layer.

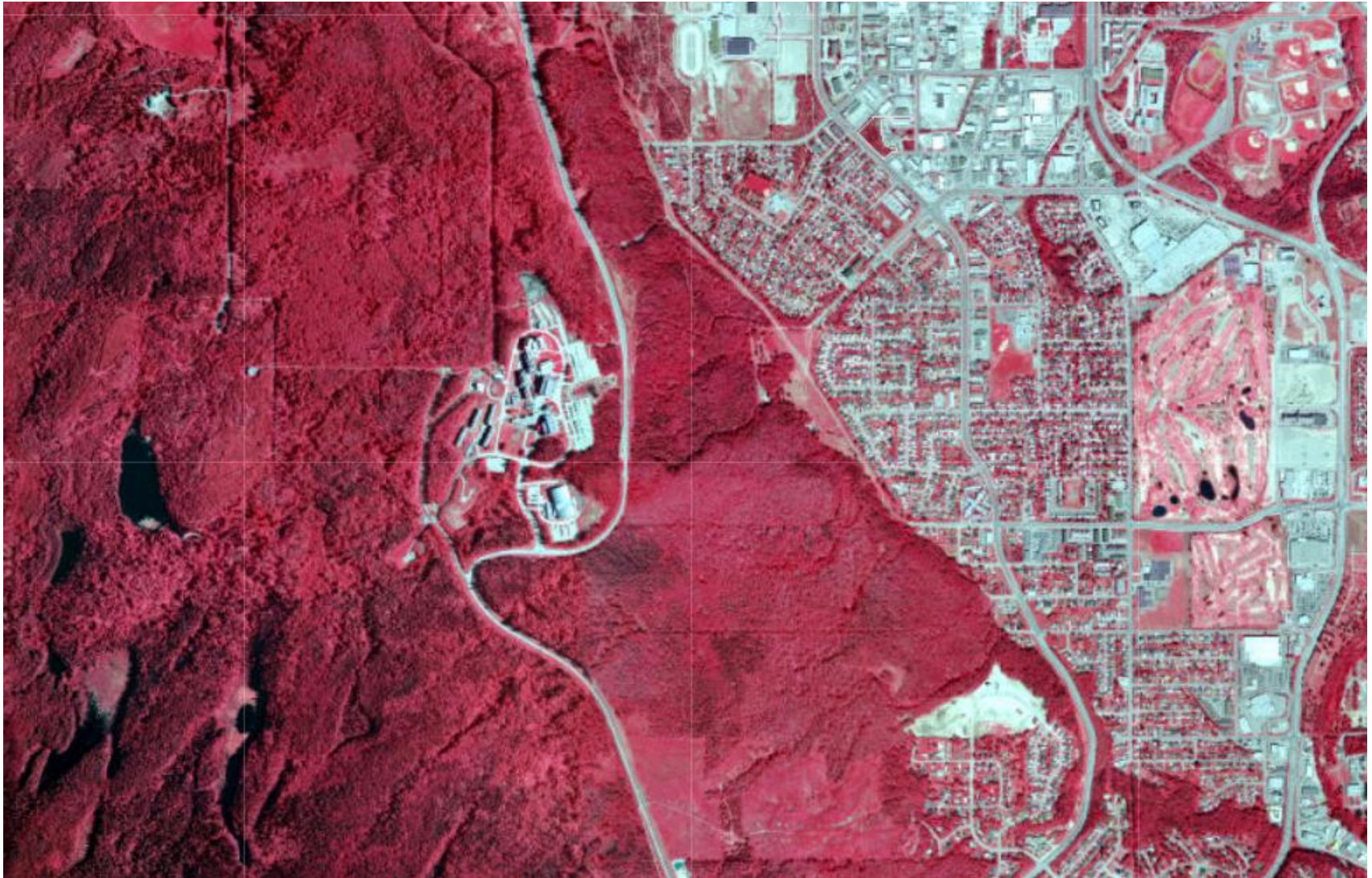
PGmap spring 2014 natural colour



<https://pgmap.princegeorge.ca/Html5Viewer/index.html?viewer=PGMap>

We are used to seeing natural colour but there are Advantages of using Infra-Red wavelengths for mapping and GIS:

PGmap spring 2014 Infra-Red image:

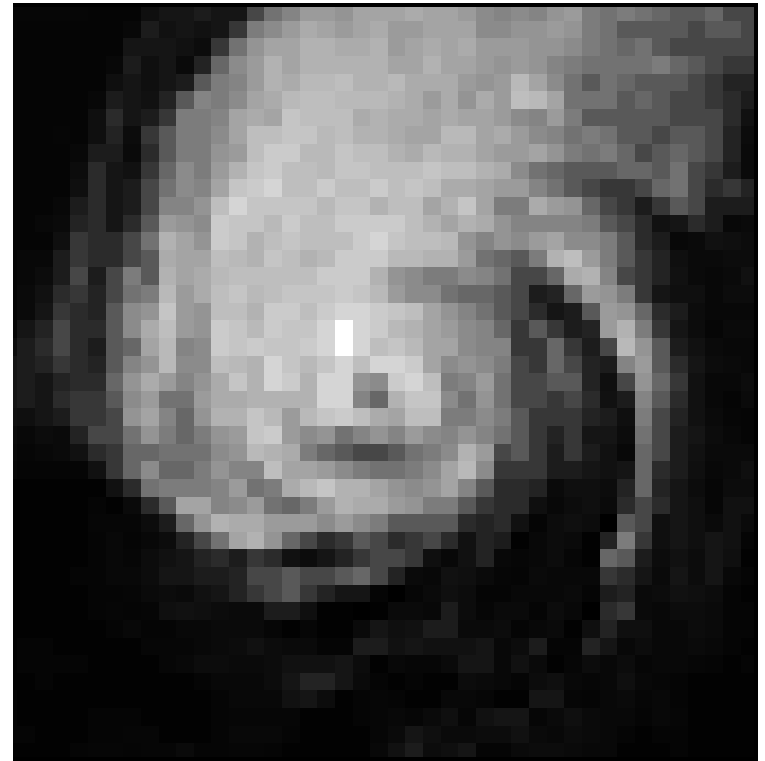


- Land-water distinctions are enhanced (but not urban features)
- Vegetation differences are enhanced, coniferous v deciduous etc..

Digital Scanning: all wavelengths

A scanner creates digital images with pixels (picture elements) -

e.g. 8 bit = 256 values
(0=dark to 255=bright)



Close-up of pixels in a digital
(scanned) image

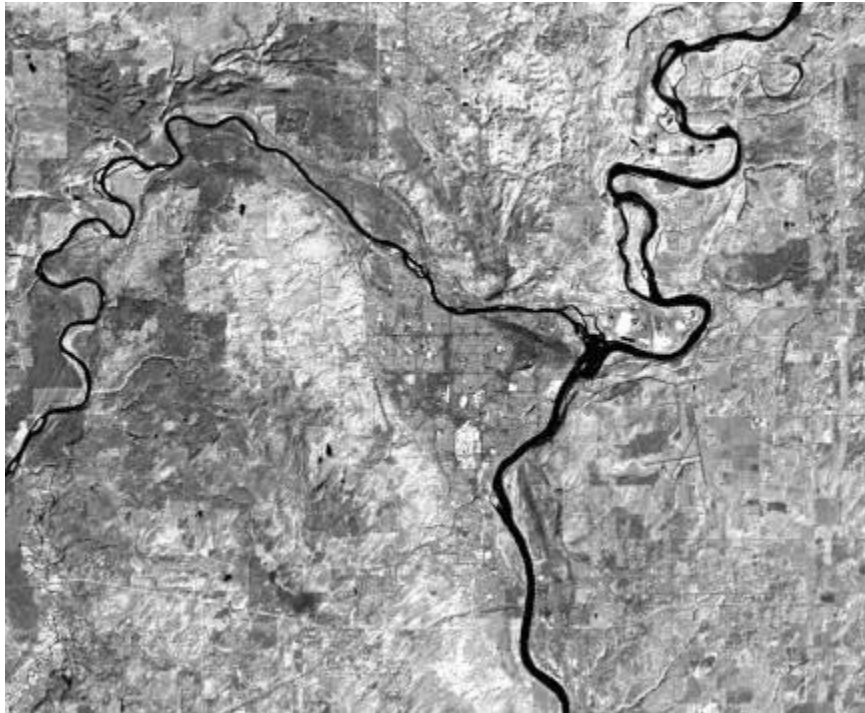
Prince George – scanned IMAGE
(not a photo)

