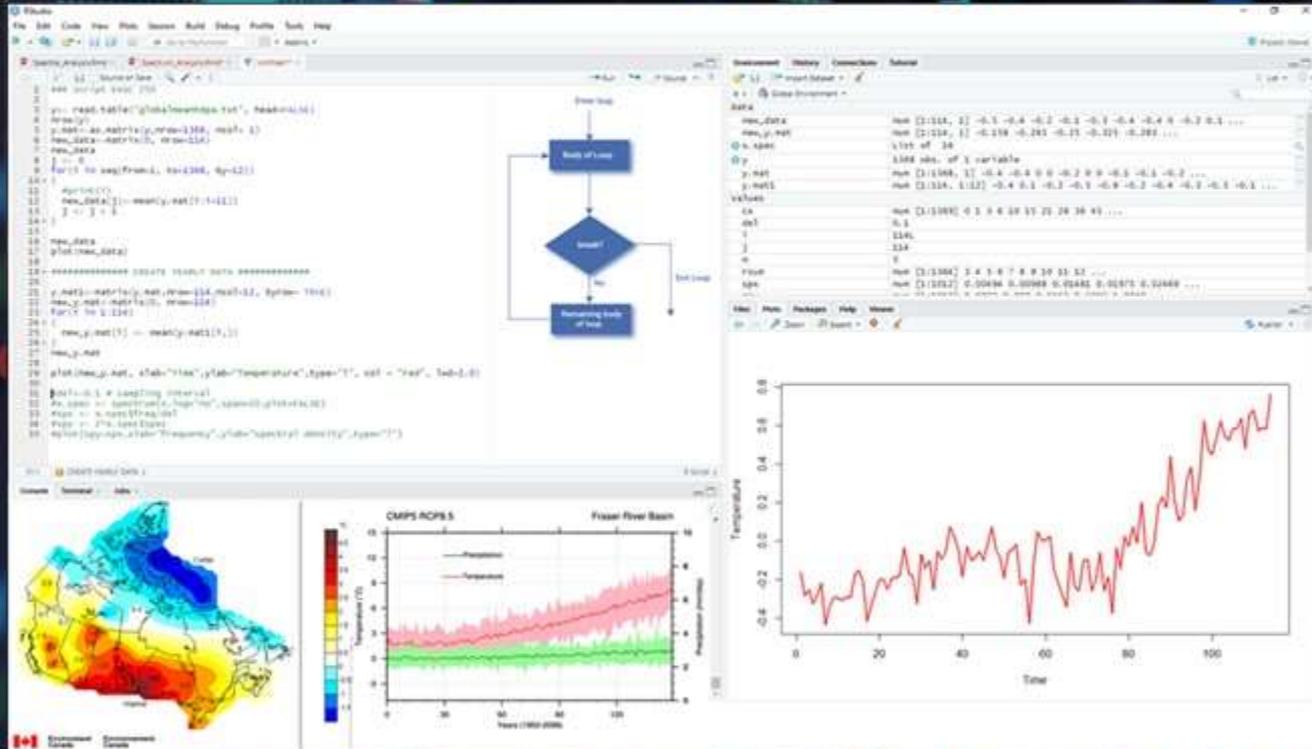


ENSC 250 : Introduction to Environmental Data Analysis

This course consists of lectures and lab components to provide students with theoretical and practical skills in data analysis using R- Programming.

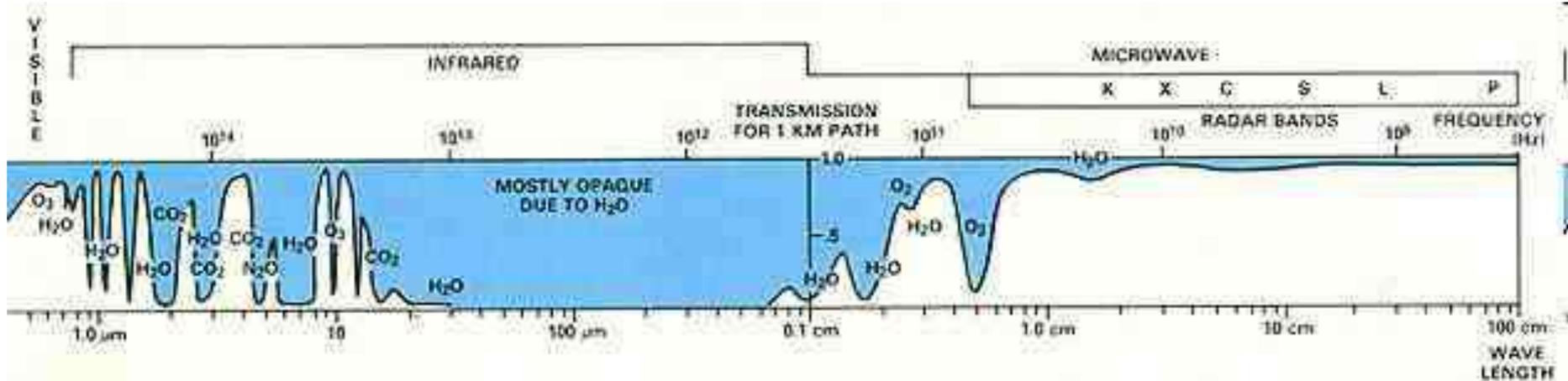
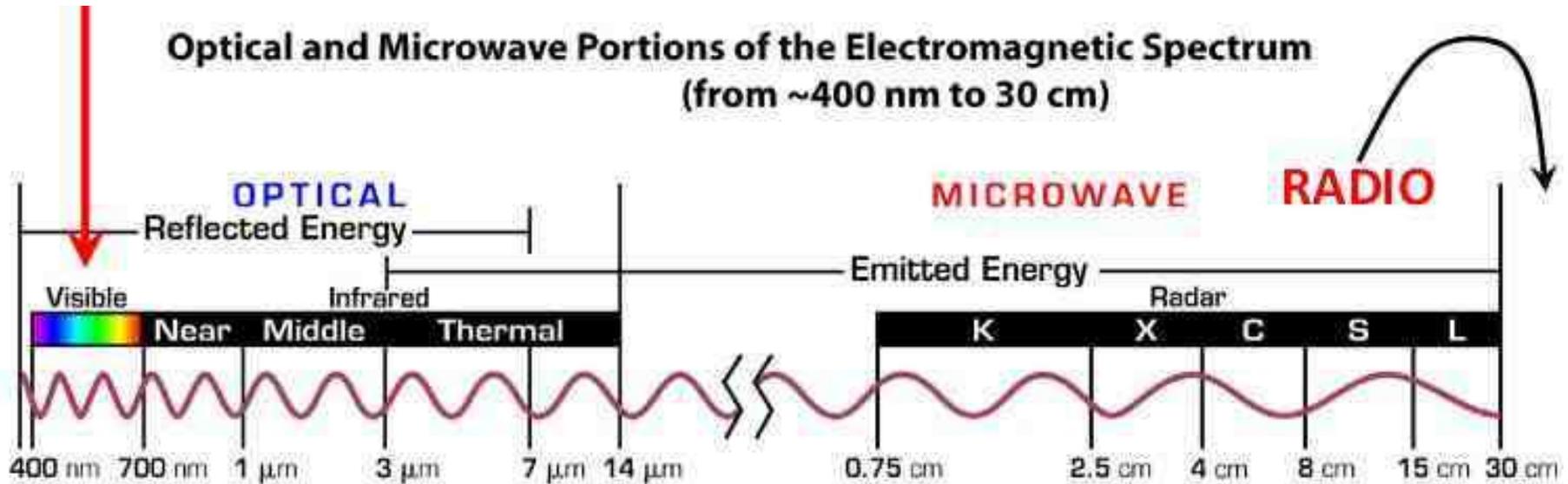


Lectures: Monday 9:30 AM - 10:20 AM, Labs: Monday 11:30 AM - 2:20 PM
Instructors: Dr. Sirajul Islam and Dr. Nikhil Aravindakshan
Email: sirajul.islam@unbc.ca

Winter 2023

Microwave Sensing: 1mm to 1 metre (mostly 1cm-30cm)

Optical and Microwave Portions of the Electromagnetic Spectrum
(from ~400 nm to 30 cm)



These wavelengths beyond the infra-red can 'see through' clouds, light rain, and snow, but there is a low amount - emitted from Earth
... and why we use these wavelengths for communications.
It is used to monitor oceans, snow, sea ice cover and atmospheric ozone



There is limited natural energy in microwave wavelengths
... so pixel size needs to be large

Passive microwave sensing is a continuation of recording thermal energy in the microwave wavelengths. The signal is a **brightness temperature** but there is less terrestrial energy to sense, so a large pixel, ca. 10-25km is needed for radiometric resolution.

