

LiDAR = Light Detection And Ranging ...also known as LASER altimetry

An increasingly common form of active remote sensing

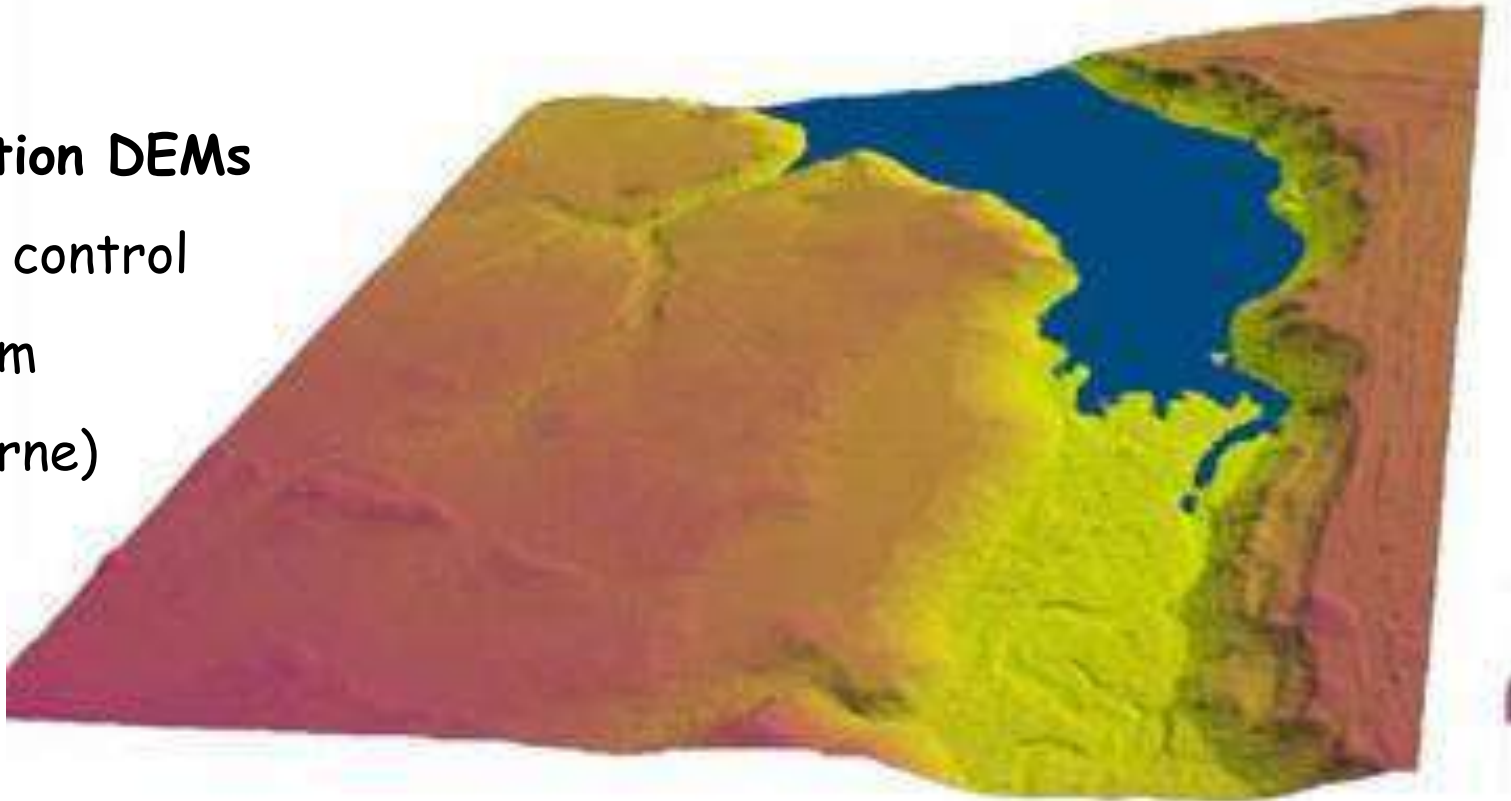
Objects reflect more in UV/visible/NIR (than radar microwaves) =
higher resolution mapping

- **high resolution DEMs**

e.g. for flood control

~1 foot or <1 m

(mostly airborne)



What is LiDAR ?

Controlled bursts of LASER
(Light Amplification by Stimulated
Emission of Radiation)

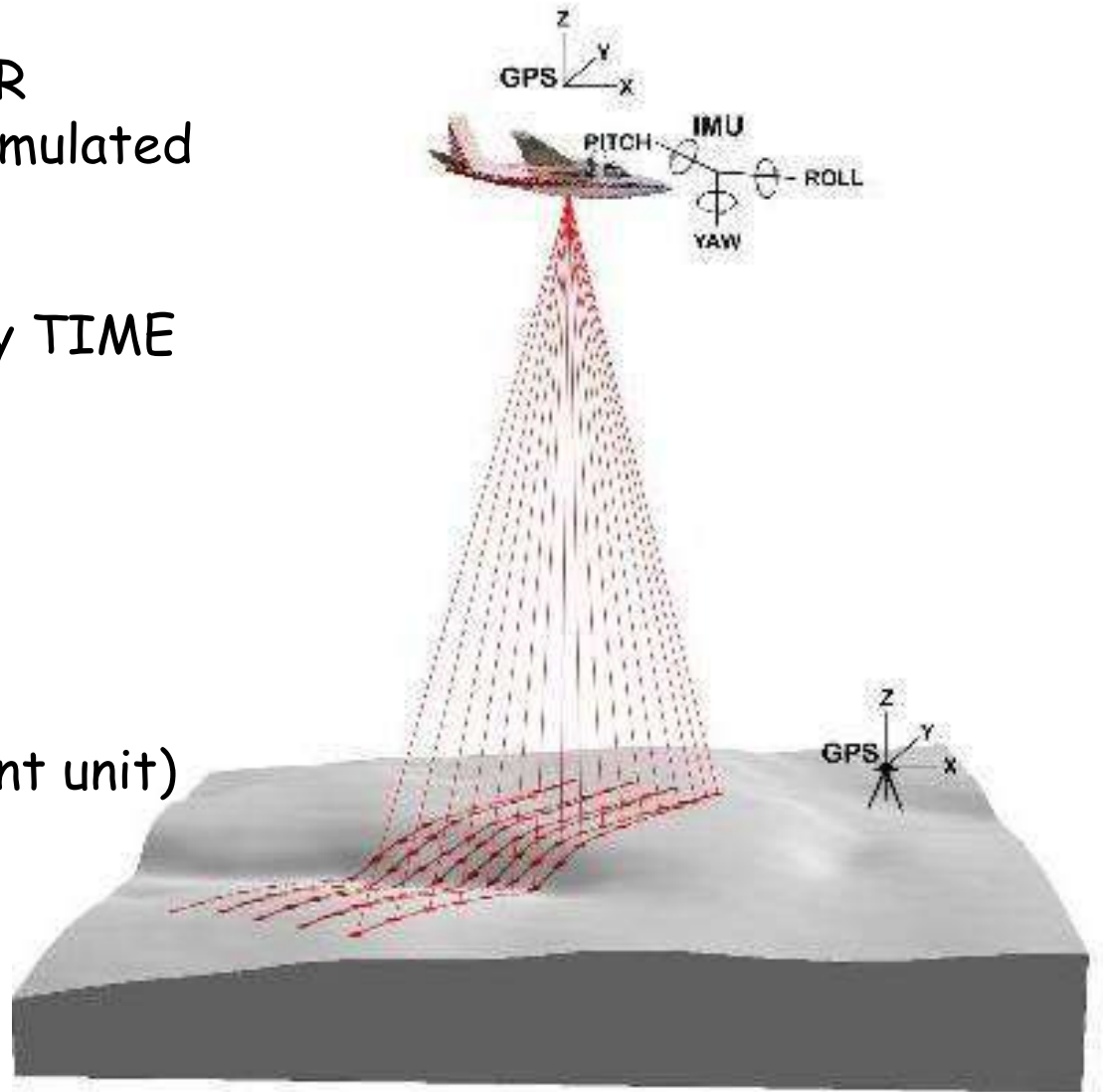
Distance to object given by TIME

-requires 3 units:

-laser emitter/receiver,

-GPS,

-IMU (Inertial measurement unit)