Visible wavelengths .. Looks like a
photo, but no camera

The **near IR** (0.7-1.3 microns) records energy related to **vegetation vigour** (health), while the **shortwave-IR** (1.3-3.0 microns) is dryness.

Neither have much to do with temperature

Near-IR



Vegetation health / vigour

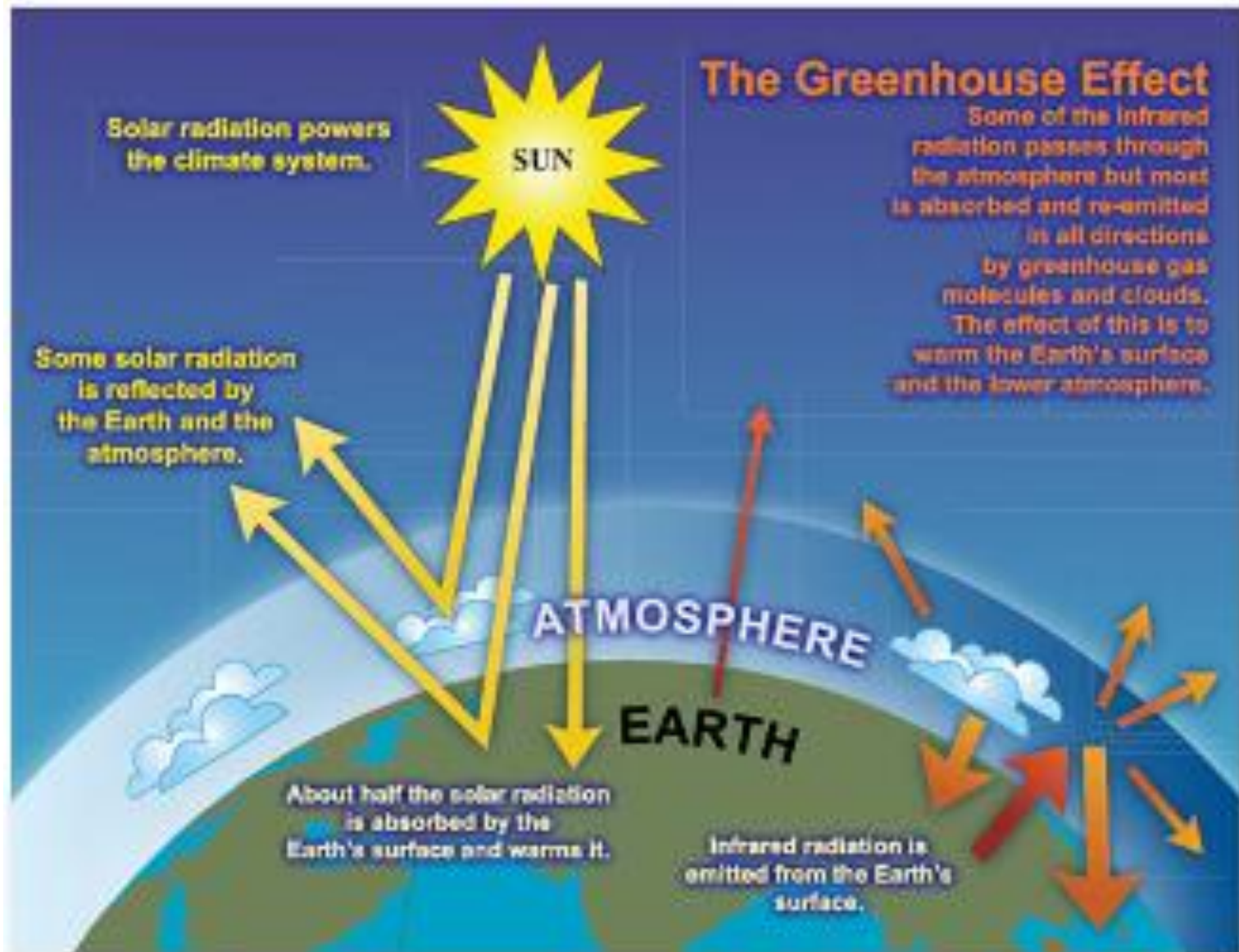
SWIR (Shortwave)



Moisture / dryness

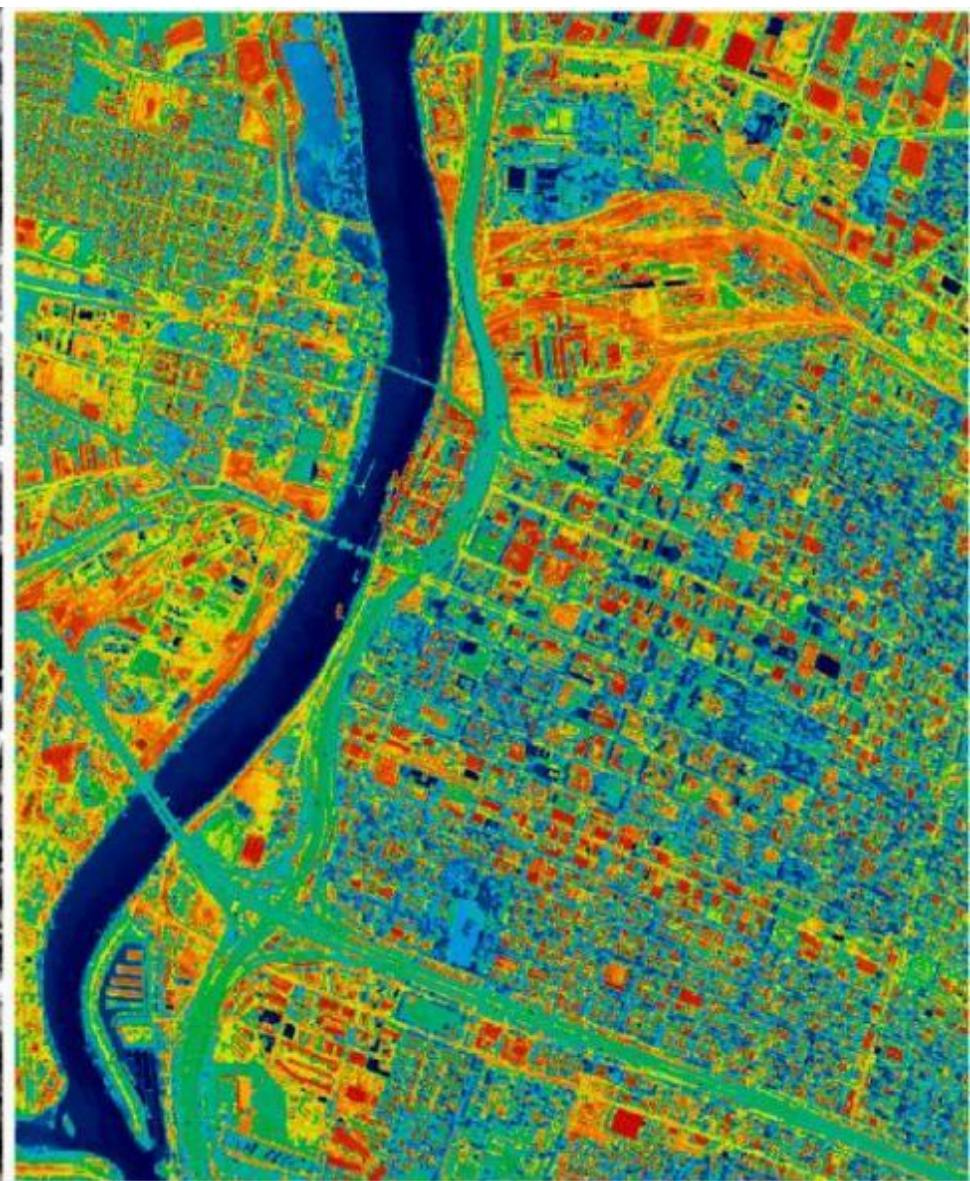
Thermal Infrared (3-14 microns)