$$\text{Radiance} = \text{temperature} \times \text{emissivity}$$

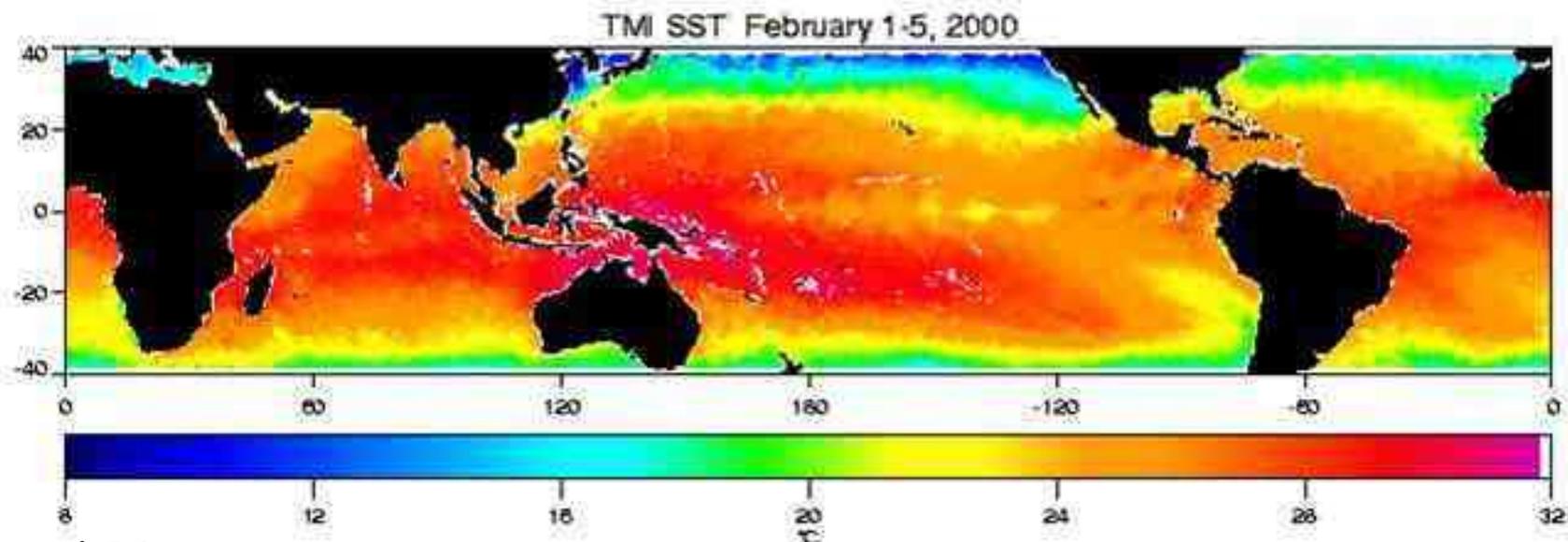
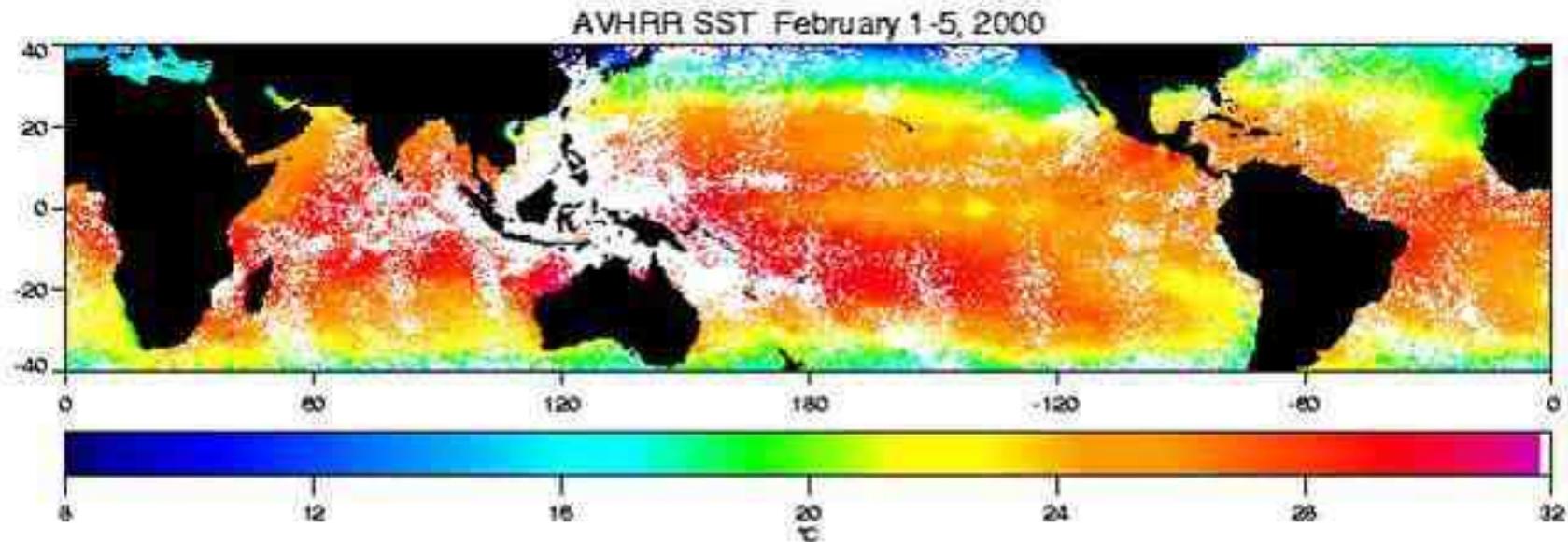
Remote sensing at microwave wavelengths is effective because ...

➤ insignificant atmospheric attenuation for microwave windows

= **unaffected by clouds**

➤ **Microwave sensors: SMMR TMI-TRMM AMSR SSM/I ESMR**

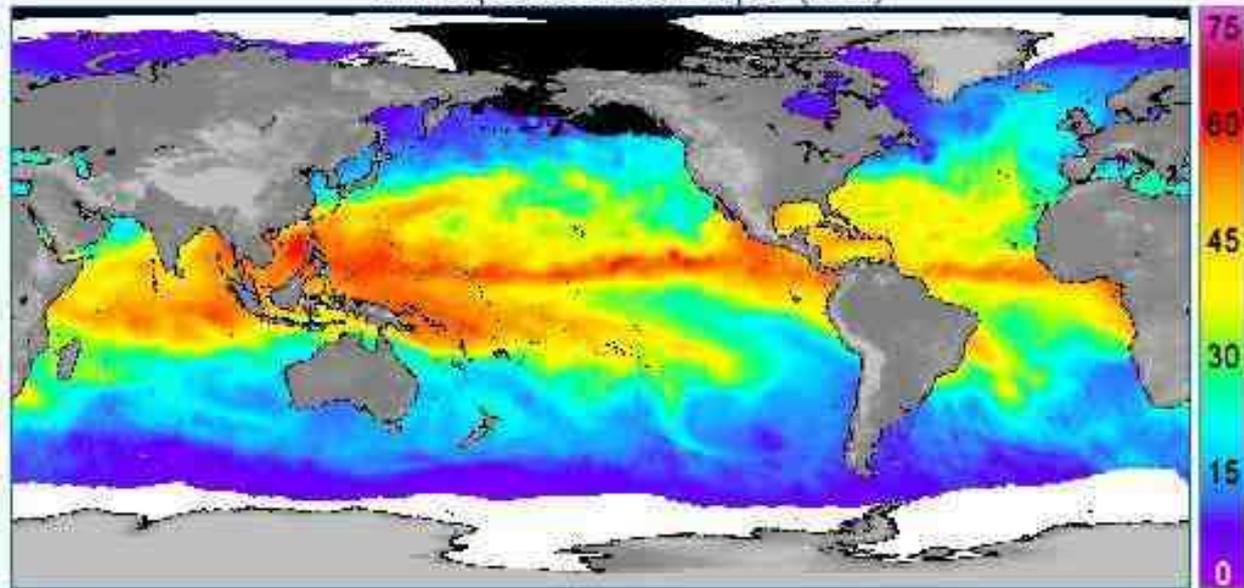
Sea Surface Temperature a. Thermal IR, b. Microwave passive



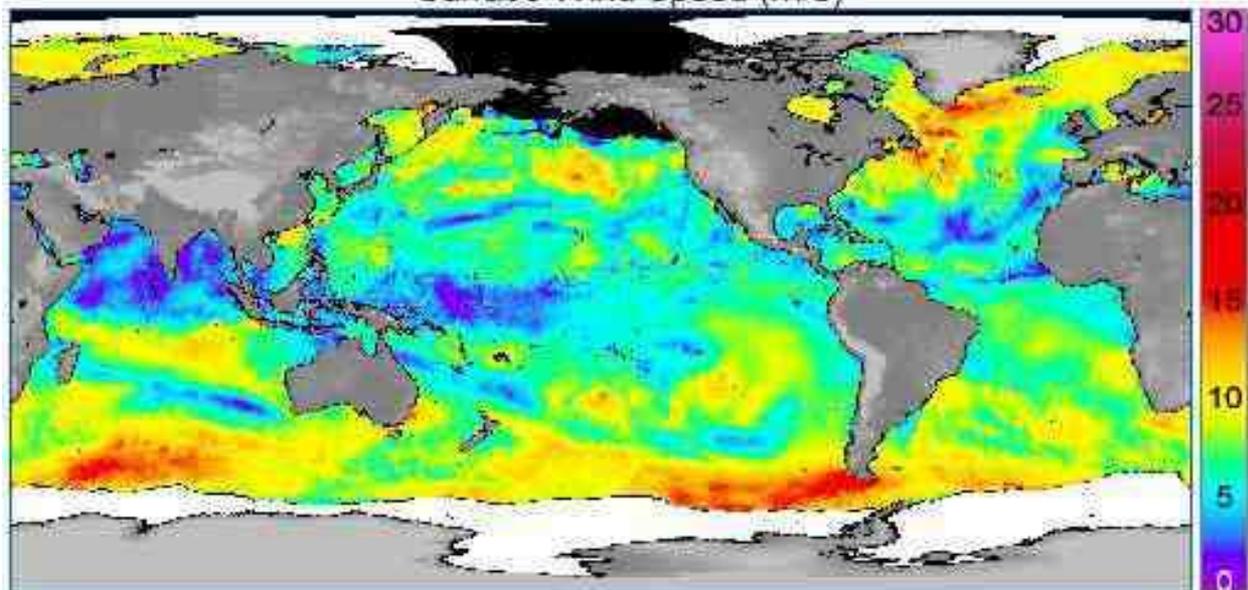
Thermal IR: higher resolution and accuracy; affected by clouds

Microwave: unaffected by clouds, sensitive to precipitation and surface roughness