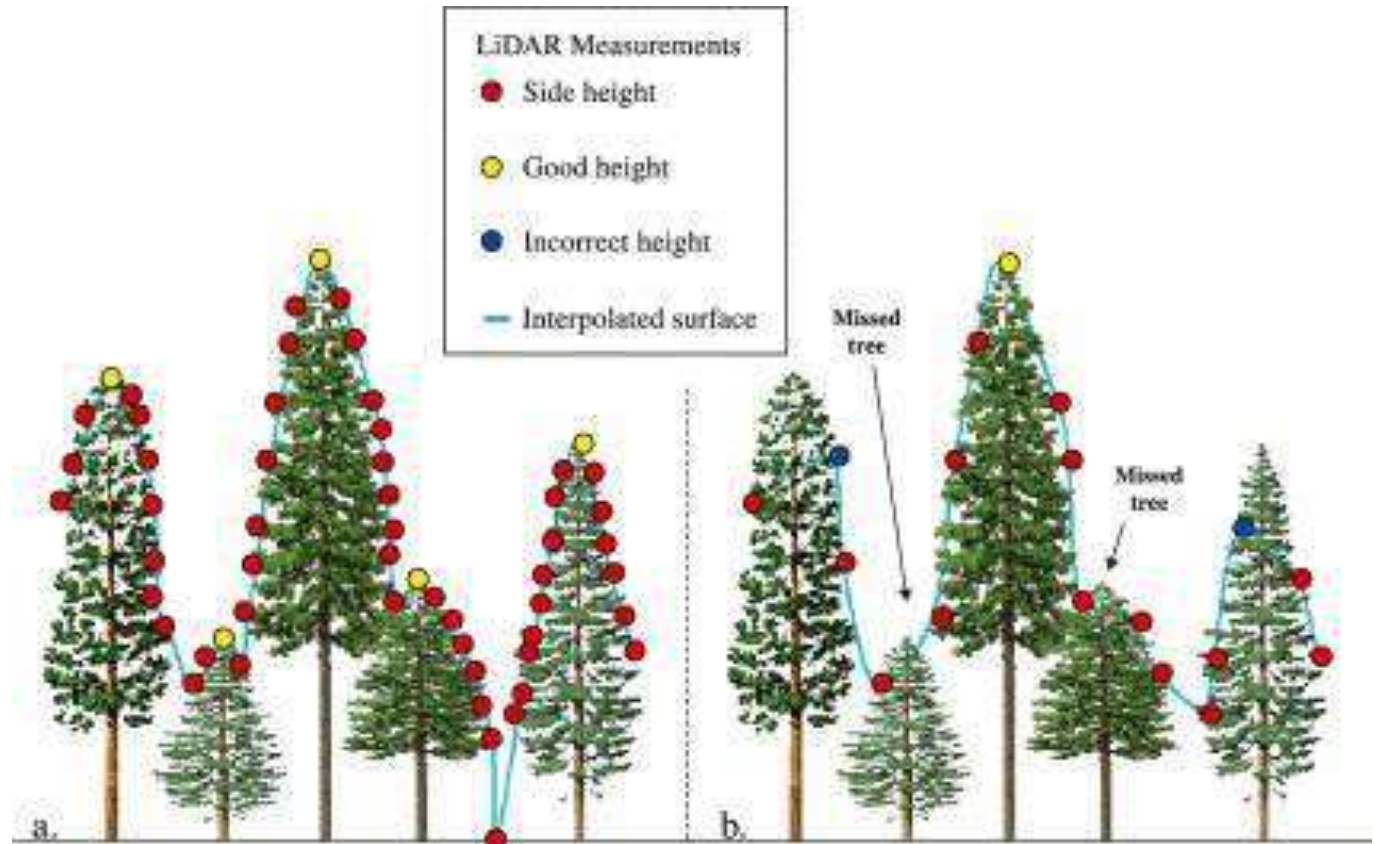
Laser pulses at up to 50,000 - 200,000 / second

Resulting cloud of points: up to 20 points / square metre

~10/sq m needed for forestry 1 / sq m for glaciers (no trees)

Horizontal accuracy 50cm - 1m, vertical ~20cm

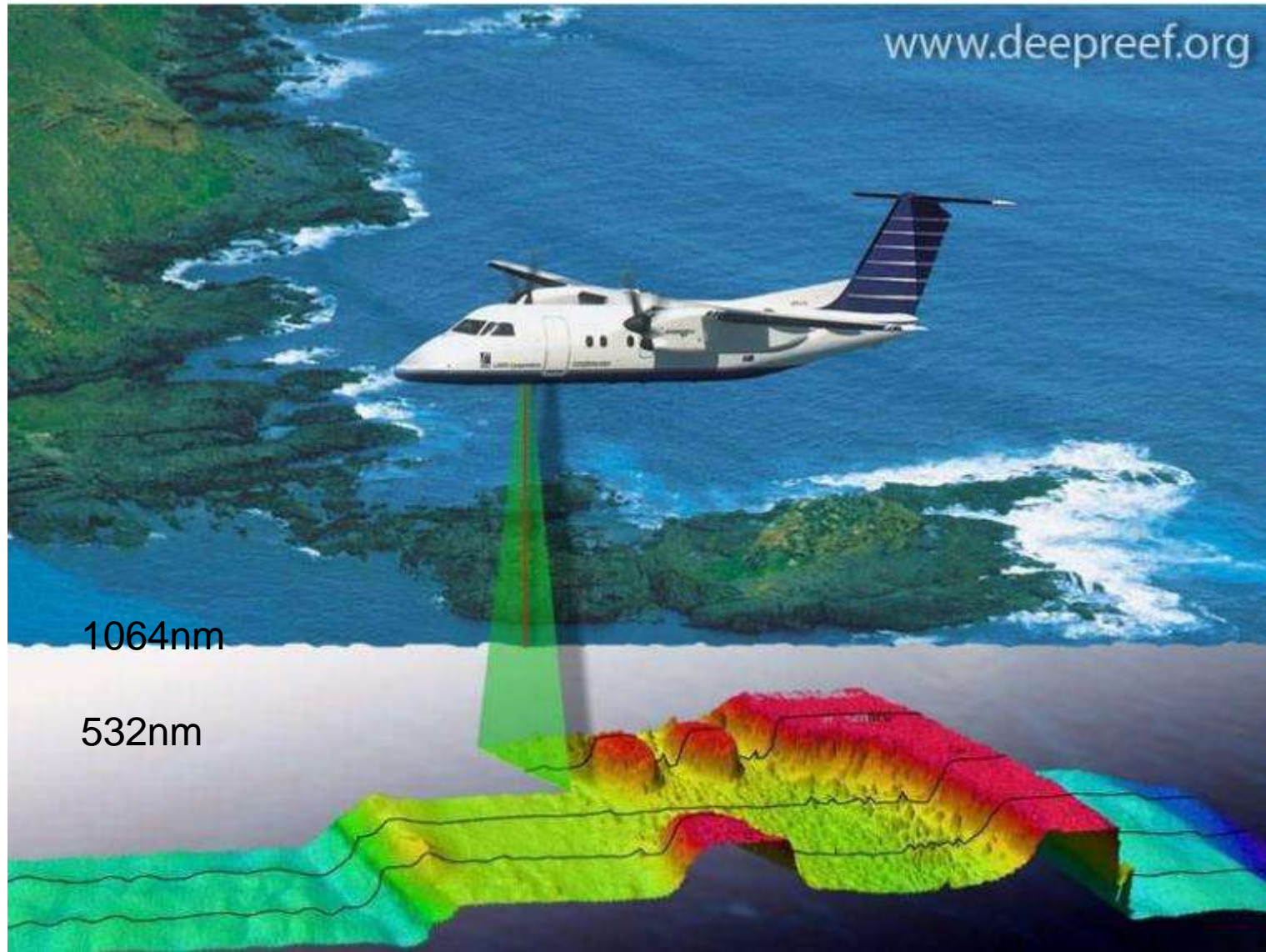
Cloud of points is converted to raster grid ~1metre



Related technologies:

SONAR: SOund Navigation and Ranging : sound propagation for communication/ navigation

SODAR: SOnic Detection And Ranging : sound propagation upwards (atmospheric)



Range finding LiDAR for topographic mapping

Unaffected by clouds above (unlike air photos) .. *why?*

Laser bursts are emitted usually at one of these wavelengths:

- 355 nm (UV): wind, water vapour
- 532 nm (green): bathymetry
- 1064 nm (Near IR): surface mapping

..... (why these ??? *) This was not solved by googling or LiDAR vendors

* I asked this every class and offered a 6-pack to who could solve this

Taser guns are at 650 nm ; phasers (Star Trek) at 350nm

LiDAR - 1064 nm, 532nm, 355nm -why those wavelengths?

Lasers produce light the same way as a neon sign - a substance is stimulated to an excited state, causing the release of extra energy as a photon of light.

Nd:YAG (*neodymium-doped yttrium aluminium garnet*) is a crystal that is used as a lasing medium for solid-state lasers. It emits at a wavelength of 1064 nm.

According to the Planck-Einstein equation:

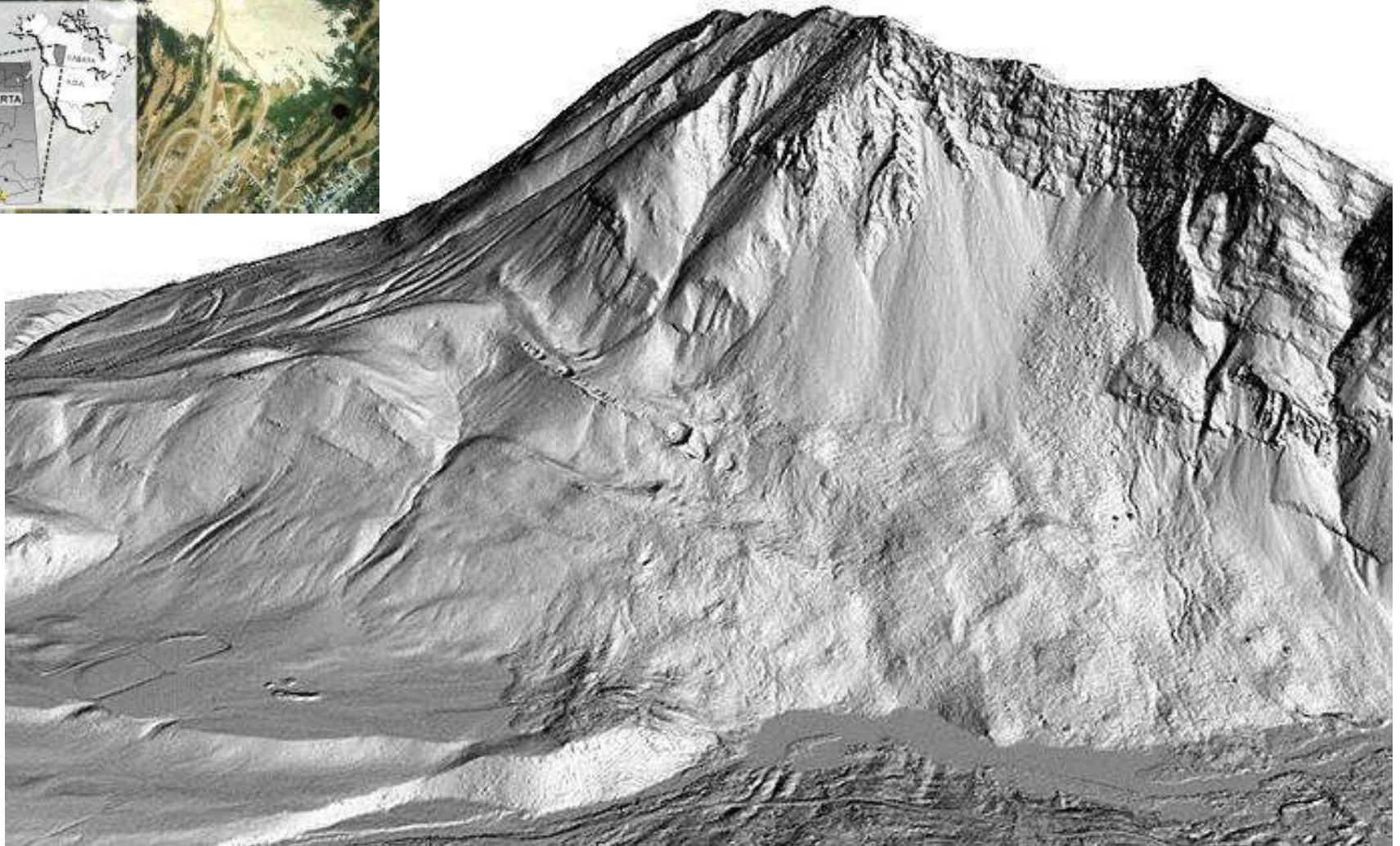
$$E = \frac{hc}{\lambda}$$

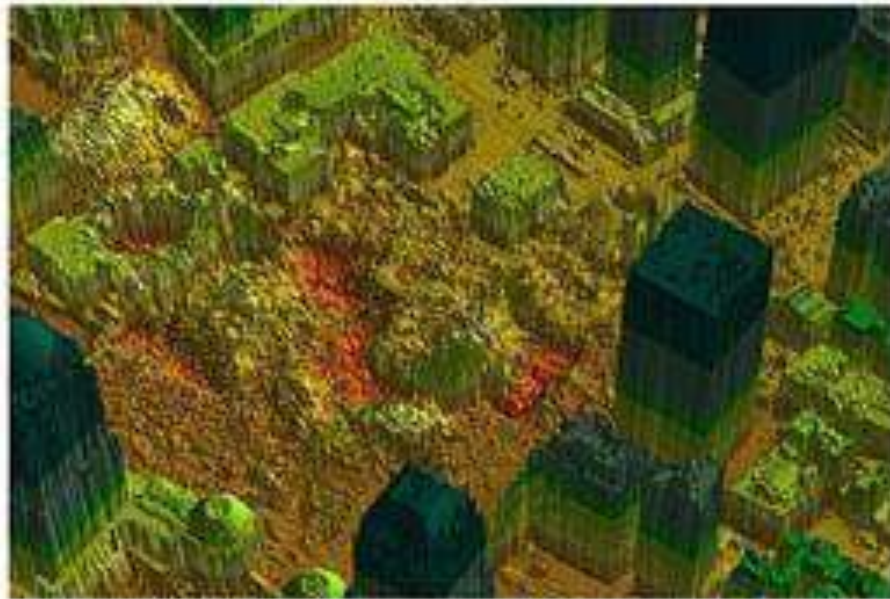
Where h = Planck's constant, and c = the speed of light; halving the wavelength, has the effect of doubling the energy released, and one-third the wavelength (355) triples the energy (= the second and third harmonics)

Solved by Patrick Daley, (Fall 2009) - wins a 6-pack of Guinness



Turtle Mountain, AB (Frank slide, 1903)



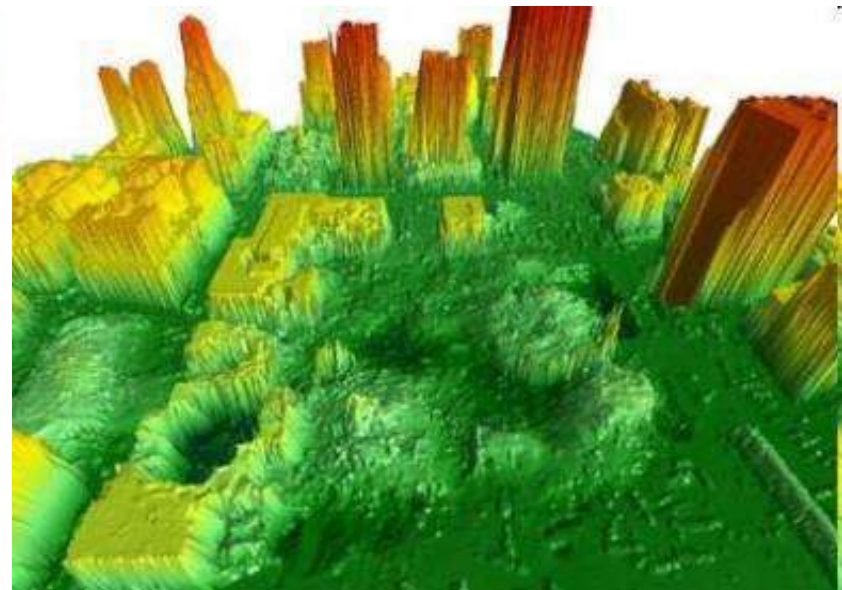


Volume estimation:

**Ground Zero, World Trade
Centre site, New York**

Post September 2001

<http://www.volker-goebel.de/Lidar.html>





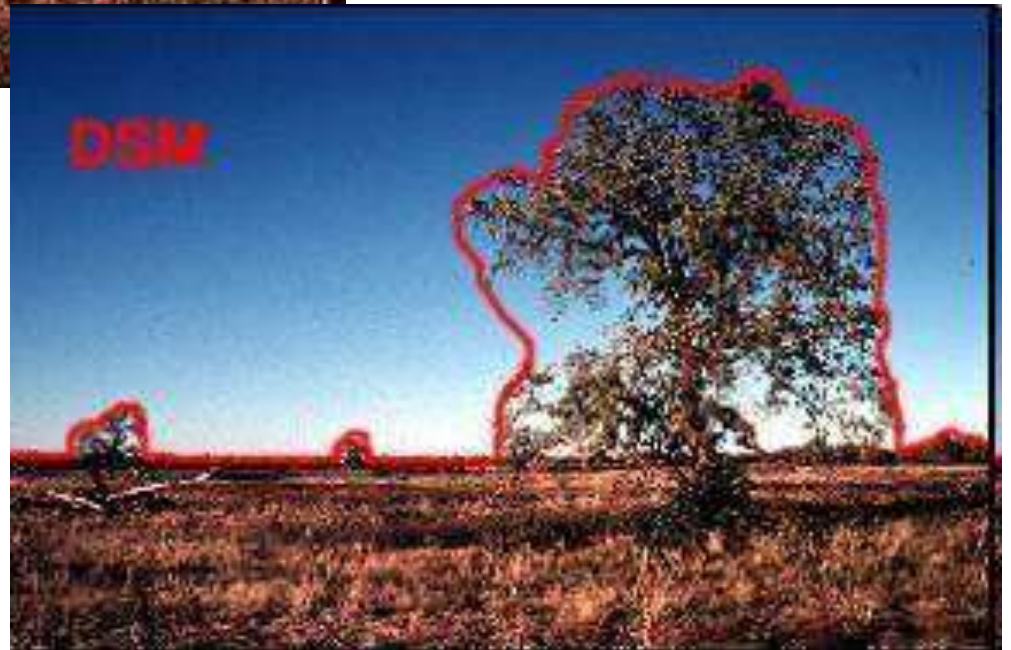
Repeat slide from DEMs

Digital Terrain Models

➤ Photogrammetric
(and LiDAR)

Digital Surface Models

➤ Spaceborne
(and LiDAR)



Vegetation: Tree Canopy Height

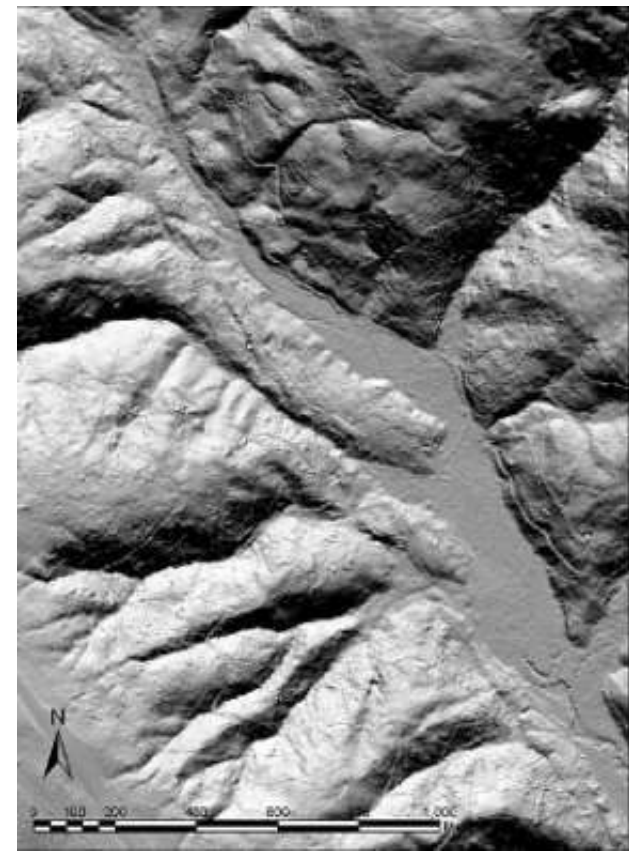
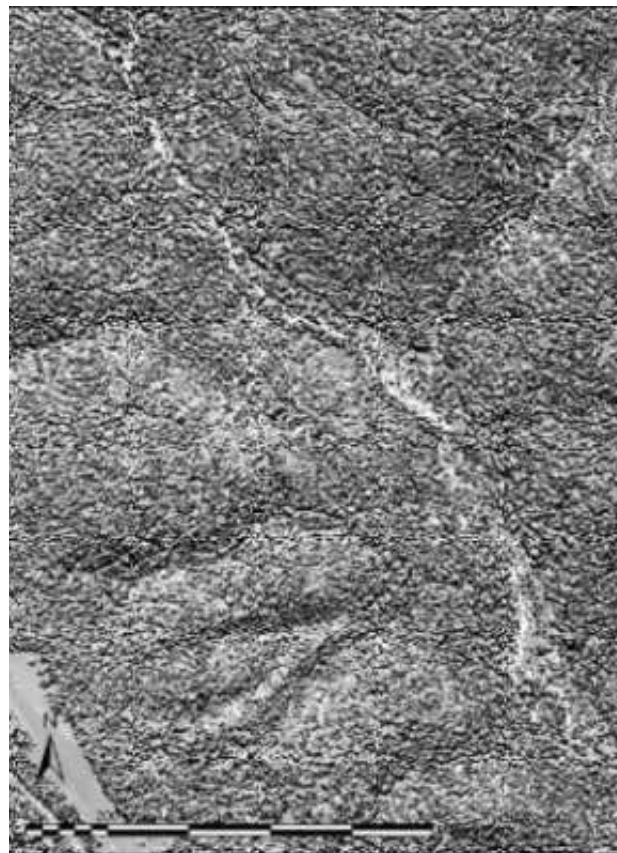
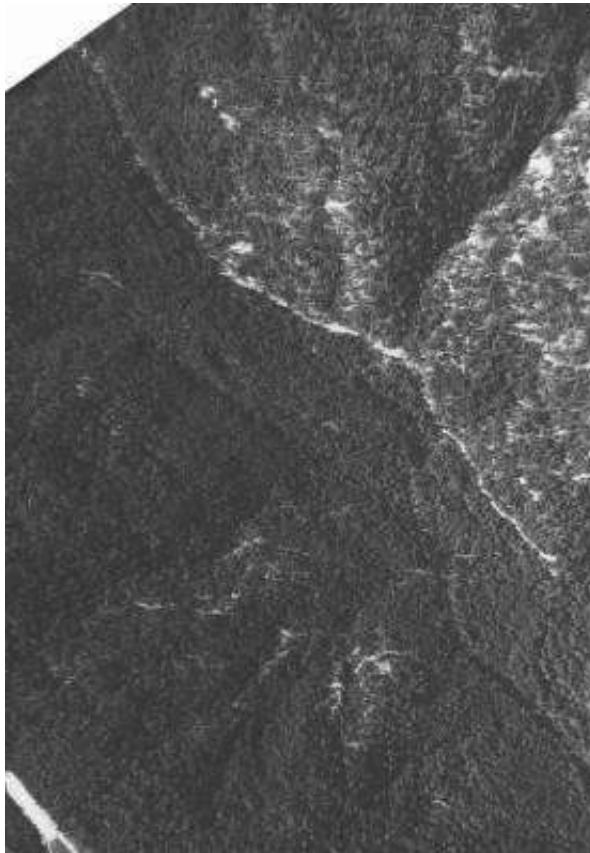
<http://quake.wr.usgs.gov/research/geology/lidar/example2.html>