This records longer wavelengths and temperature as energy is **emitted** NOT reflected IR



Daytime

Day and night



Normal colour and thermal images of Sacramento, CA

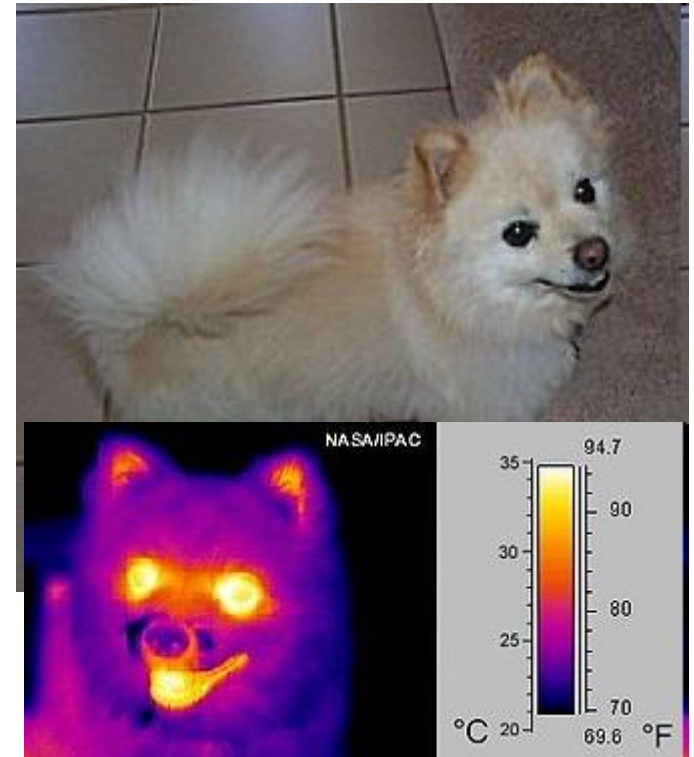
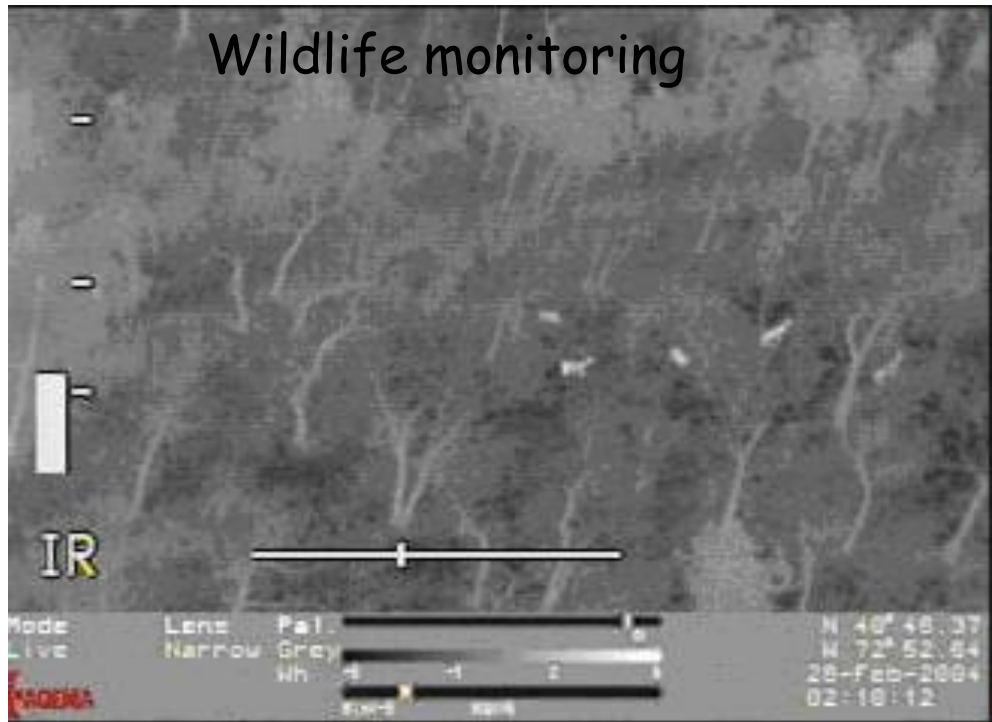
Drones with thermal cameras used to locate Koalas in Australian bush fires