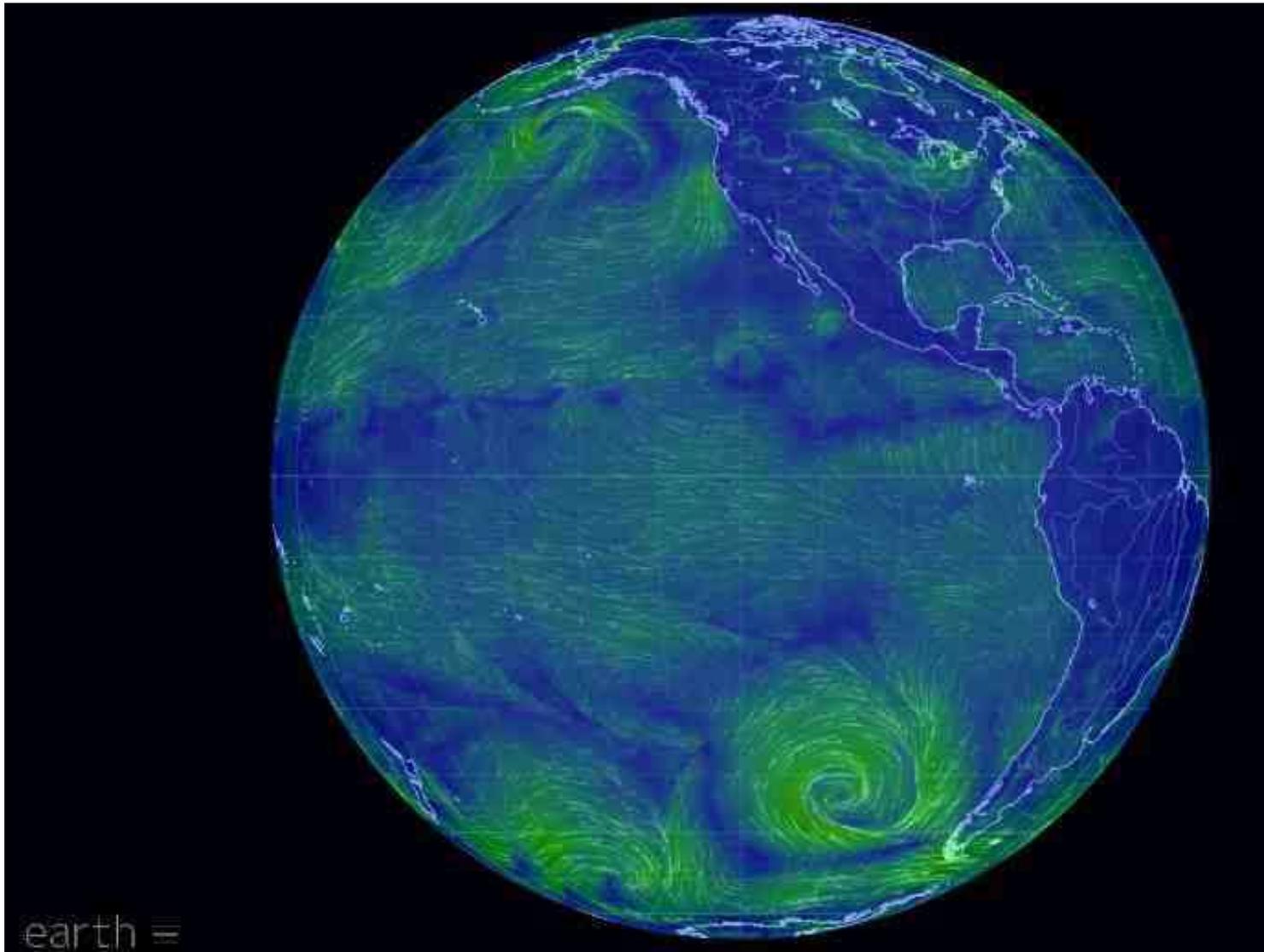
Atmospheric Water Vapor (mm)



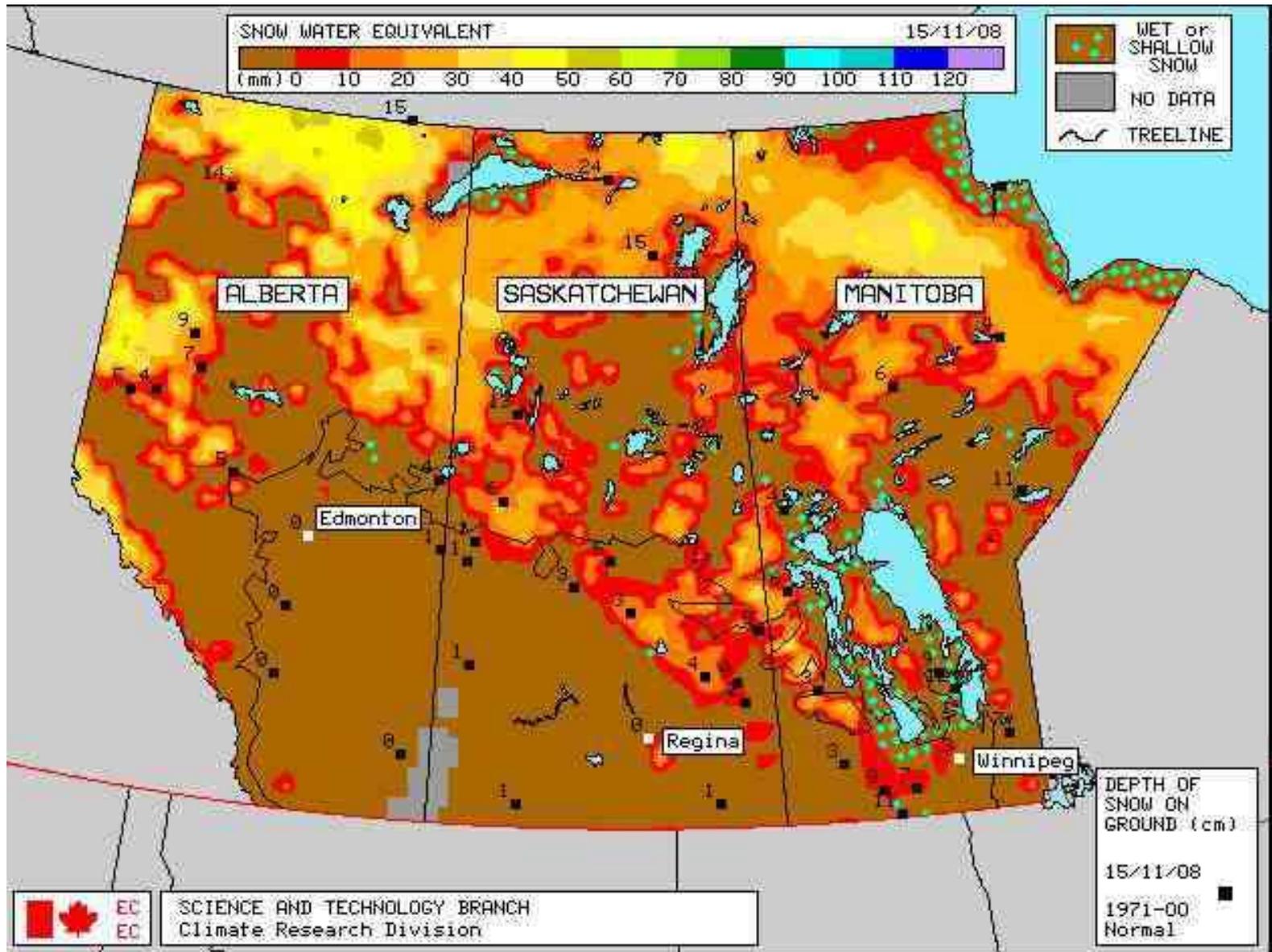
Surface Wind Speed (m/s)



<https://earth.nullschool.net>



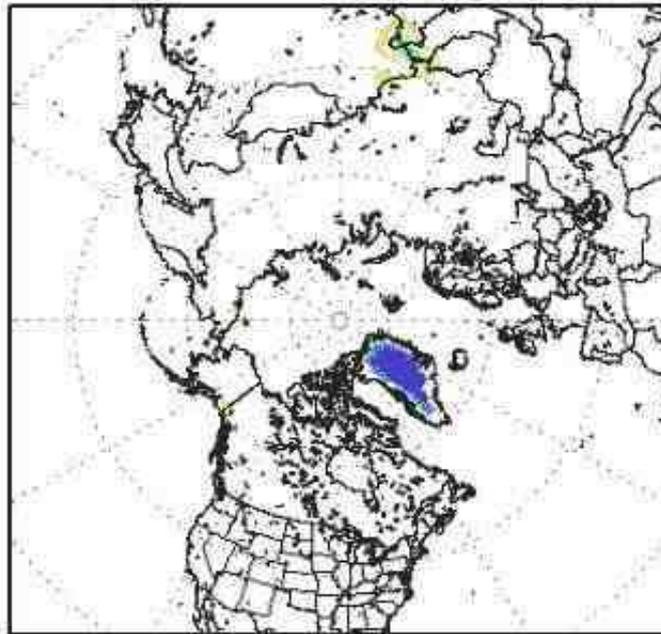
Snow Water Equivalent Map for Canadian Prairies: AMSR-E