Air photo

Vegetation surface DSM

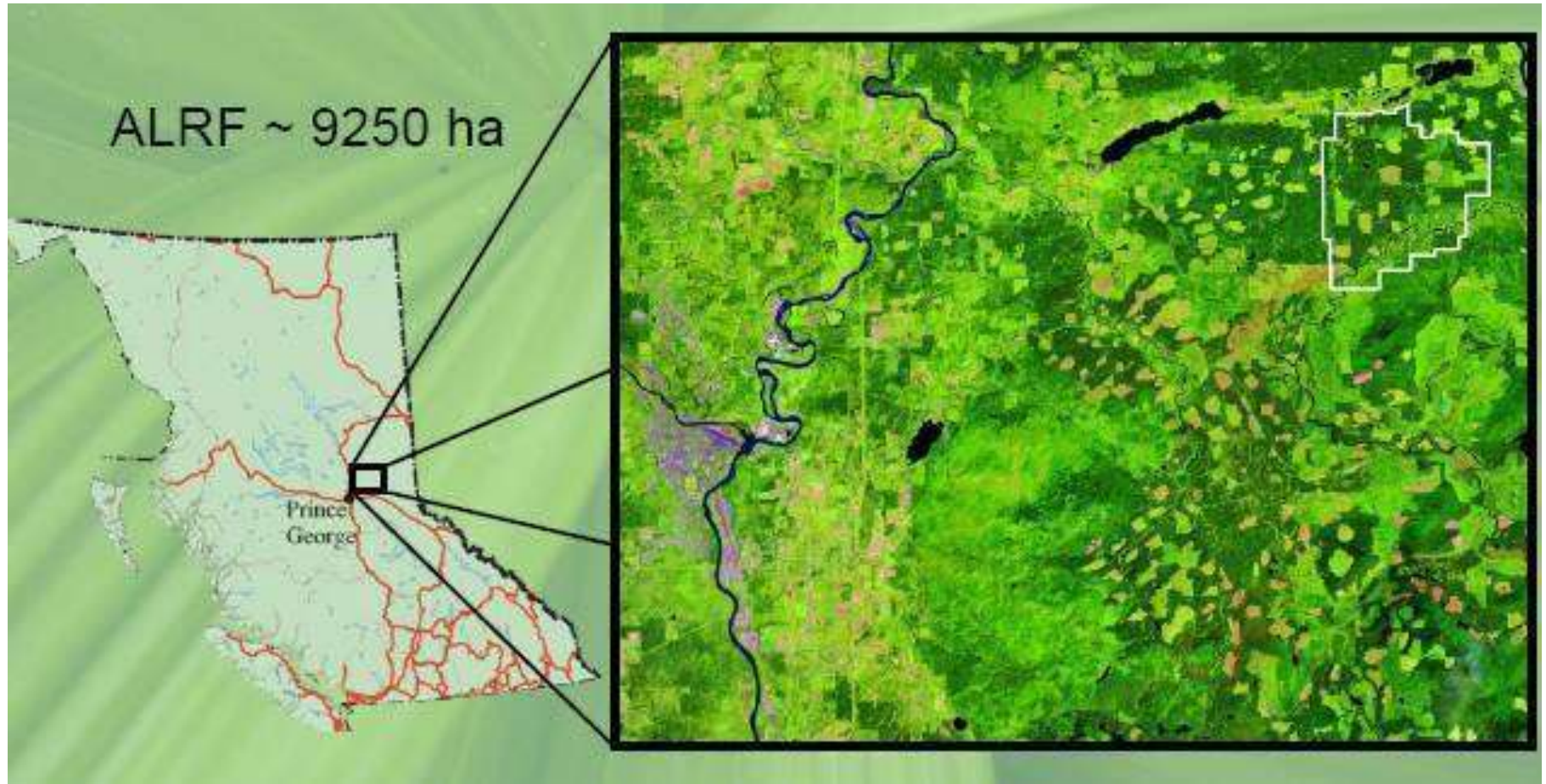
Bald Earth Model (BEM/ BEDEM)

Vegetation height = DSM minus BEM

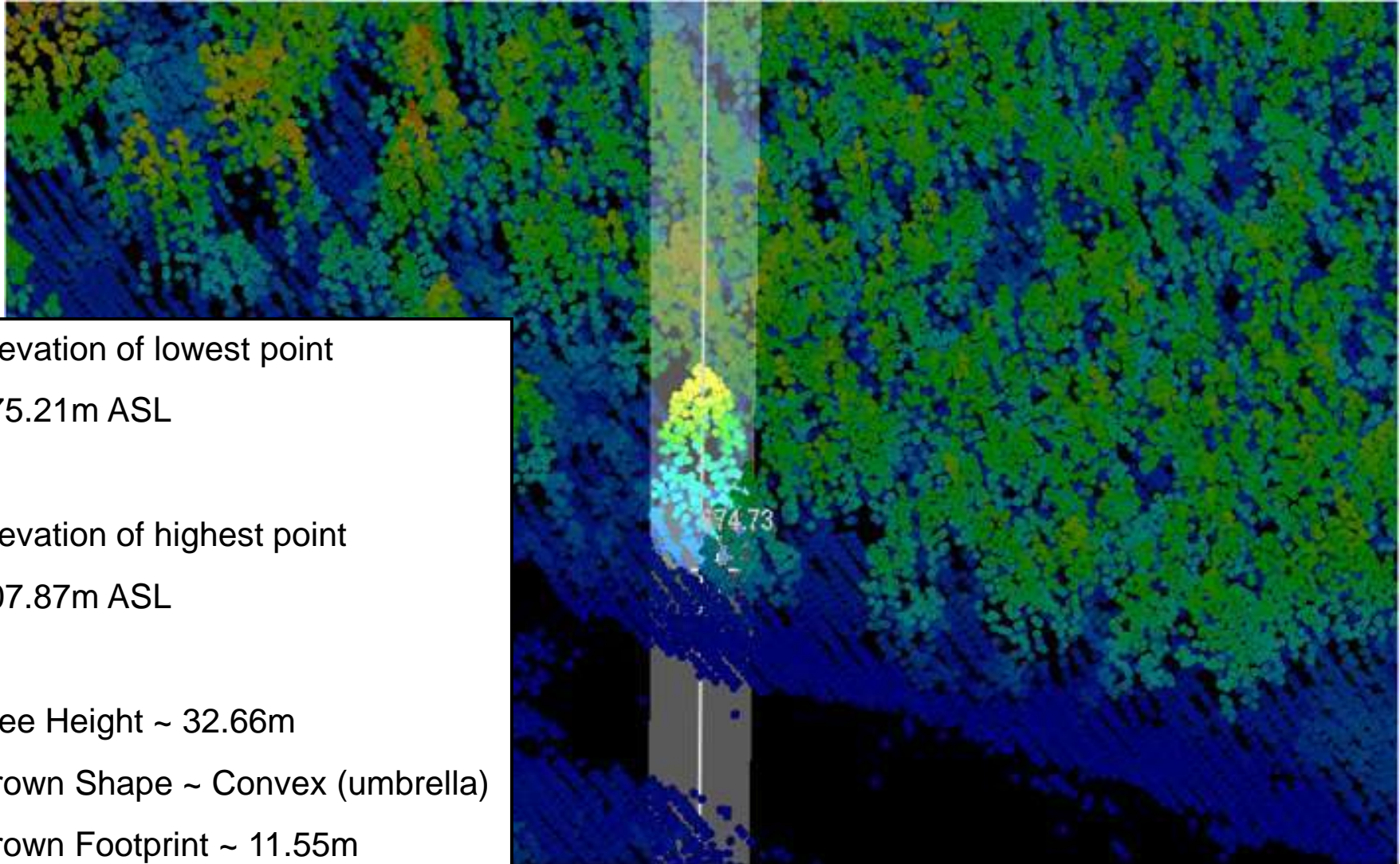


Aleza Lake Research Forest

Oldest research forest in BC, jointly operated by UBC and UNBC
60km north-east of Prince George