Night vision goggles (Russian military -> equipment) - sensing thermal IR

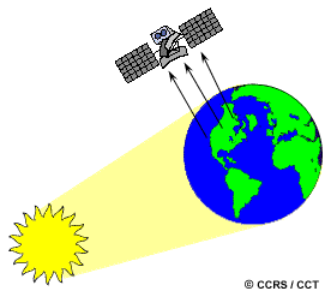


Wildlife monitoring

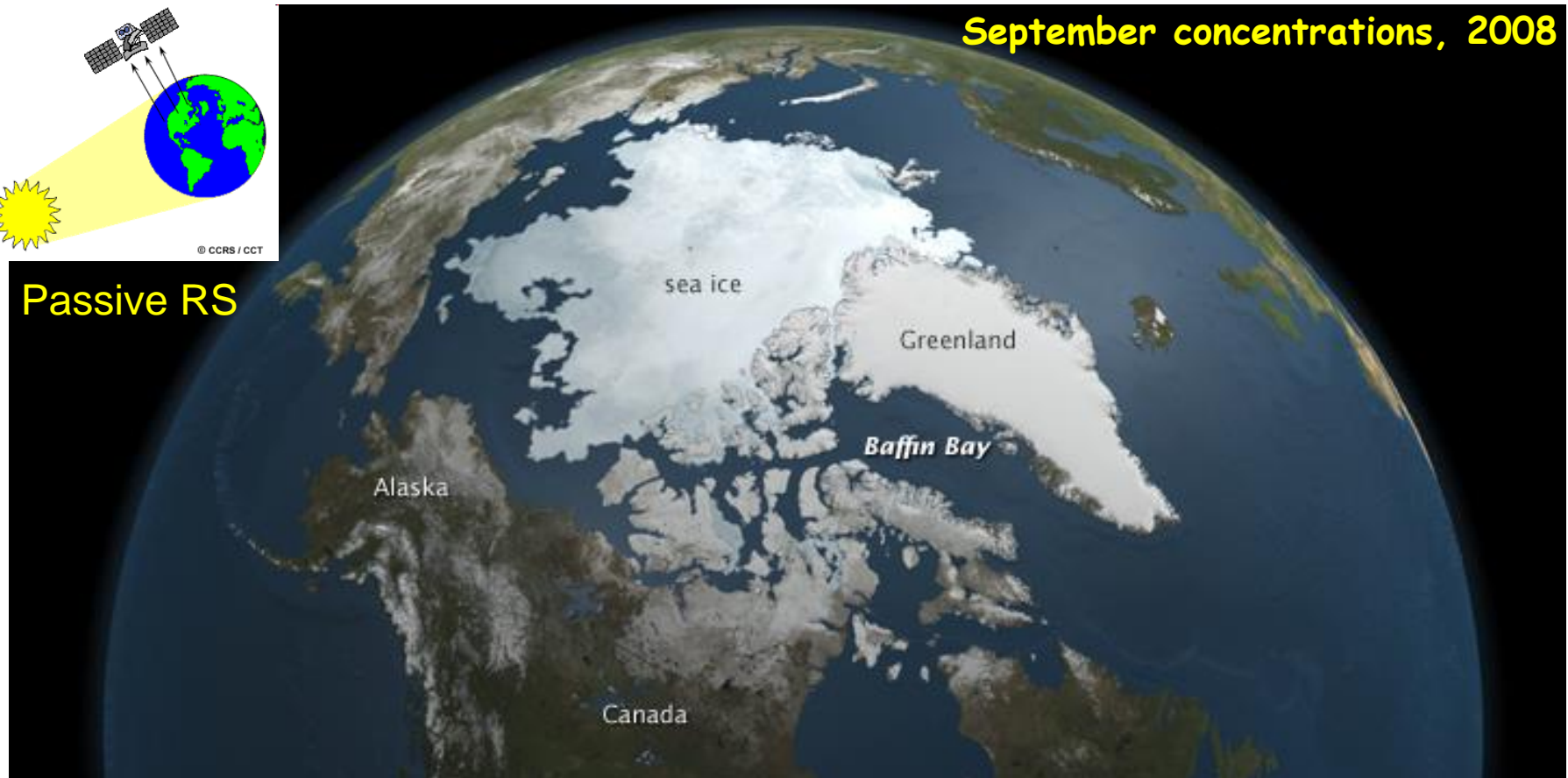


Microwave: 1mm - 1 metre ('passive')

These wavelengths beyond the infra-red can 'see through' clouds, light rain, and snow, but there is a low amount of it; low resolution e.g. 10km pixels ... this is why we use these wavelengths for communications.



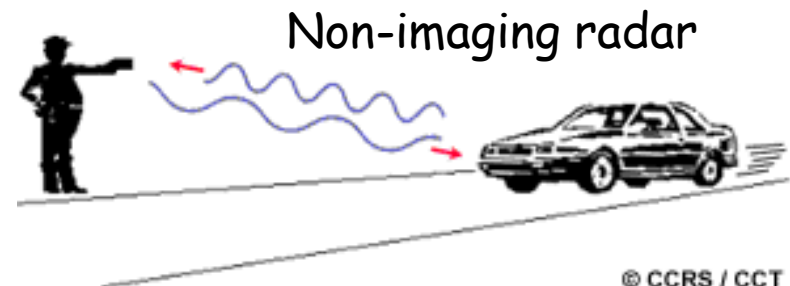
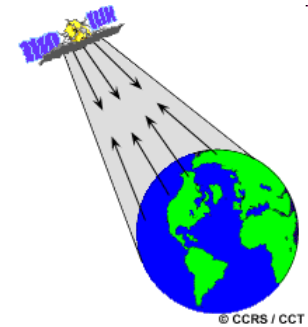
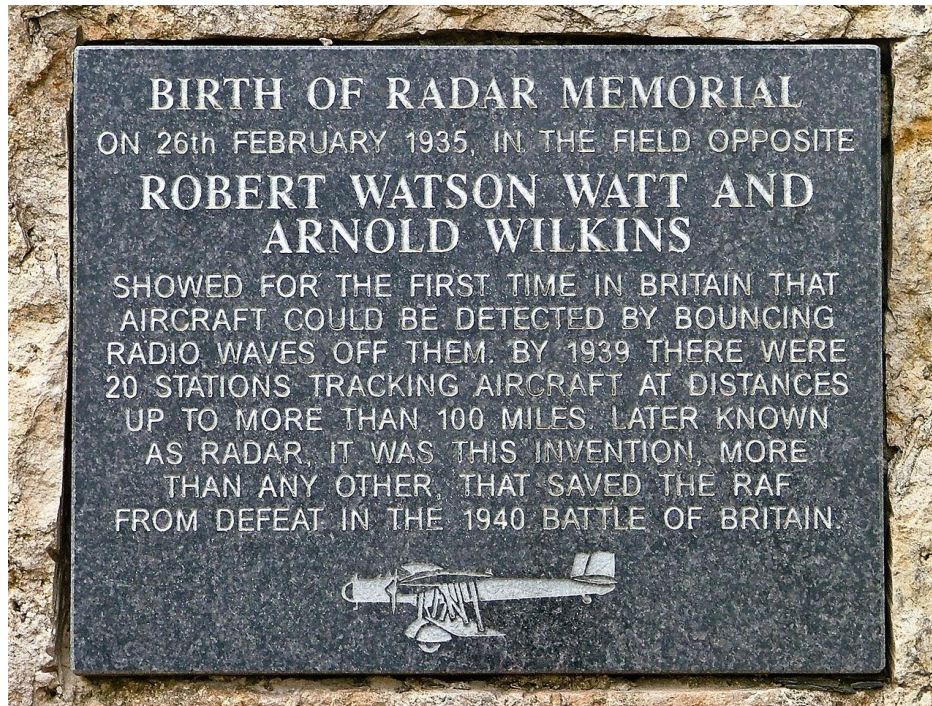
Passive RS




Microwave: - RAdio Detection And Ranging (RADAR)

'active' remote sensing at wavelengths of 1-30 cm

The original technology was developed in the 1930s
to detect enemy ships and planes during WWII