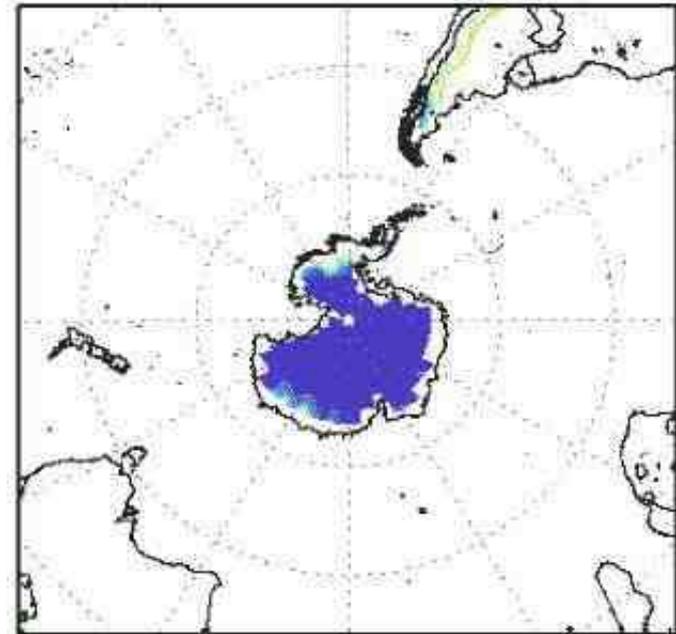
SSM/I Snow Cover for Jul 2005

frequency of occurrence

Northern Hemisphere



Southern Hemisphere



fraction of time and area



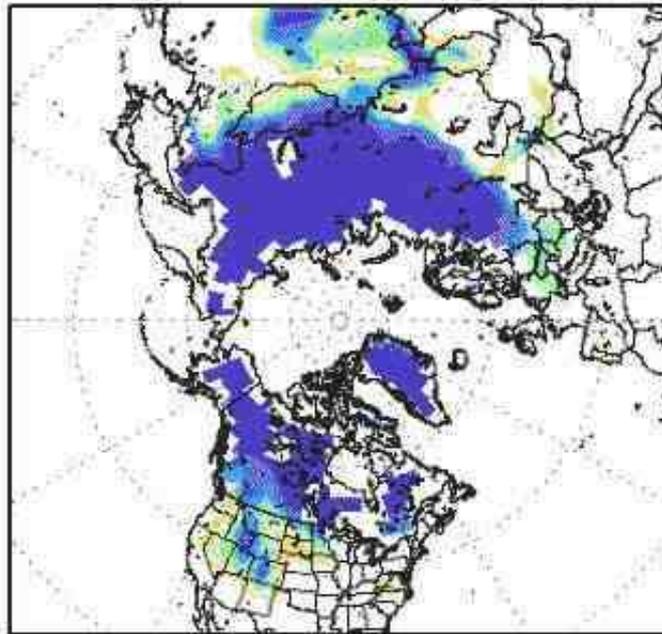
fraction of time and area

3 Aug 2005 NOAA/NESDIS/ORA/SCSB-GICS

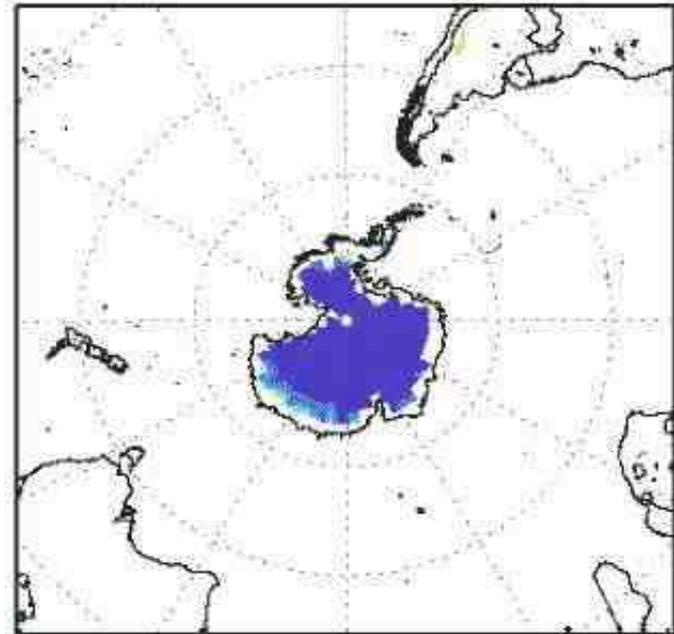
SSM/I Snow Cover for Mar 2005

frequency of occurrence

Northern Hemisphere



Southern Hemisphere

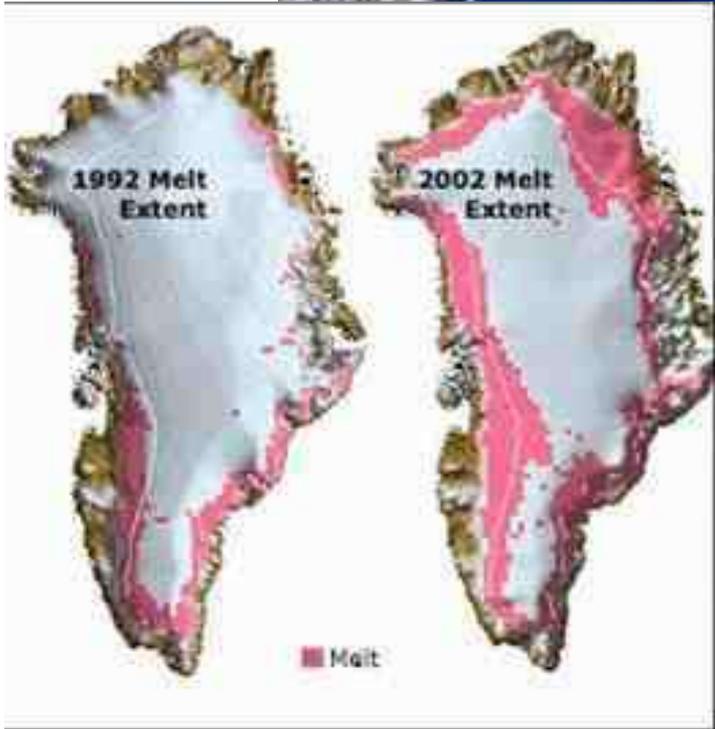
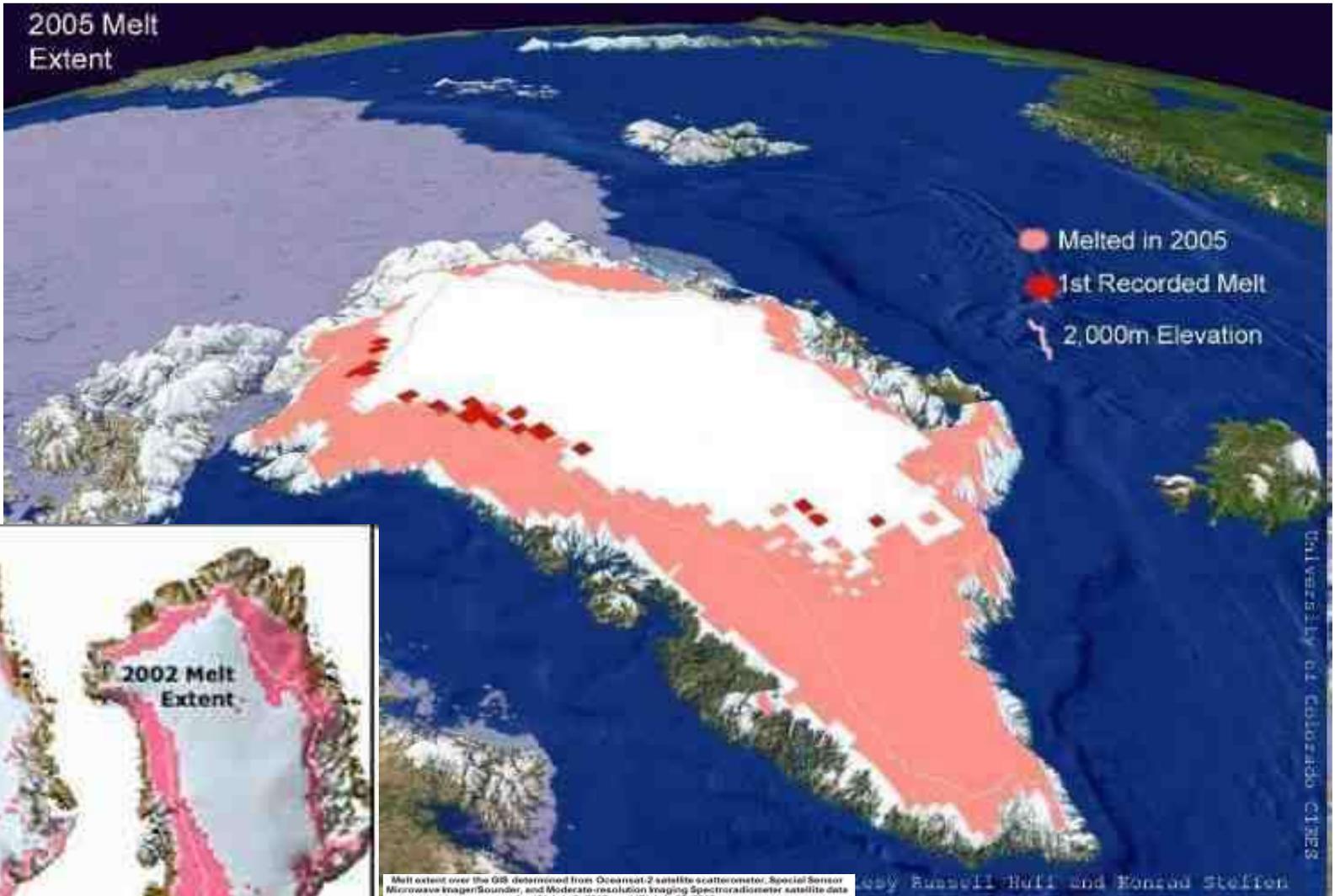