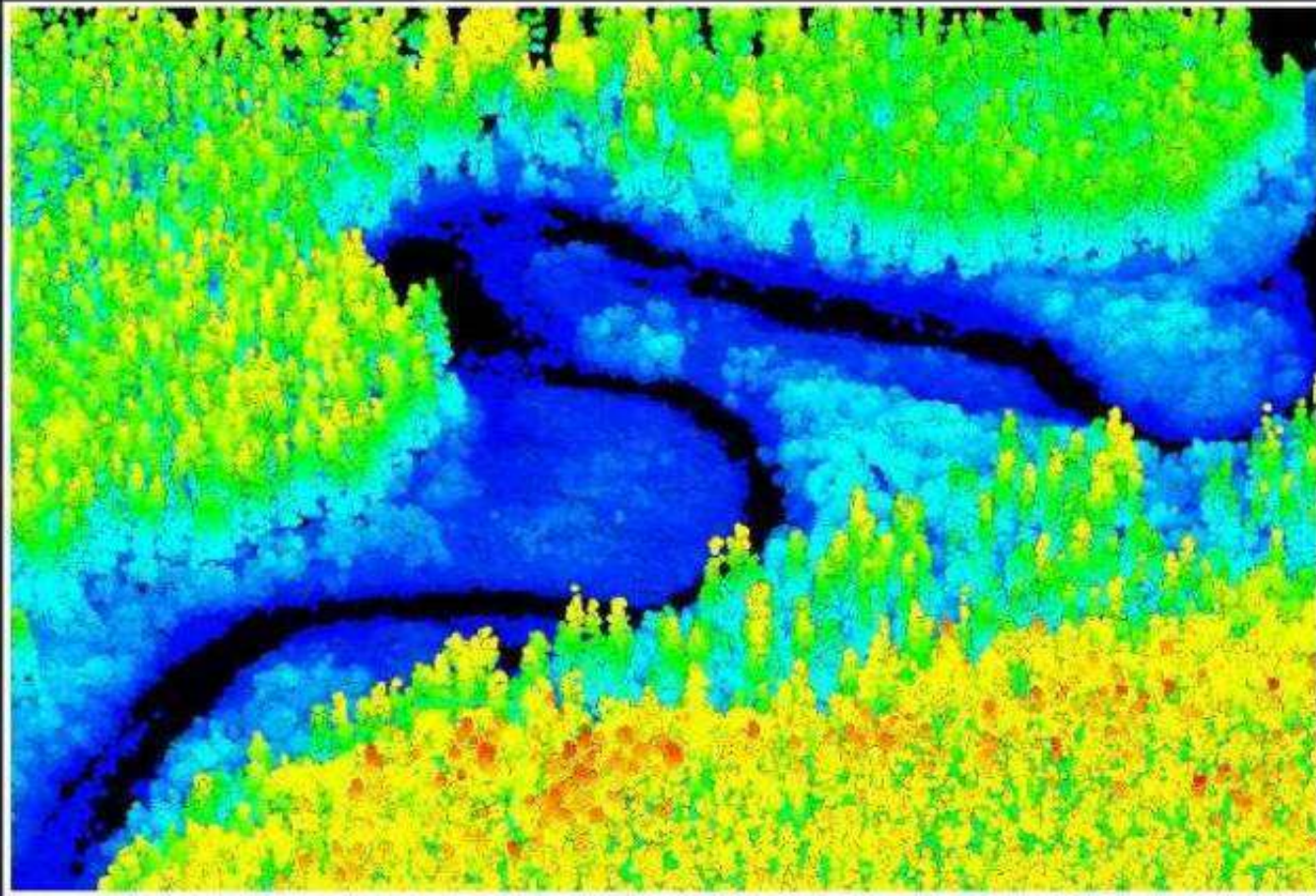


LiDAR reveals both 'bare earth' (ground) and canopy height



UNBC LiDAR datasets: UNBC campus, Aleza Lake RF, JPRF, Ancient Forest

Mass Points



500m x 500m ~ 1,000,000 points

LiDAR Data Products

Mass points detailing elevation can be converted into:

- Bare Earth Model (BEM)
- Slope, Aspect, and Hillshade models
- Canopy Surface Model

Numerical models can be built to estimate:

- Species, volume, dbh, biomass

Canopy Surface Model

shaded relief draped on DEM



Canopy Height = Canopy Surface – Bare Earth

Canopy Height Model

tree height = DN (brightness)



Hansard Creek Digital Aerial Photography



1:2,500



Contour Model (1m Interval)

Aleza Lake FSR

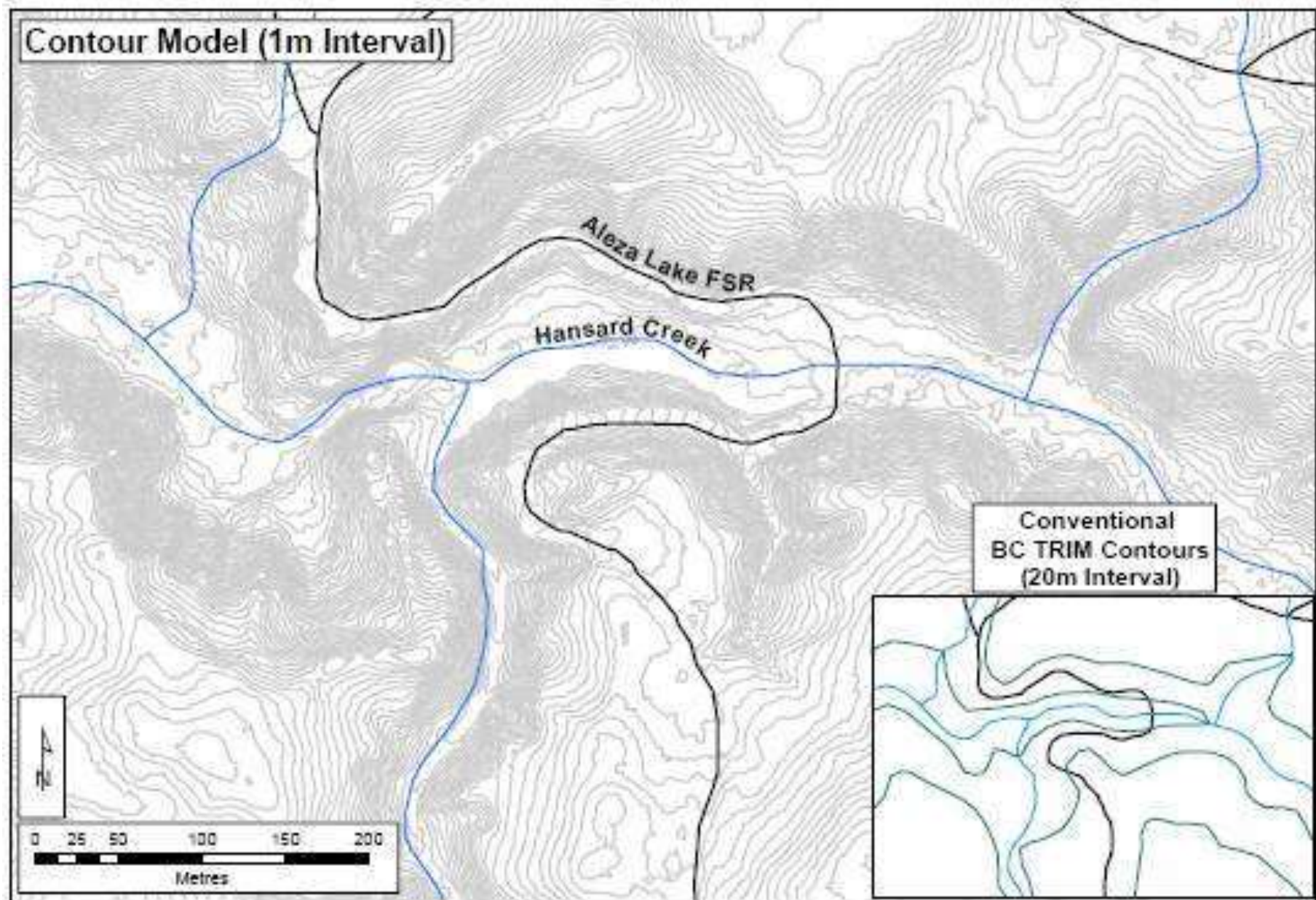
Hansard Creek

Conventional
BC TRIM Contours
(20m Interval)