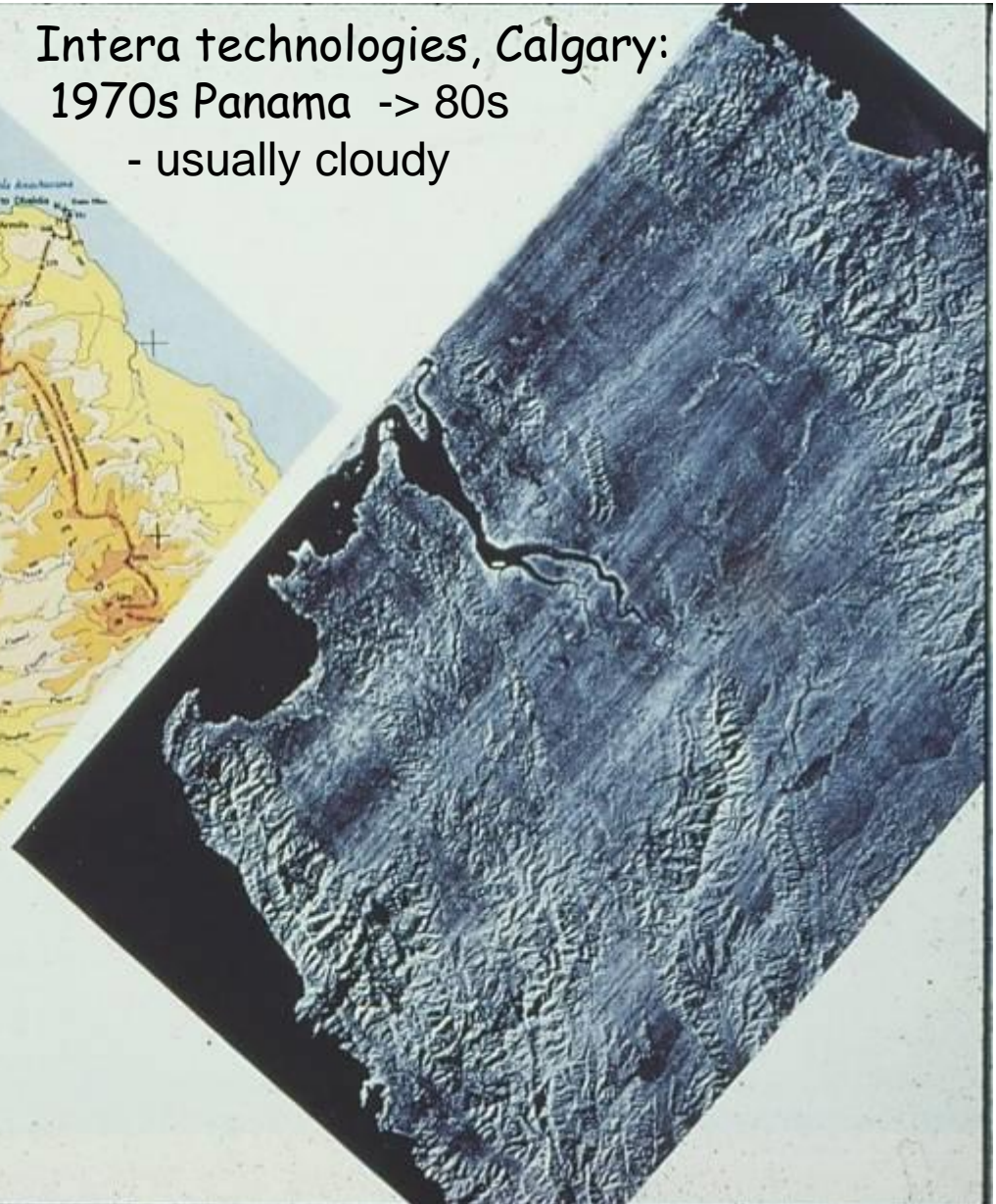
Imaging radar systems have been in use since the 1950s.



Active R

The diagram shows a satellite in the top left corner with a yellow sun-like symbol on its side. Several parallel arrows point from the satellite towards a blue and white globe of the Earth in the bottom right corner. The text 'Active R' is written in a large, bold, black font to the right of the satellite.

© CCRS / CCT



Massachusetts-based Raytheon in 1947 named the original microwave the **“Radarange”** because it cooked food using the same radio-wave-producing magnetron tubes that the company manufactured for use in military radar.

Raytheon credits the discovery of microwave cooking to a radar engineer named Percy L. Spencer. One day in 1945, Spencer was walking through a radar test room with a chocolate bar in his pocket, and the candy began to melt.



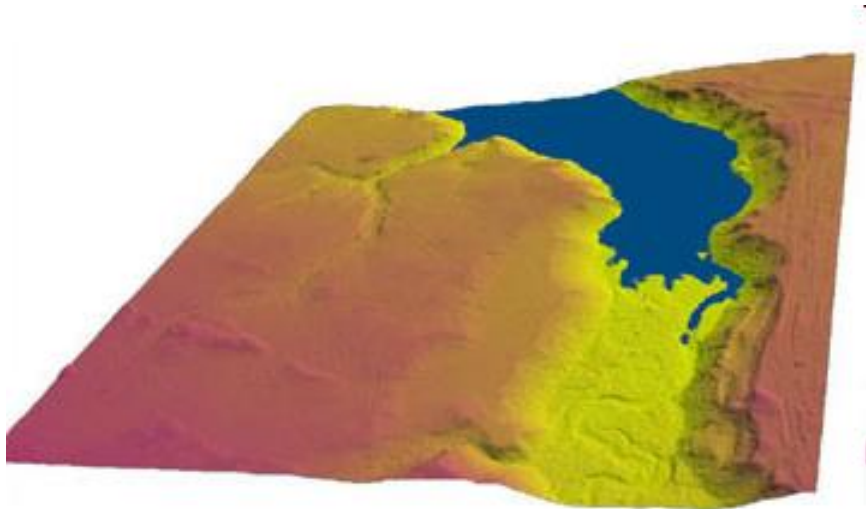
2000 -> **LiDAR** = Light Detection And Ranging