fraction of time and area

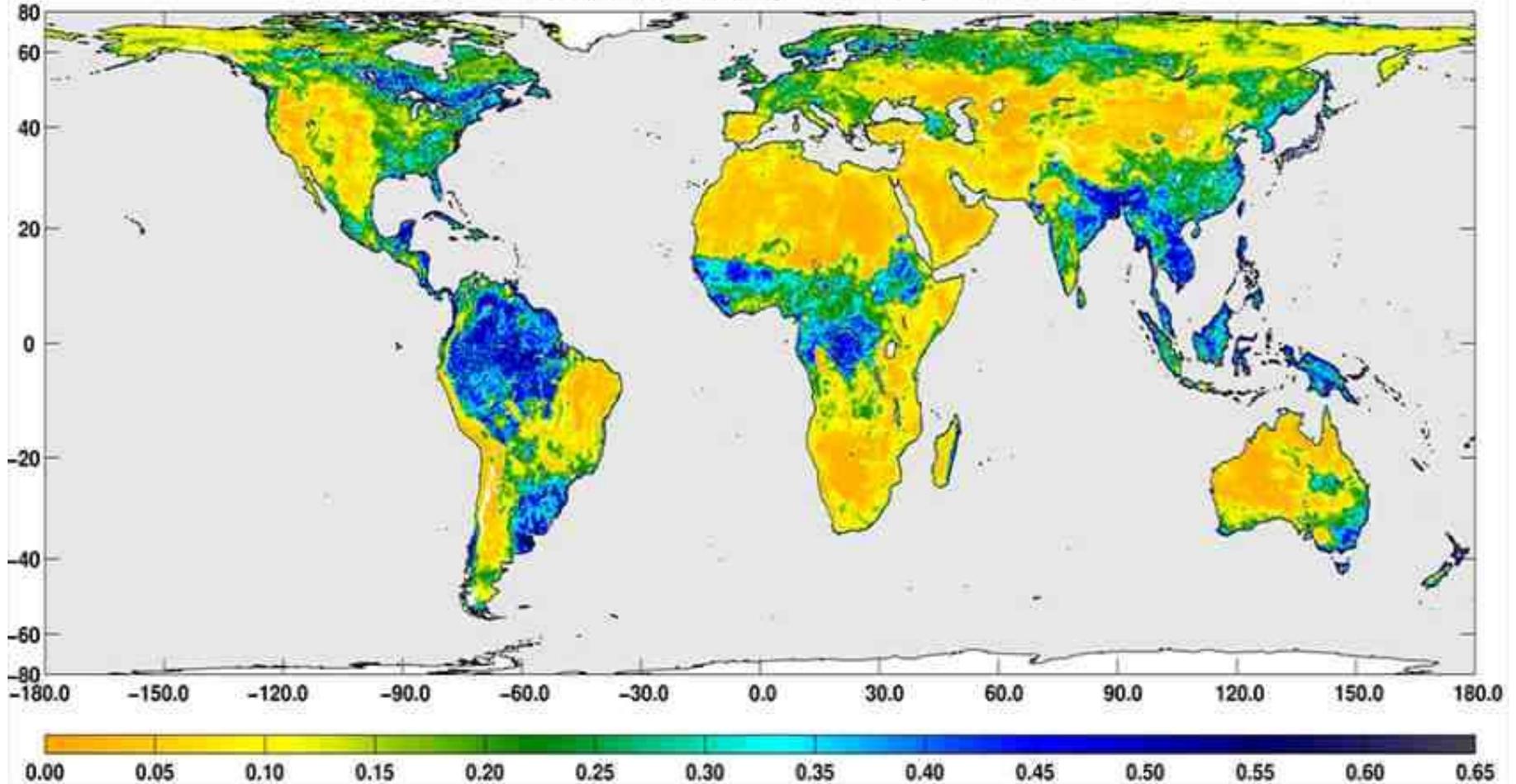


fraction of time and area

Changes in snowmelt, Greenland

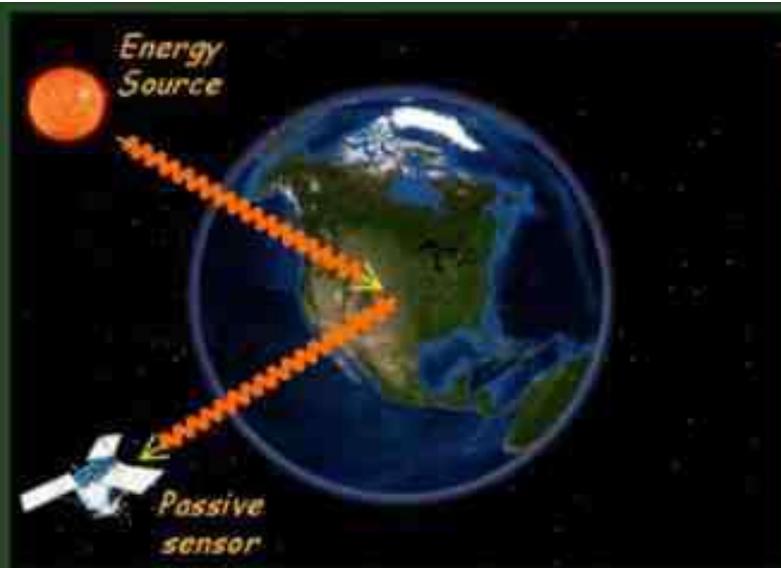


SMAP L2_SM_P (VPOL) (August 25 - August 27, 2015)



A three-day composite global map of surface soil moisture as retrieved from SMAP's radiometer instrument between Aug. 25-27, 2015. Wetter areas are blue and drier areas are yellow. *Image Credit: NASA: Soil Moisture Active Passive (SMAP)*

So far, we have mostly looked at 'passive' remote sensing systems.
As **passive** microwave sensors deal with very low resolution, more applications in these wavelengths use **active** sensors:

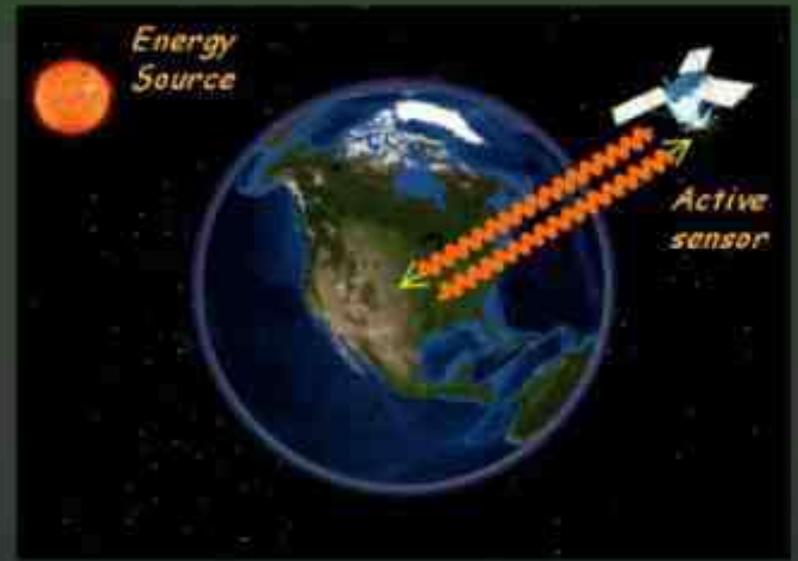


Passive sensors:

- Rely on the sun as an energy source
- Detect only naturally occurring energy

Active sensors:

- Act as their own energy source
- Detect backscattered energy

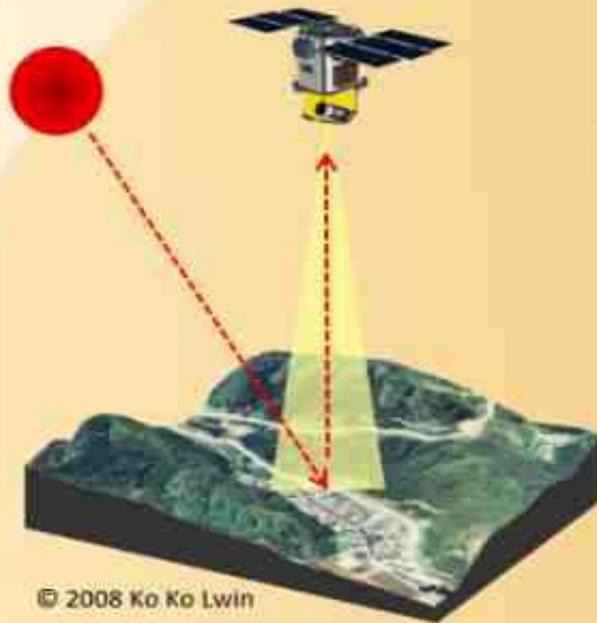


1.4 Types of Remote Sensing

Passive Remote Sensing and Active Remote Sensing

Passive Remote Sensing

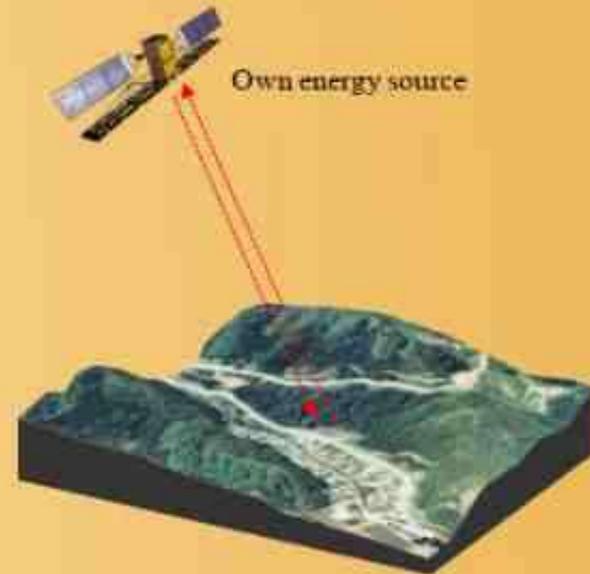
Remote sensing of energy naturally reflected or radiated from the terrain.



© 2008 Ko Ko Lwin

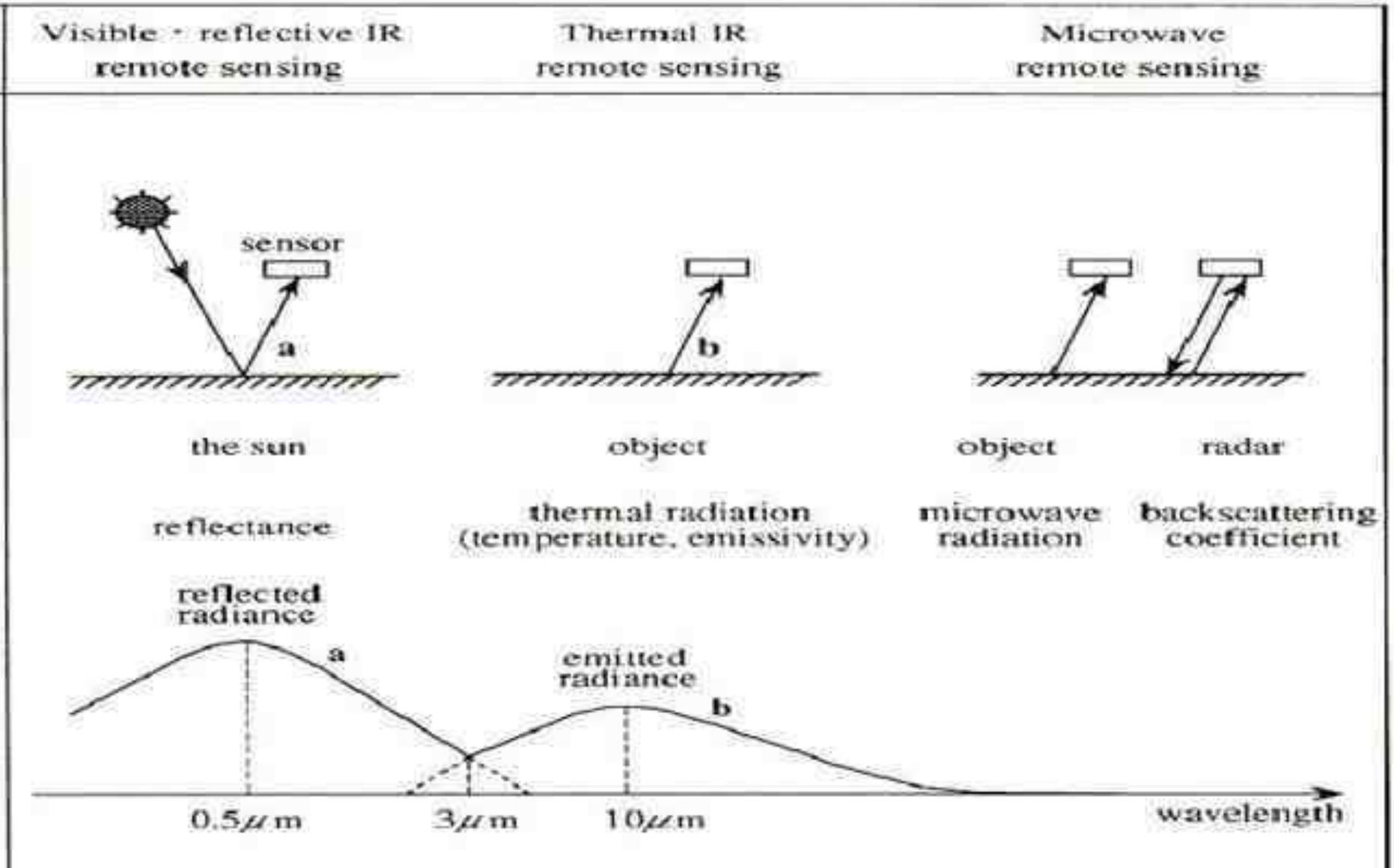
Active Remote Sensing

Remote sensing methods that provide their own source of electromagnetic radiation to illuminate the terrain. Radar is one example.