0 25 50 100 150 200

Metres



Hillshade Model

Aleza Lake FSR

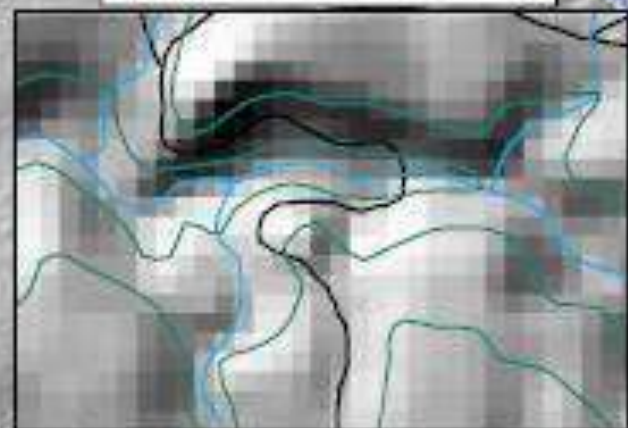
Hansard Creek

Hillshade Model built
from conventional BC DEM

42

0 25 50 100 150 200

Metres



Canopy Height Model

Alora Lake FSR

Hunsford Creek



High : 35

Low : 0

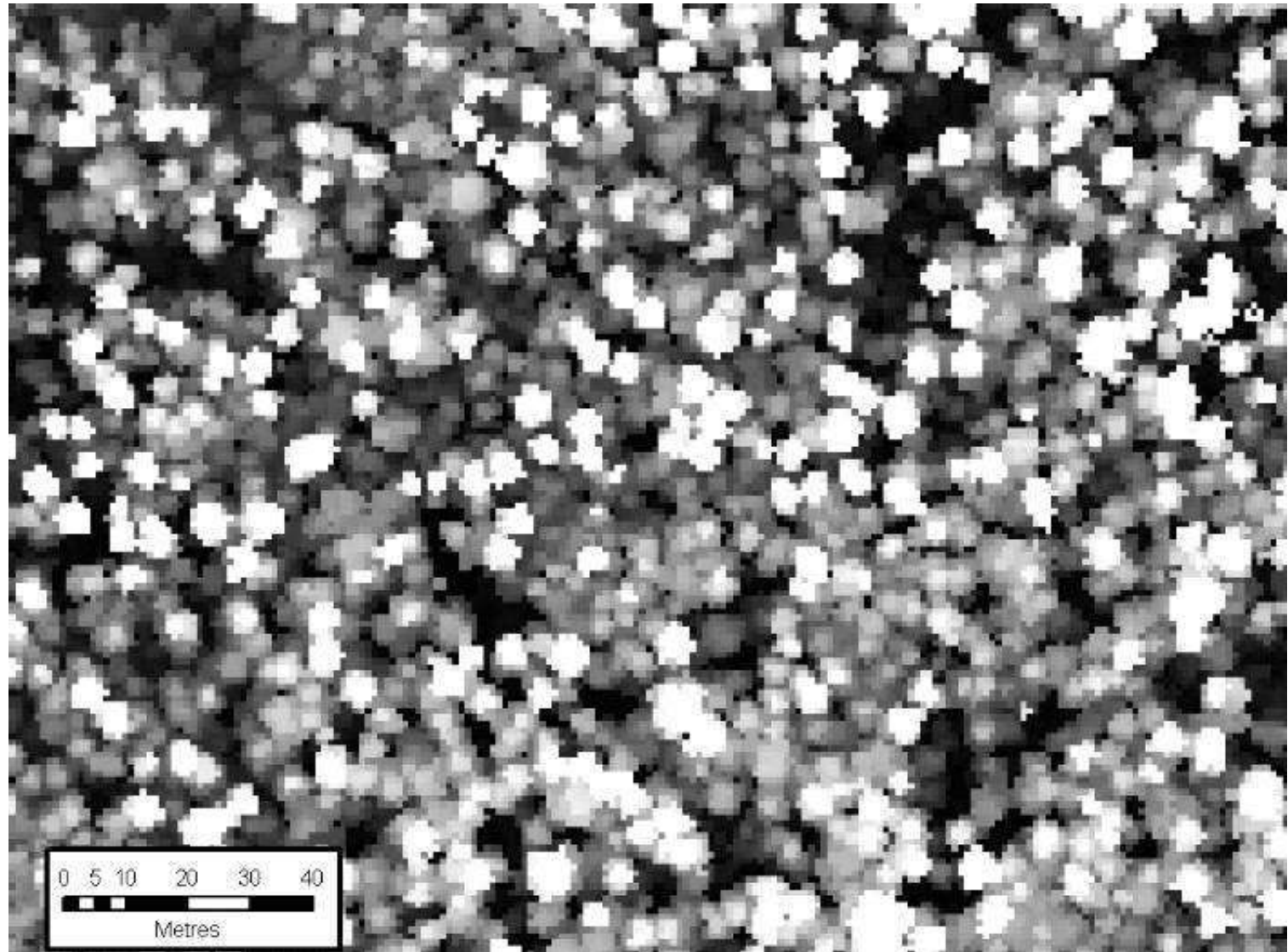


0 25 50 100 150 200

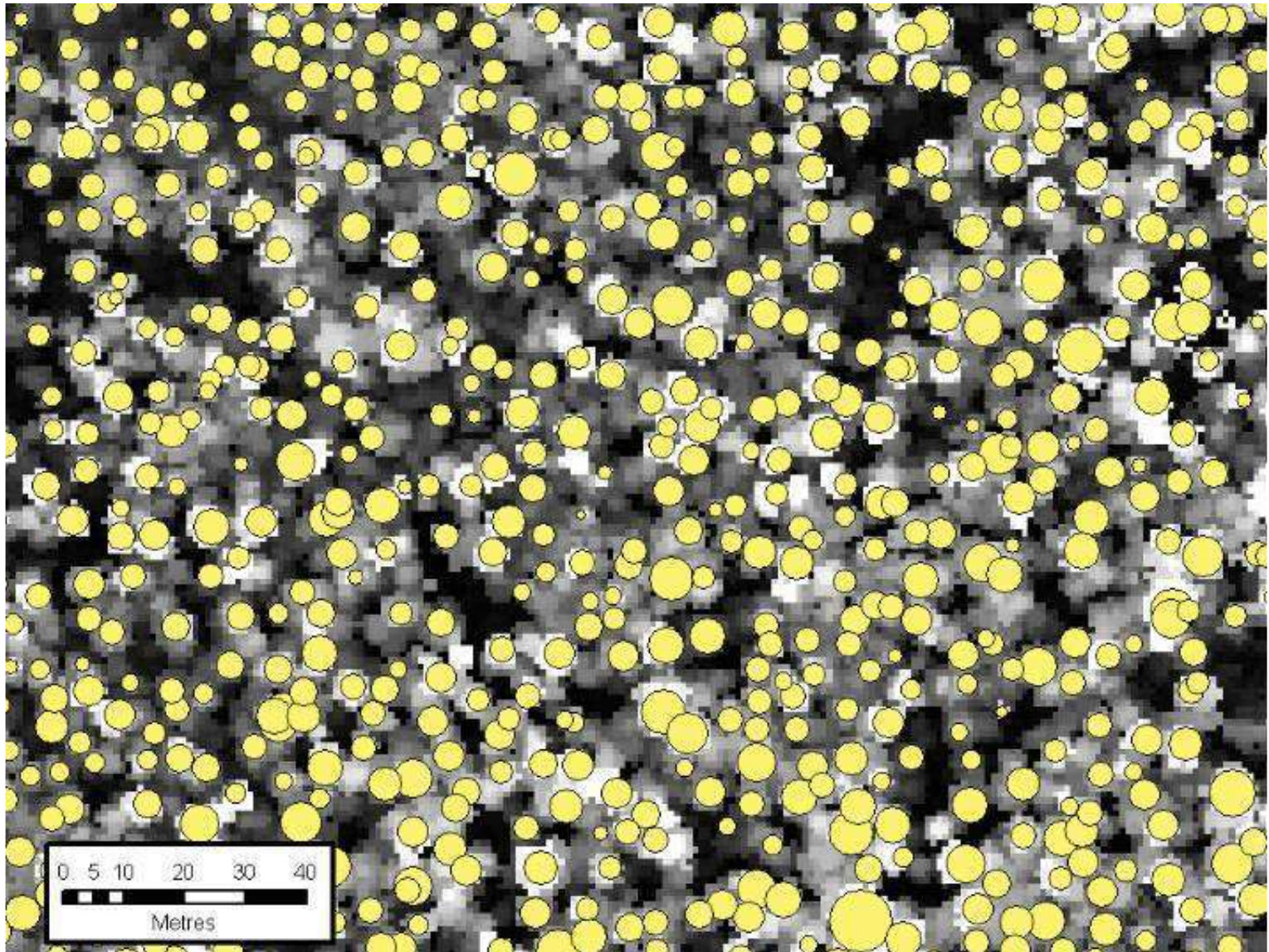
Metres

Tree Stem Maps

Individual tree crowns are discernable from the Canopy Height Model so we developed a tree finding algorithm to identify tree stem locations