.. is the other common form of active remote sensing

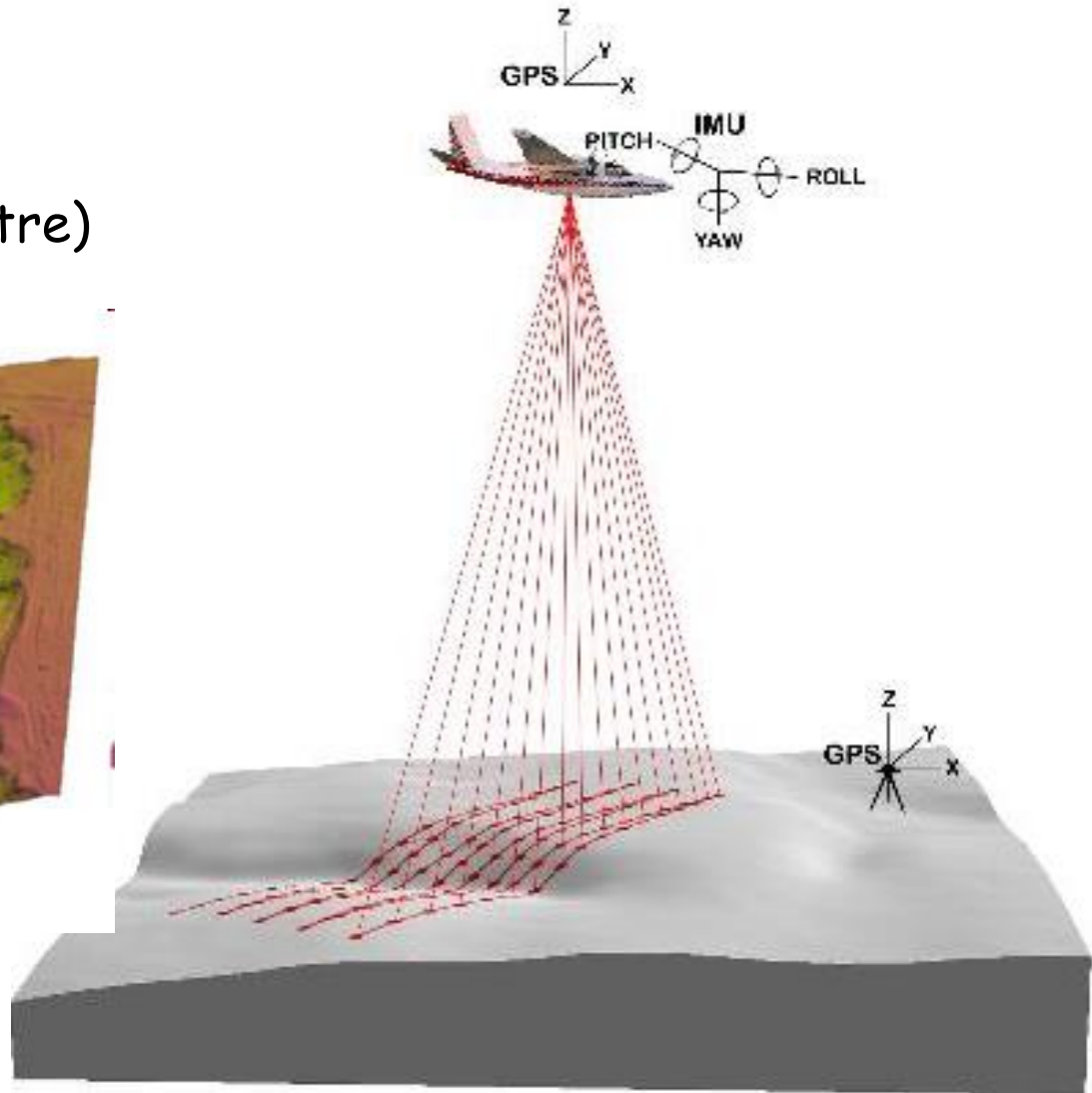
visible/NIR wavelengths

It is often used to create

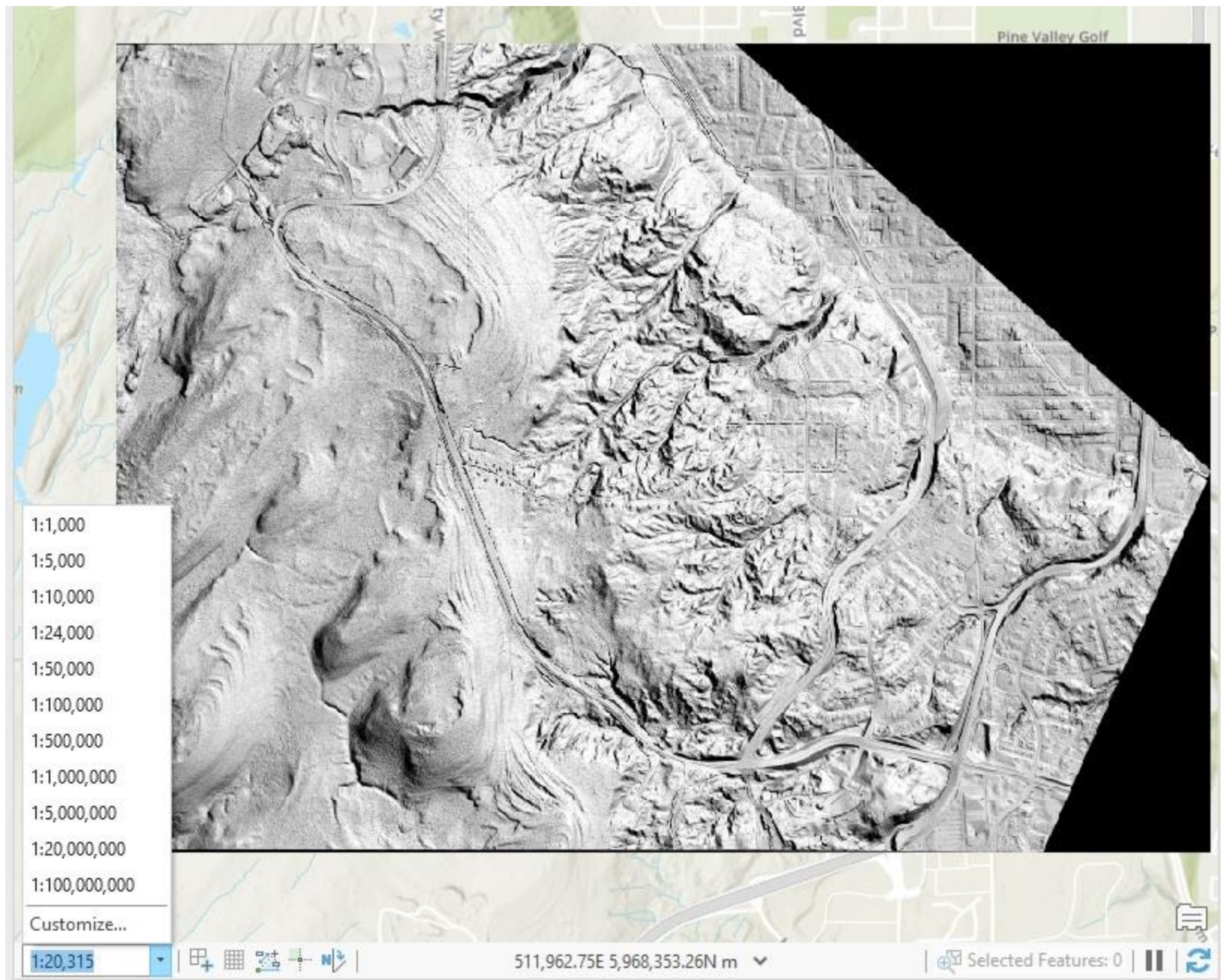
high resolution DEMs (< 1 metre)