RADAR is the most commonly used space-based active sensing system.

It is an acronym for **RADio Detection And Ranging**.

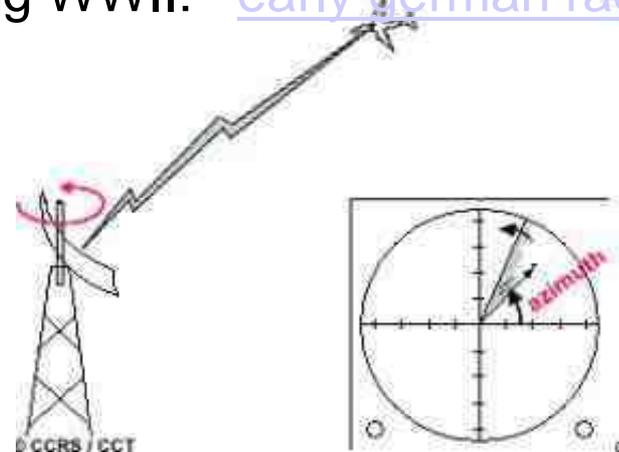
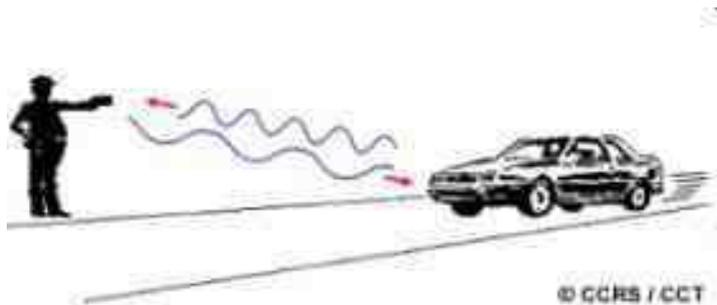


Radar systems were first implemented in the 1930s to detect ships on water and to measure their proximity, and later airplanes.

Imaging radar systems have been in use since the 1950s.

The original technology was developed during WWII: [early german radar](#).

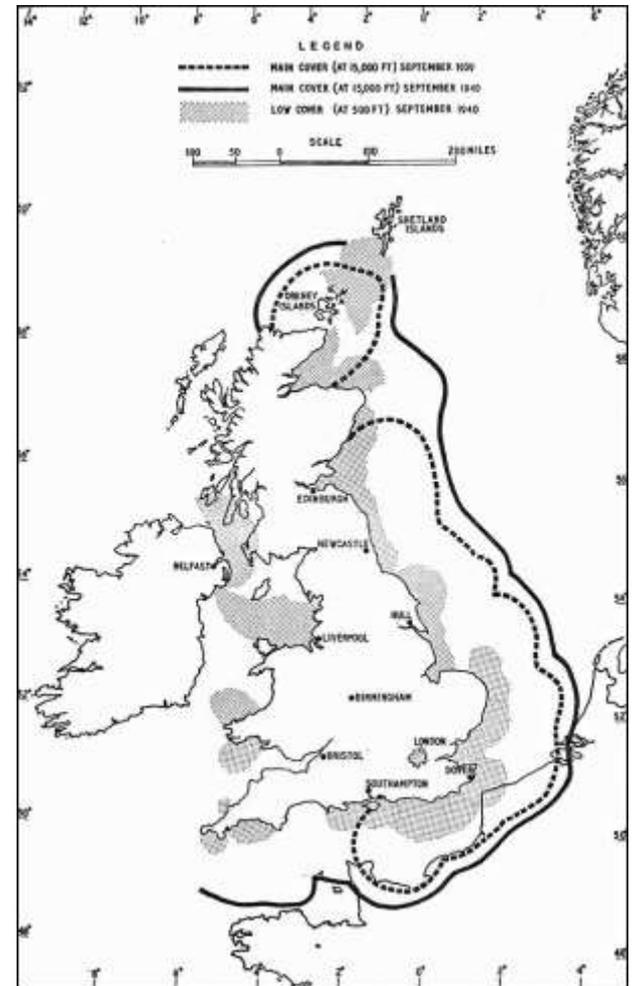
Non-imaging radar



Plan position indicators (PPI) produce a type of image. These radars use a circular display screen to indicate objects surrounding the rotating antenna. They are commonly used for weather monitoring, air traffic control and navigational systems.

Invention/development of RADAR: Robert Watson-Watt (1935)

Use of transmitting Radio waves to detect
enemy aircraft in World War II



In 1956, he moved to Canada where Watson-Watt reportedly was pulled over for speeding by a radar gun-toting policeman (his own invention).

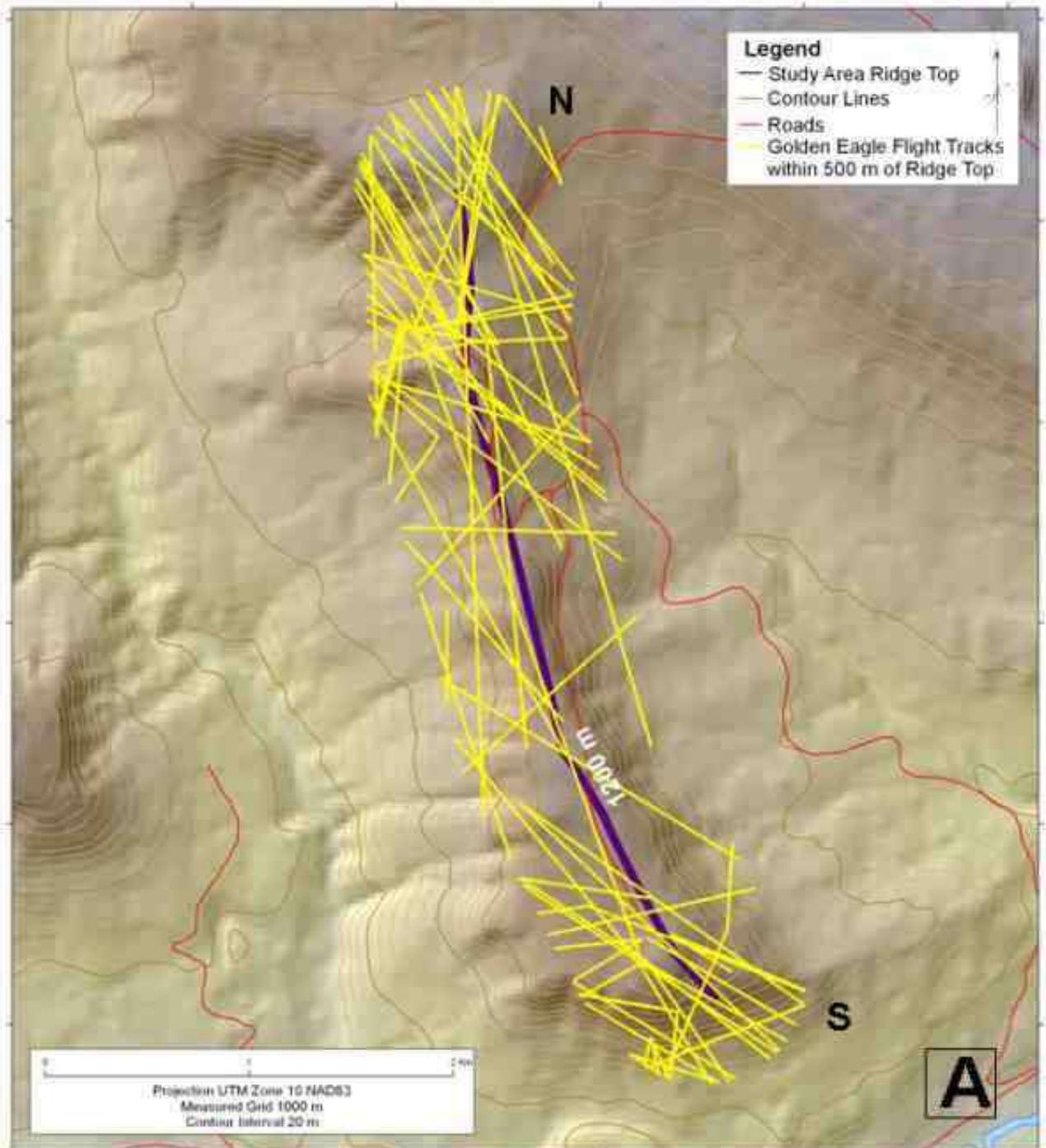
Massachusetts-based Raytheon in 1947 named the original microwave the “**Radarange**” because it cooked food using the same radio-wave-producing magnetron tubes that the company manufactured for use in military radar.

Raytheon credits the discovery of microwave cooking to an engineer named Percy L. Spencer. One day in 1945, Spencer was walking through a radar test room with a chocolate bar in his pocket, and the candy began to melt.