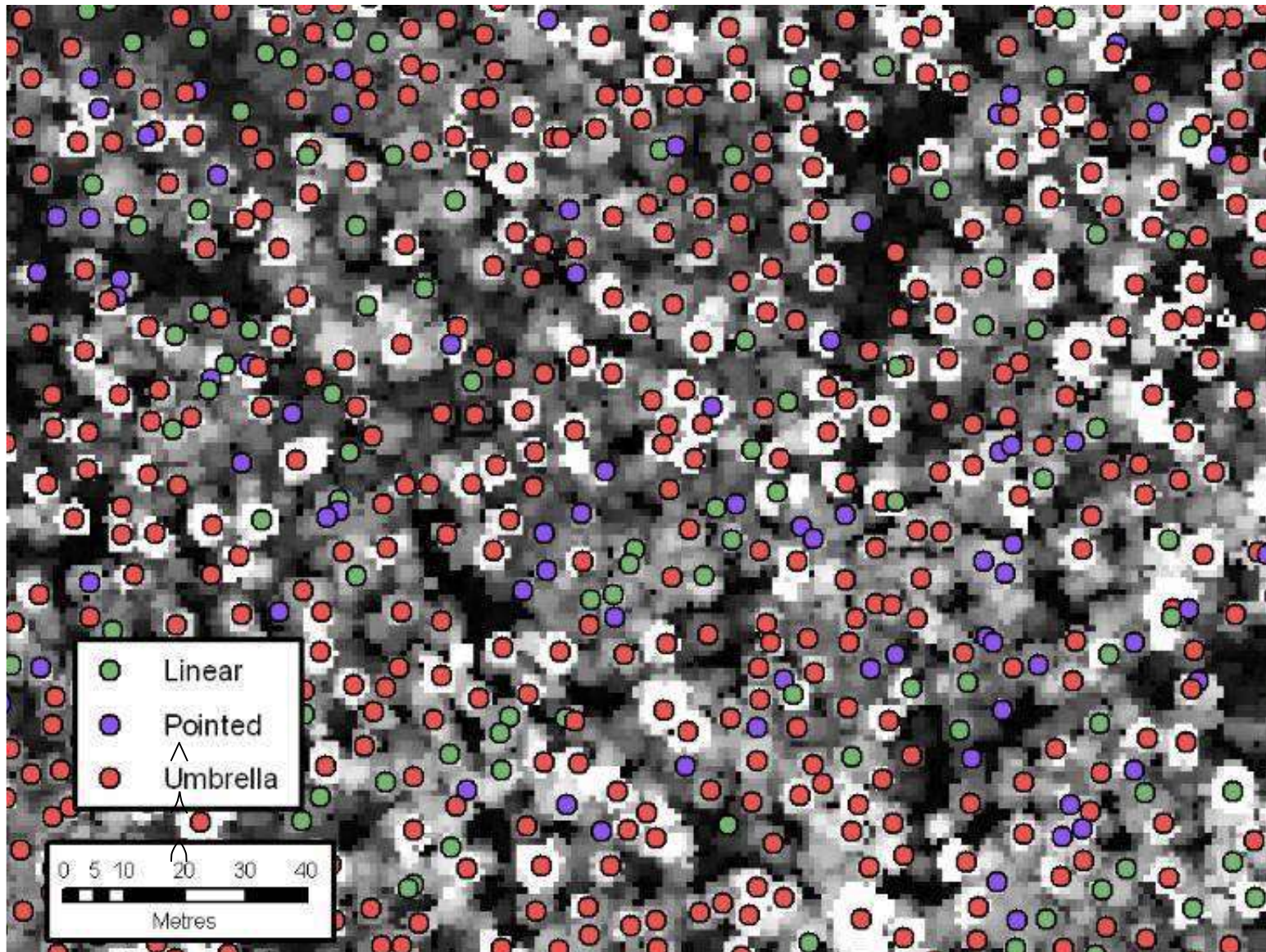


LiDAR Data - tree stems



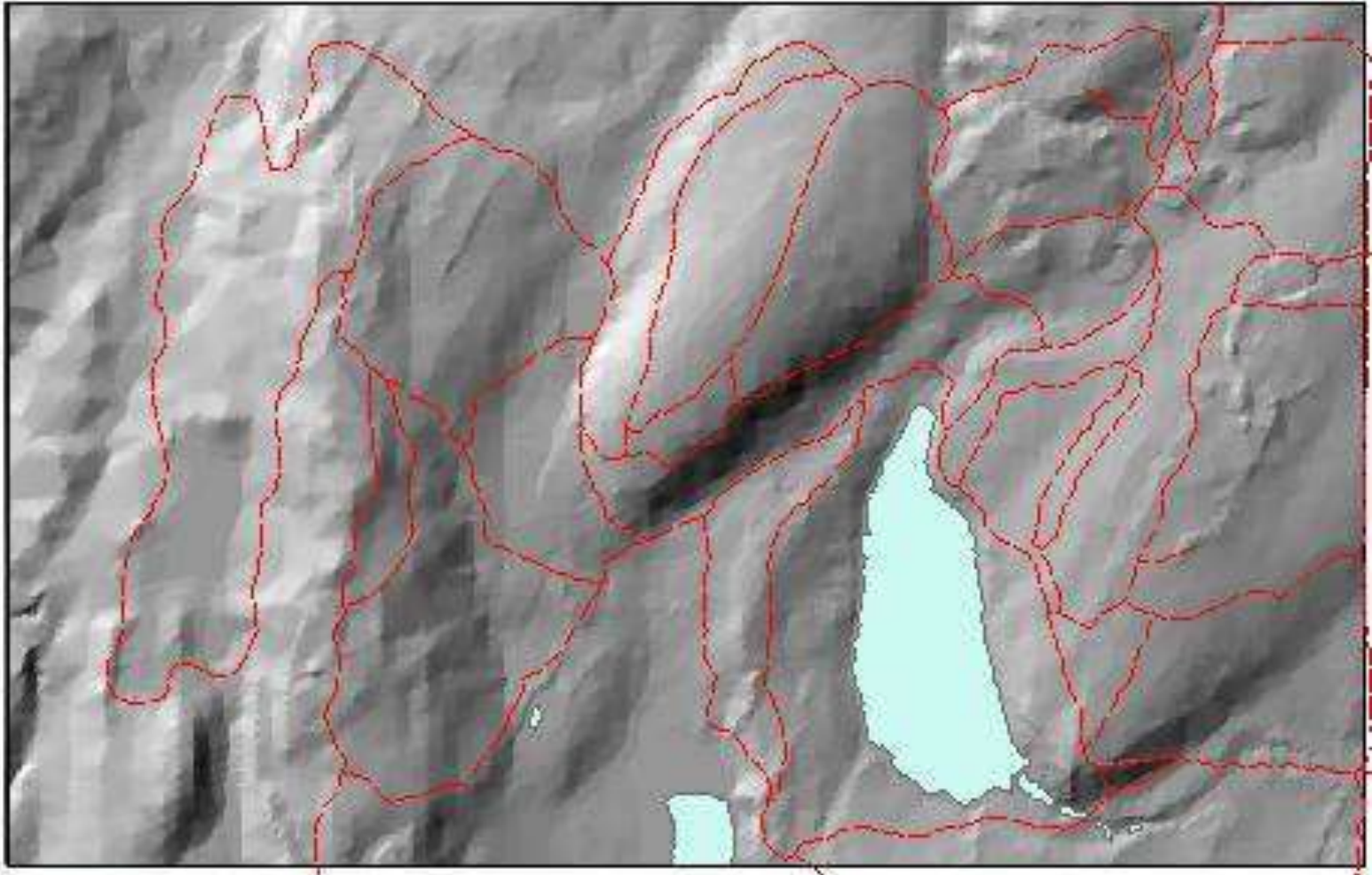
Tree Stems

(displayed by crown shape)