Major BC cities with rivers are mapped by LiDAR for flood levels

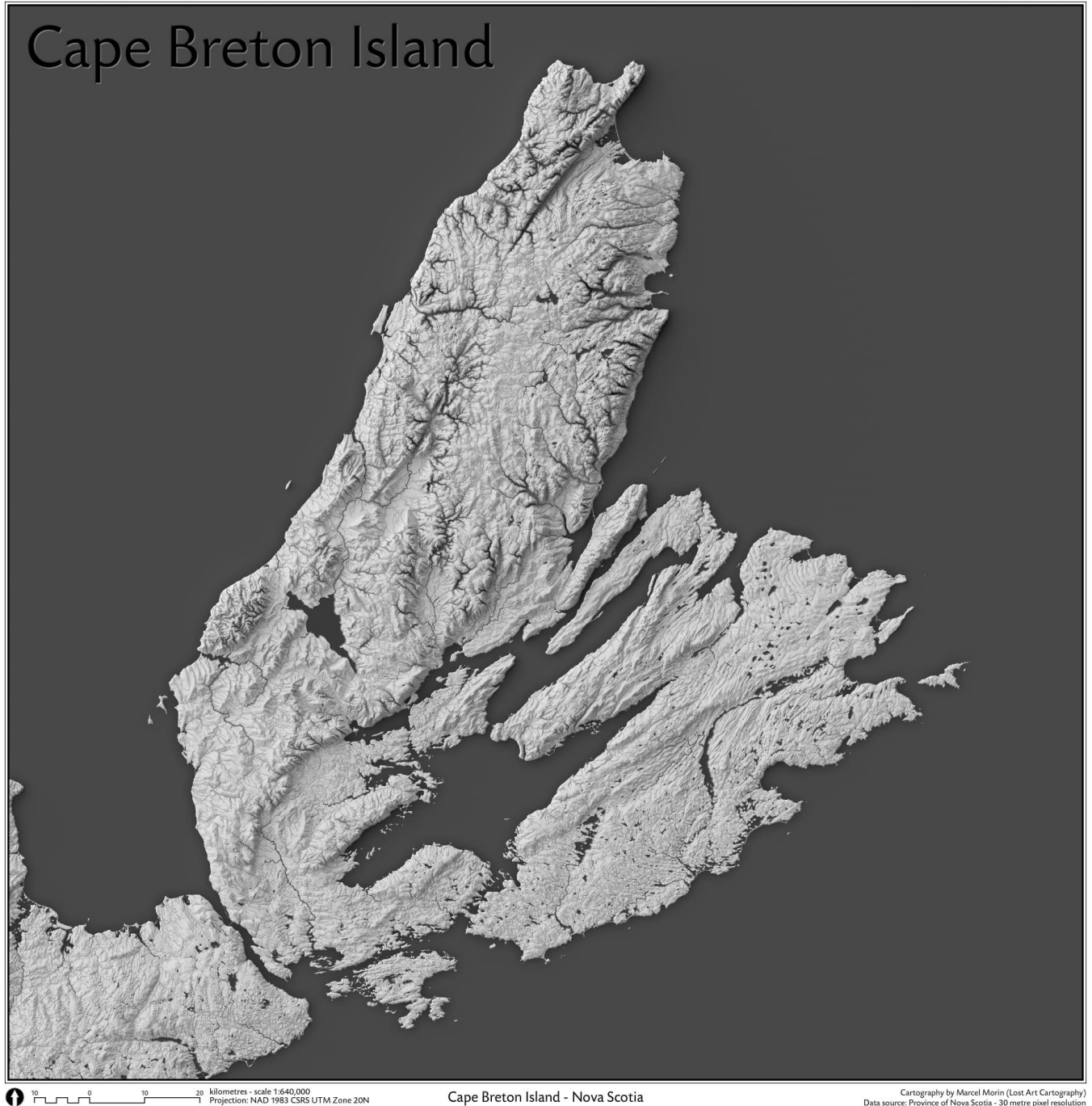


Cranbrook Hill – LiDAR DEM, City of PG (image from Lab 1)

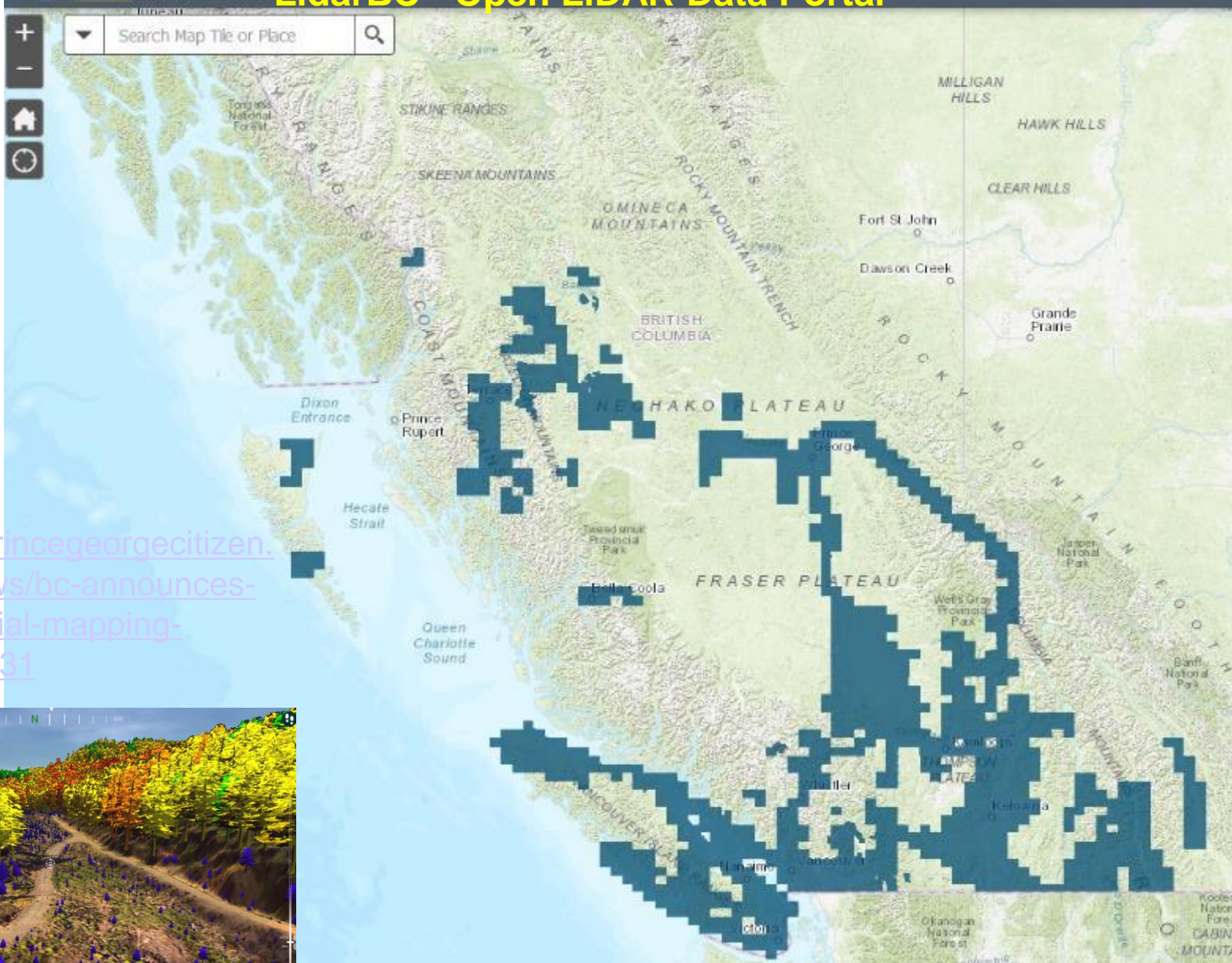


Cape Breton Island

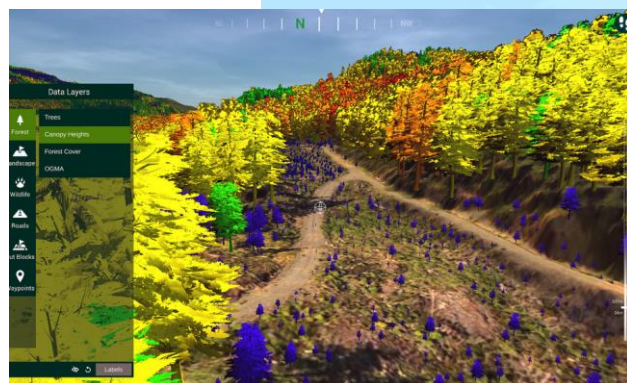
Maritime
provinces:
complete
LiDAR DEM
freely
downloadable



LidarBC - Open LiDAR Data Portal



<https://www.princegeorgecitizen.com/local-news/bc-announces-38-million-aerial-mapping-project-6853531>



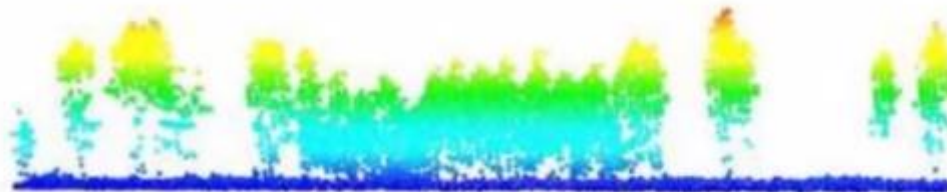
Point
elevation



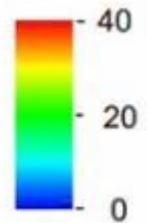
Surface
elevation



Point
height above
surface



Height (m)