**UNBC bird
study using
RADAR - near
Chetwynd**
(Dr. Ken Otter)

Dokie Ridge
Site of wind
turbines

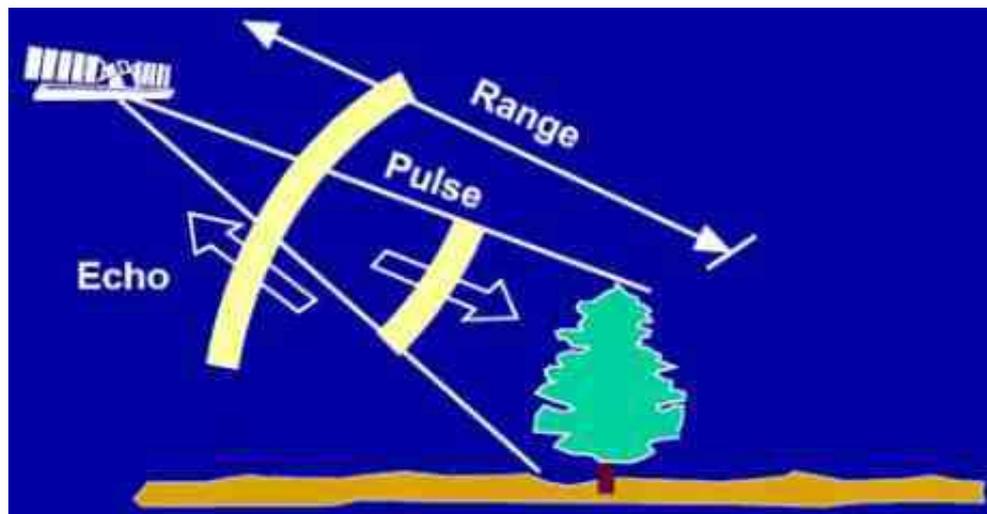


Most early imaging RADAR was airborne, e.g. Calgary Intera technologies: Panama

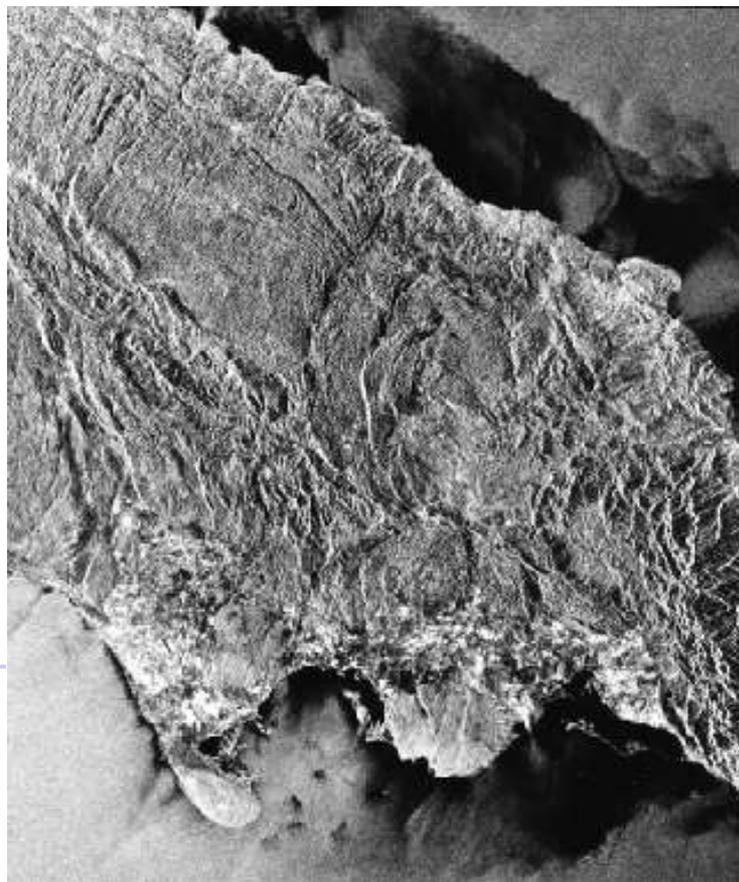


Tropical areas are often cloud-covered and poorly mapped without RADAR

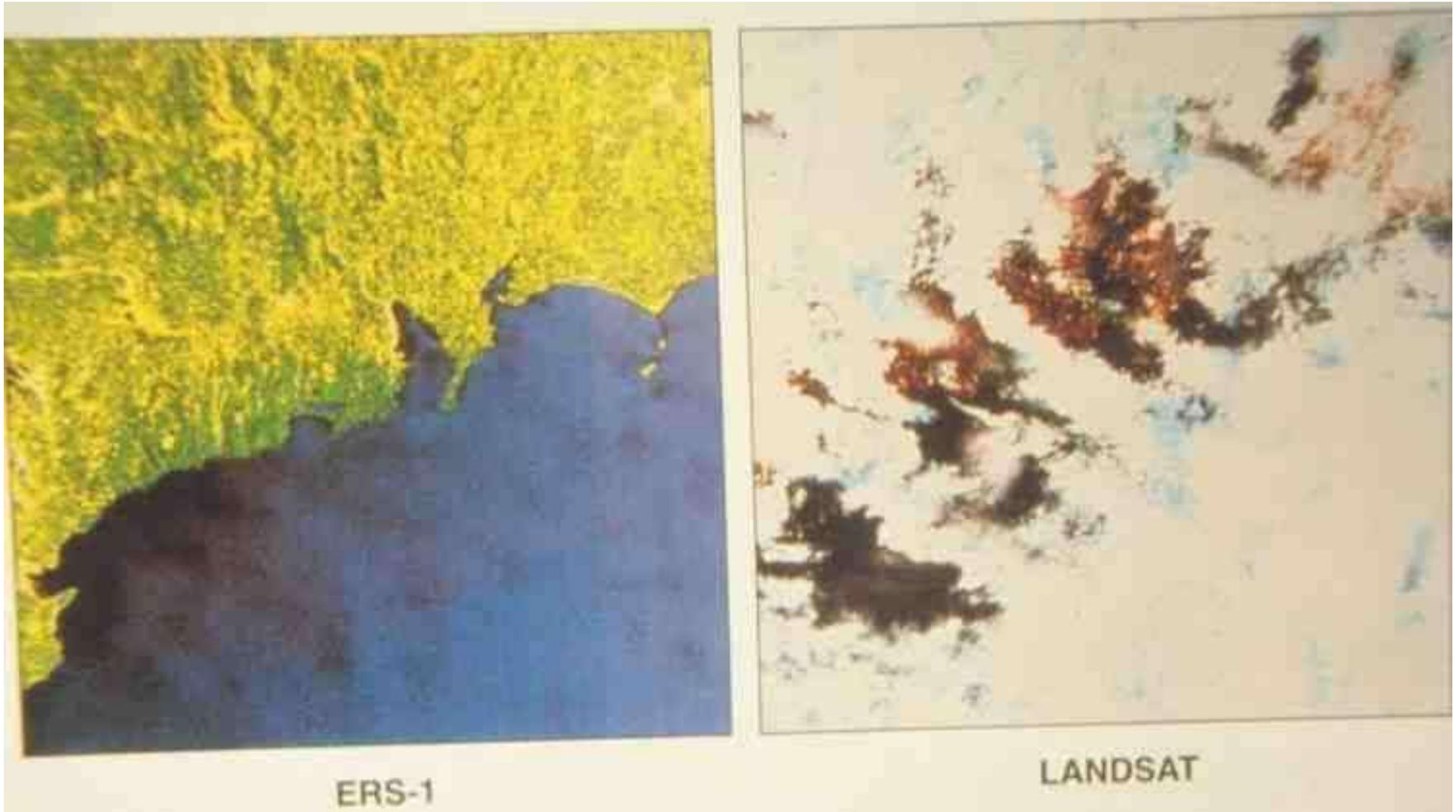
The RADAR device transmits energy, a portion of which is returned to the sensor. The time taken gives the distance (location) of the target, the strength of the return describes its characteristics.



Satellite imaging radar started with [SEASAT](#) launched in 1978.



As it is not affected by darkness or weather, it is especially useful in arctic regions for mapping ice; and tropical areas, which are consistently cloud covered as well as other areas often cloud covered, both temperate and tropical.



Ireland, 1991: Radar and Visible image

In RADAR microwave, it is usual to refer to bands by frequency in Gigahertz (waves/second) as in wavelength

Frequency is inversely proportional to wavelengths

e.g. 1cm to 10cm = 30 to 3 GHz

P = penetration

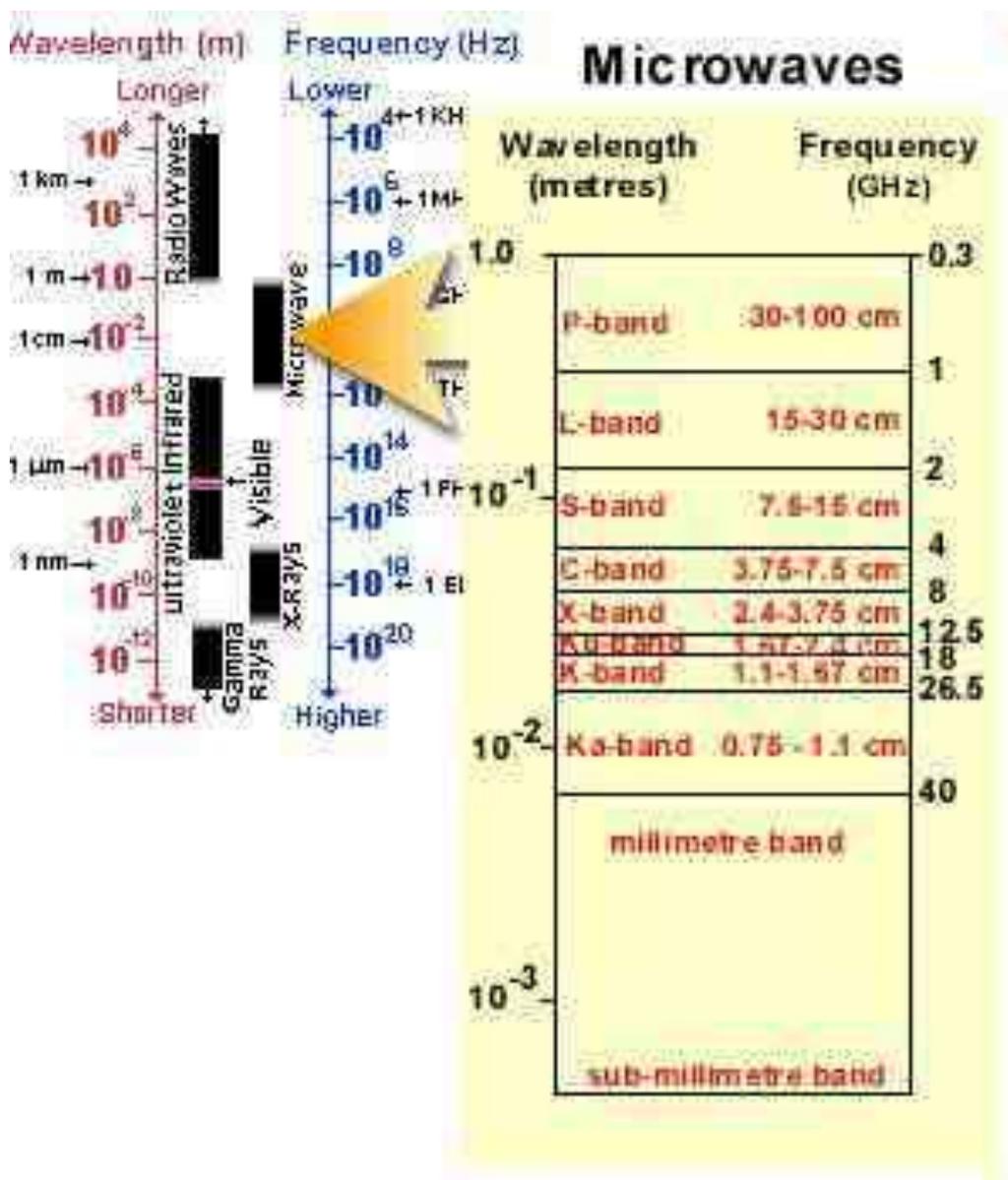
L=Longwave

S= shortwave

C=compromise

X= Cross(hairs) as in WWII

K = Kurtz (short in german)





(a) C-band



(b) L-band



(c) P-band

Fig. 3. Comparison between HH-polarized SAR images acquired with the *JPL-AIRSAR* in three bands (C, L and P), on the same harvested area near Whitecourt, Alberta, in May 1991.