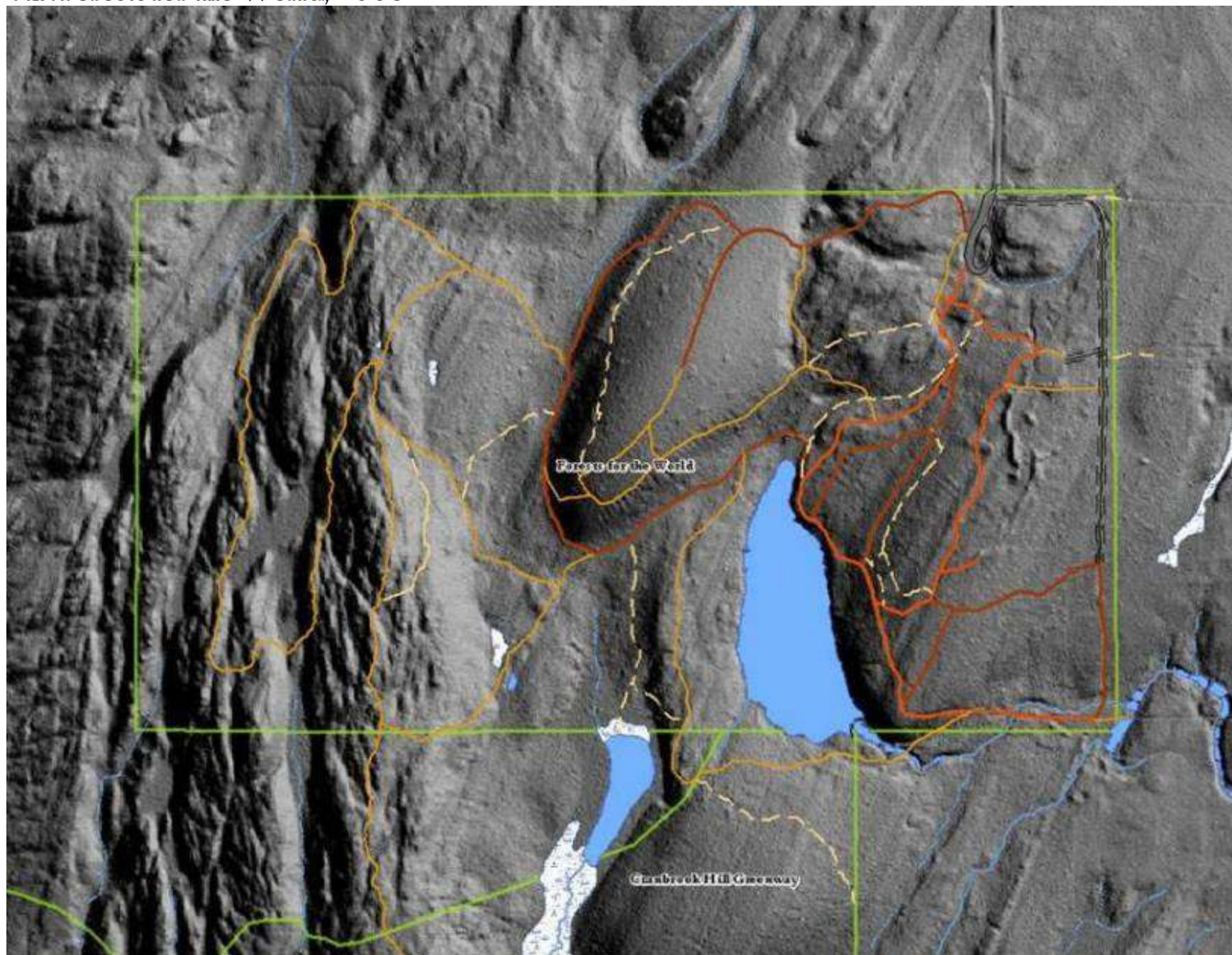


Forests for the World

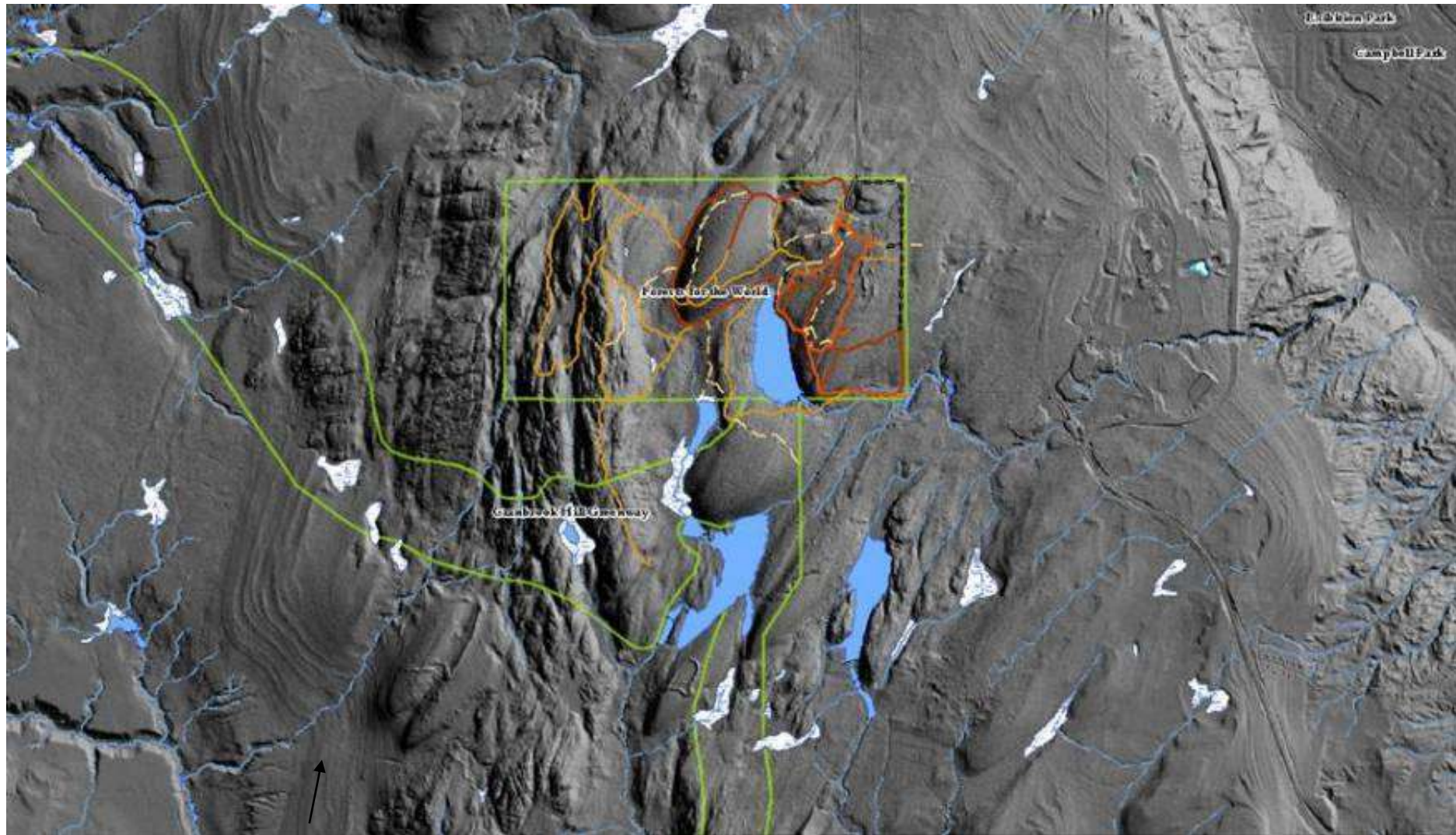
City 1 metre DEM (from 1m contours) 2000s



LiDAR Forests for the World, 2009



UNBC / Cranbrook Hill LiDAR 2009



<https://pgmap.princegeorge.ca/Html5Viewer/index.html?viewer=PGMap>

50cm beach lines

LiDAR Platforms

Airborne since 1970s e.g. [Optech](#) (Ottawa) [NorthWest Geo](#) (Calgary)

And many others ... including UNBC (Brian Menounos)
- LiDAR is mostly airborne, while RADAR is mostly spaceborne

Spaceborne

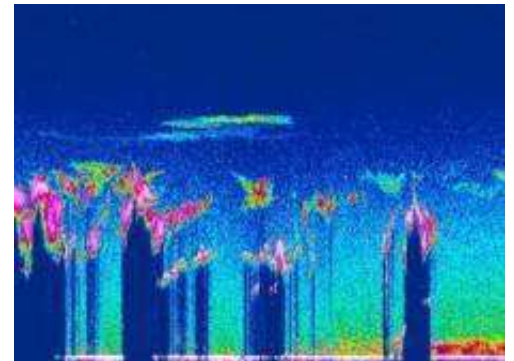
ICESat (Jan 2003-→2009): Geoscience Laser Altimeter System ([GLAS](#)):

66m 'footprint' and 10cm vertical resolution, designed for polar icecaps

ICESat2 (Sept 2018): <https://icesat-2.gsfc.nasa.gov>

CALIPSO:

Cloud-Aerosol Lidar and Infrared Pathfinder Satellite Observation
<https://calipso.cnes.fr/en/CALIPSO/lidar.htm>



LiDAR summary

Present drawbacks: (all reducing with technology increase)

- o The relative high cost of collecting LiDAR
- o High data volume - Terabytes
- o Steep learning curve in research and understanding
(involving utilizing the entire point cloud)

LiDAR summary

Advantages:

- ✓ Very high resolution DEM for many applications
- ✓ All urban areas with flooding potential
- ✓ Multi-layer data for forestry and ecosystems
- ✓ Increasing data supply - some free download e.g. PEI, NS, NB
- ✓ Increasing conference content in GIS/RS/Cartography/Forestry
- ✓ Many online resources e.g. :

USGS: <http://lidar.cr.usgs.gov/knowledge.php>

BC CARMS: <http://carms.geog.uvic.ca/carmslidarnew.html>

Sentinel 2 - LiDAR mashup

Marcel Morin

'Lost Art
Cartography'

Annapolis Valley,
NS



LidarBC - Open LiDAR Data Portal - Web Map (free download)



<https://www.arcgis.com/apps/mapviewer/index.html?webmap=c2967cee749b4bdbac5e7c62935ca167>

Ground based - 'terrestrial' Lidar

Lidar-based rock-fall hazard characterization of cliffs

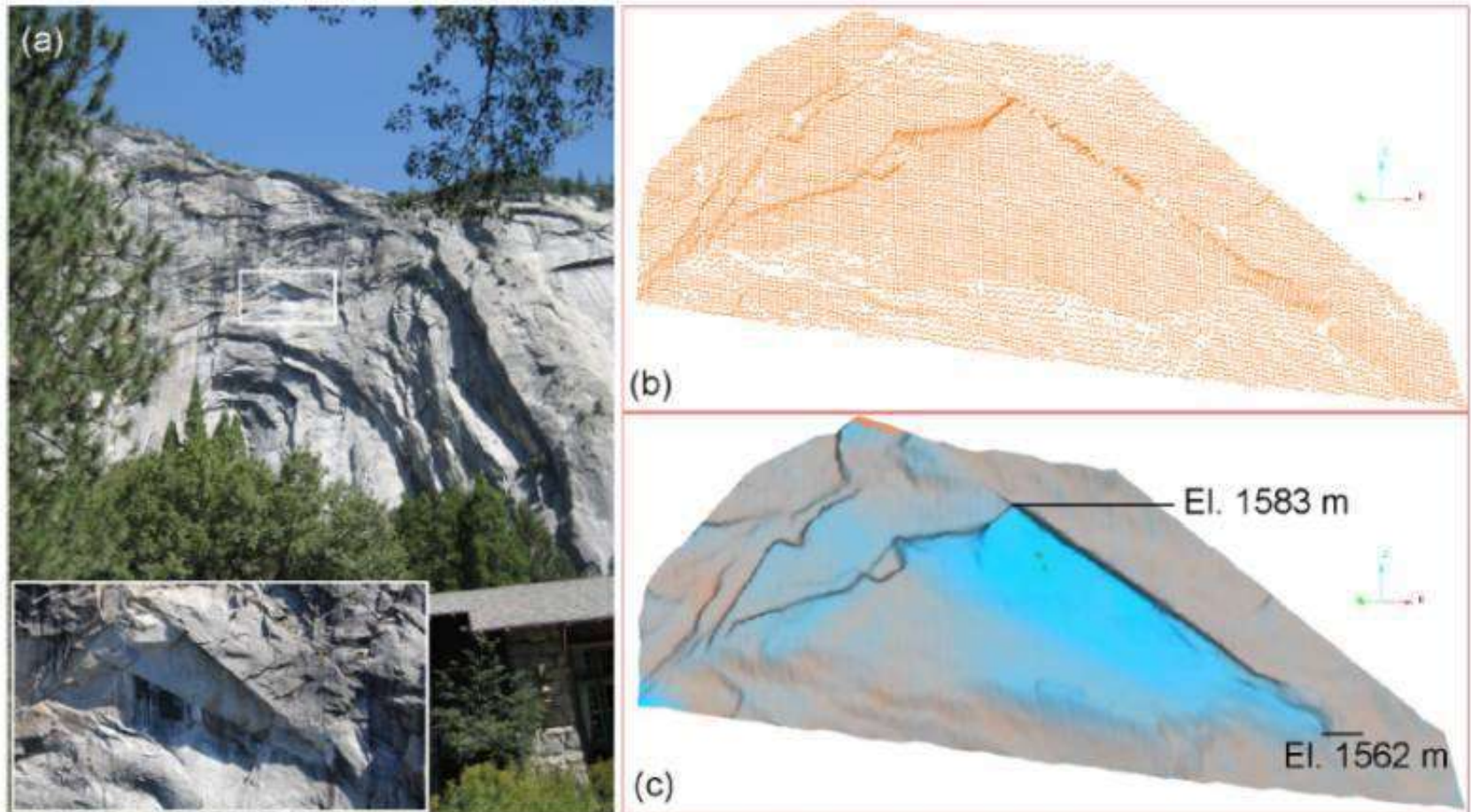


Figure 1. (a) Image of a 2009 rock-fall in Yosemite National Park with (b) point cloud and (c) surface model of the source area. Brightest-blue colored areas of surface model in (c) indicate areas of change following the rock fall.

LiDAR imagery of Gaping Gill - Britain's largest cavern

<http://www.eepublishers.co.za/images/upload/PositionIT-pages%2029-32.pdf>



Fig. 1: Gaping Gill Main Chamber LiDAR survey 2003. Vertex cloud looking west.



Fig. 2: Gaping Gill Main Chamber LiDAR survey 2003. Vertex cloud looking east.

Video: <http://www.youtube.com/watch?v=8HdgliagAds>

Stonehenge: <https://www.wessexarch.co.uk/our-work/explore-stonehenge-landscape>

Heritage building scanning: <http://www.youtube.com/watch?v=4AGk01lms5k>



Conference group photo (RW in red jacket, front centre)



The same Conference group LiDAR scan image