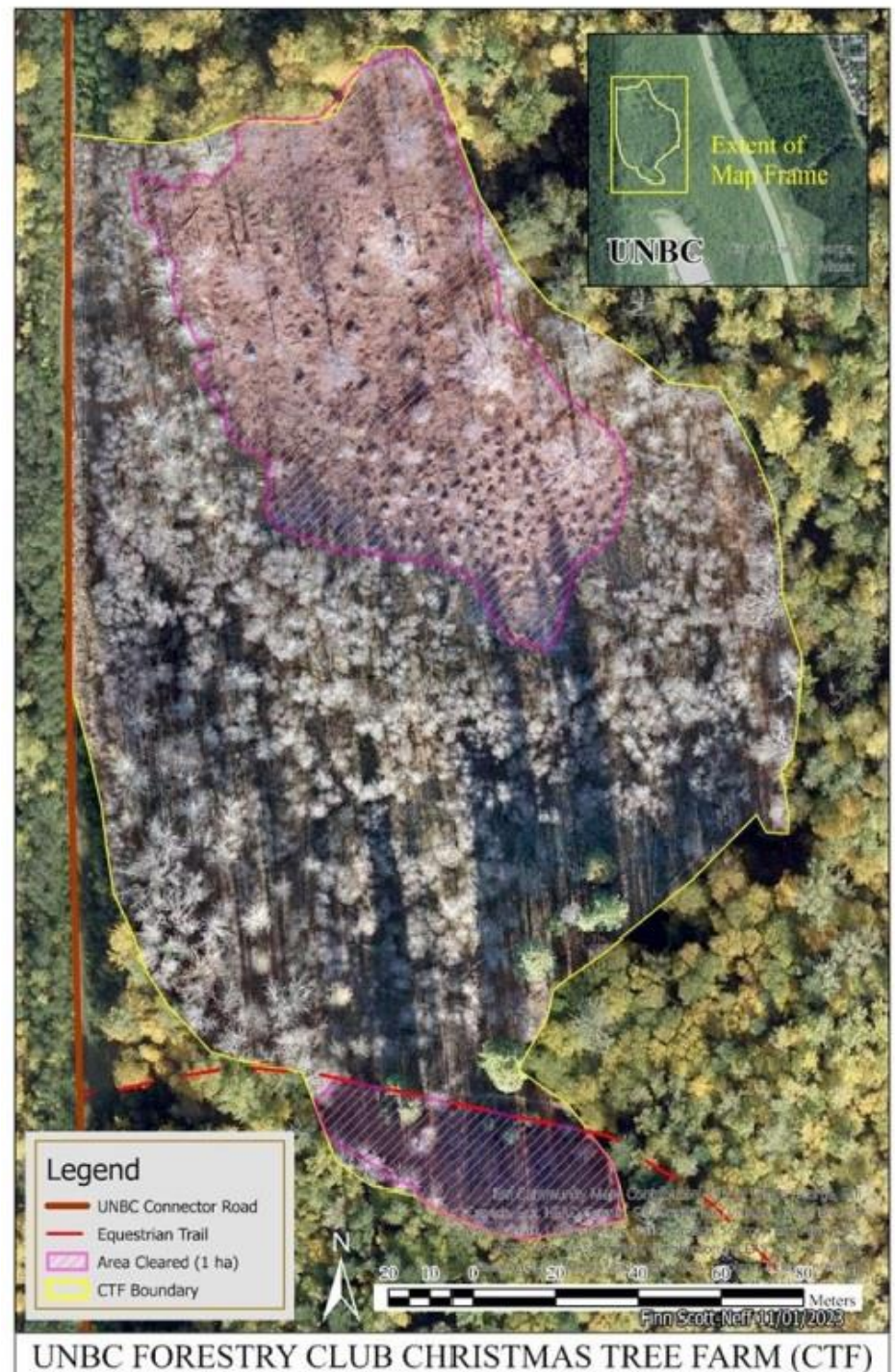
University of Calgary fly-through: LiDAR DEM and draped orthophotography

http://www.youtube.com/watch?v=_myUhYPeAew

Captured by quadcopter UAV, fall 2023
for GEOG 357 project, by Matt McLean

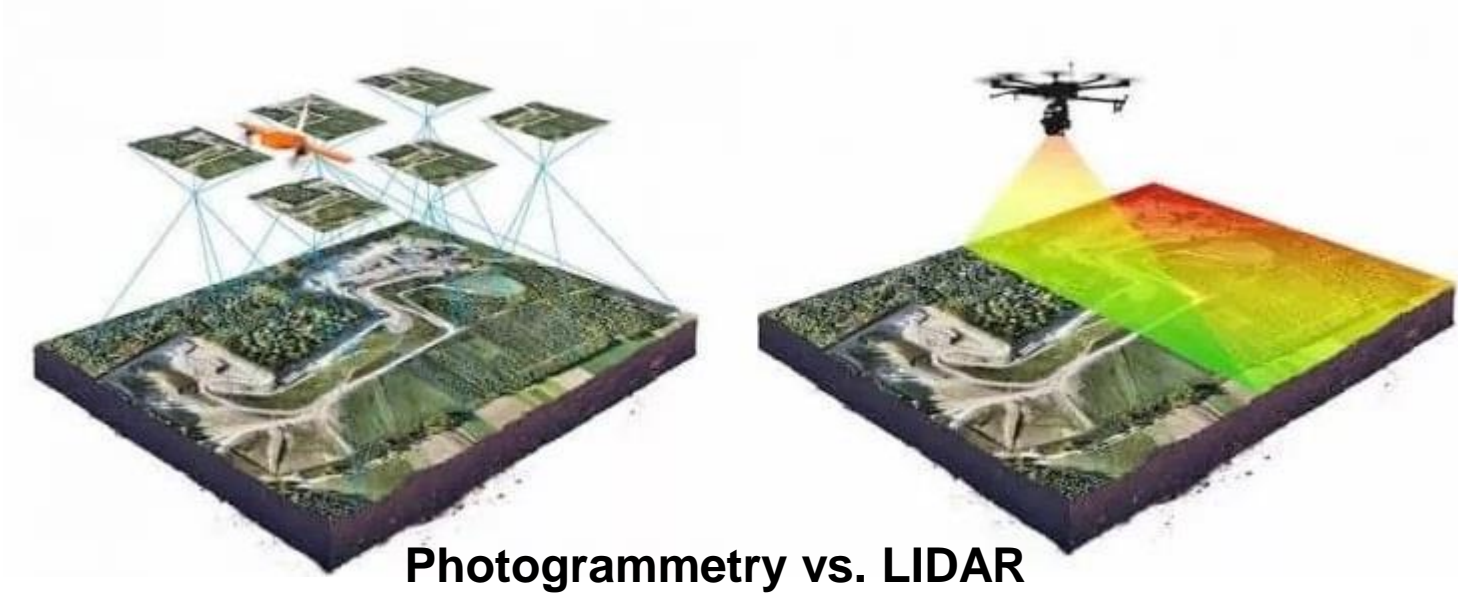
Pixels 3cm (visible) and 10cm (thermal)

DEM from City of PG LiDAR
DEM combined with orthophoto



2000s -> Mapping from drones - UAVs

Unmanned Aerial Vehicles – easily and quickly launched



Matterhorn:

https://www.youtube.com/watch?v=Fs2C_wXQ_IM



This week's lab: Lab 07 Web mapping or online mapping

... is the process of creating and distributing maps on the World Wide Web, usually through the use of Web geographic information systems.

Web mapping is more than just web cartography, it is a service where consumers may choose what the map will show.

They can be divided into *static* and *dynamic* web maps and further into *interactive* and *view only* web maps.

e.g.

1994: Atlas of Canada, world first online atlas

2004: OpenStreetMap (OSM)

2005: Google maps

2012: Apple maps