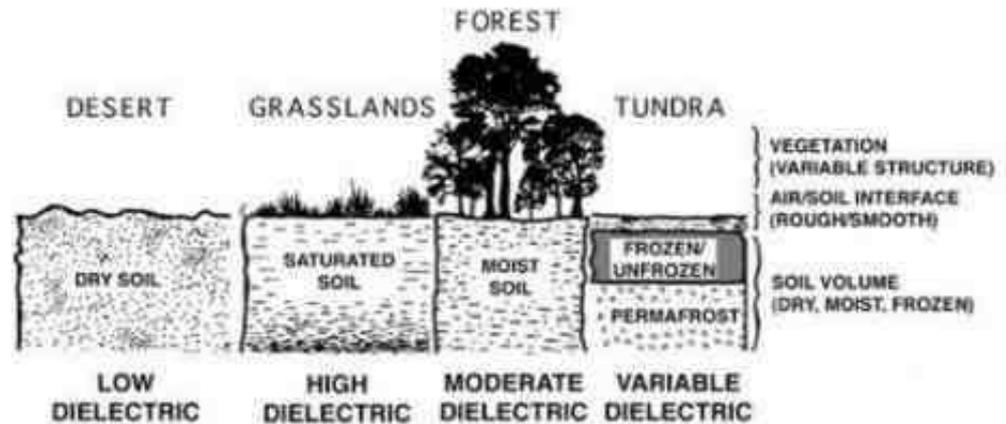
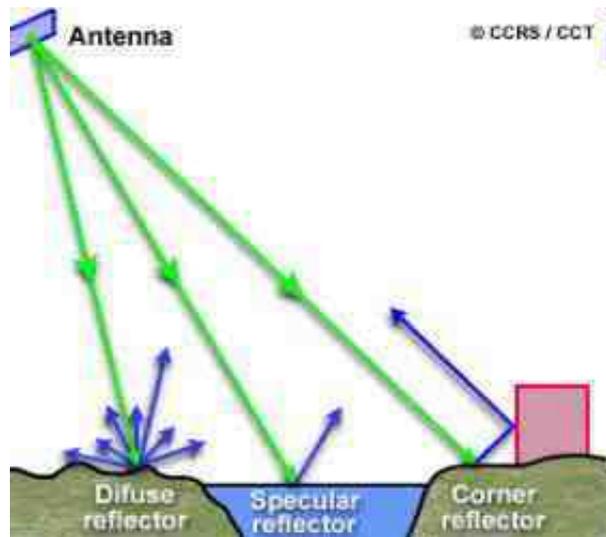
multiband - CPL
(multifrequency) image
of San Francisco



Radar image interpretation: Digital Numbers

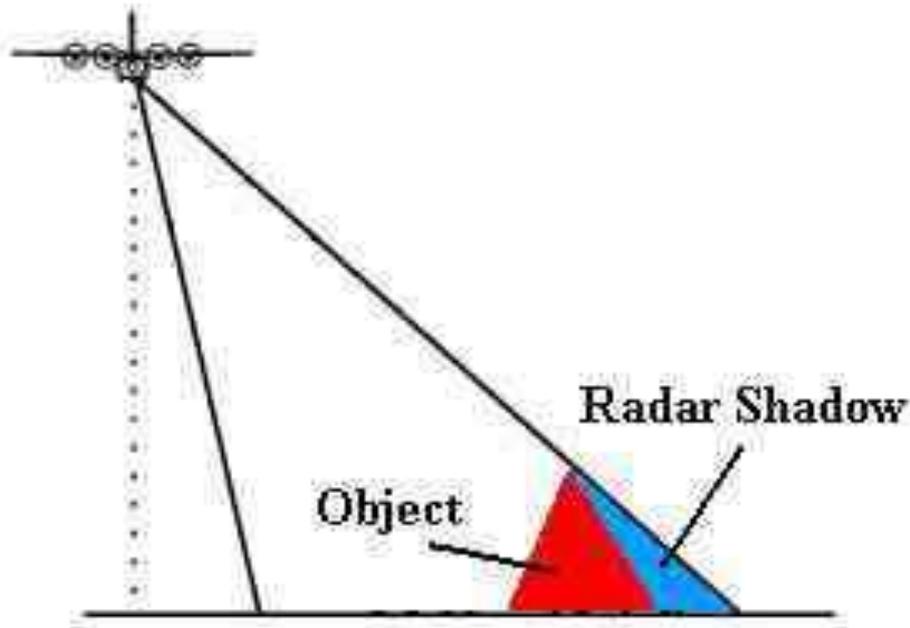
The response to radar energy by the target depends on three factors:

- **Surface structure and roughness**
- **Moisture content: electrical properties (dielectric constant)**
- **Radar - surface geometry relationship**



http://www.geog.ucsb.edu/~jeff/115a/remote_sensing/radar/radarroughness.jpg

Radar - surface geometry relationship: shadows



<http://hosting.soonet.ca/eliris/remotesensing/bl130lec13.html>

Some RADAR satellite systems (Date launched, Wavelength, Resolution)

Satellite	Launch date	Wavelength	Pixel size
SEASAT (USA)	1978	L	25m
SIR- A, B, C (USA) <u>JPL</u>	1981	L	40m (Shuttle Imaging Radar)
ERS (EUROPE)	1991, 1995	C	30m
JERS (JAPAN)	1992	L	25m
RADARSAT (CANADA)	1995	C	10-100m <u>CCRS - Radar</u>
ENVISAT (EUROPE)	2002		multiple

RADARSAT 2 (Canada) 2007 C 3-100m

Sentinel-1 (ESA) A/B 2014/2016 C 10m

RADARSAT - Canadian Space Agency

RADARSAT1: 1995-2013, RADARSAT2: 2007 ->

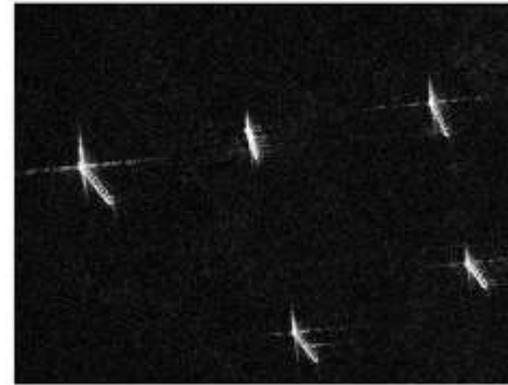
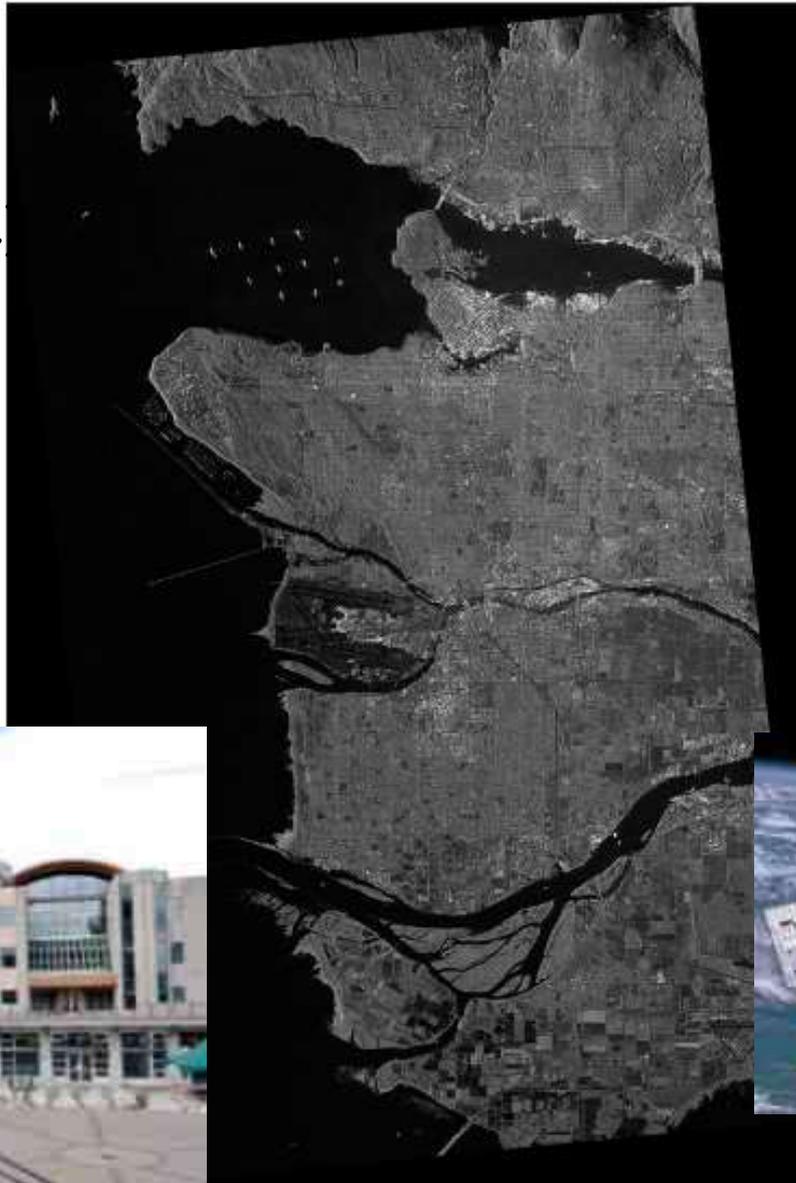
Bright = texture

Low = low dielectric constant (low texture)

Highest -
corner reflectors

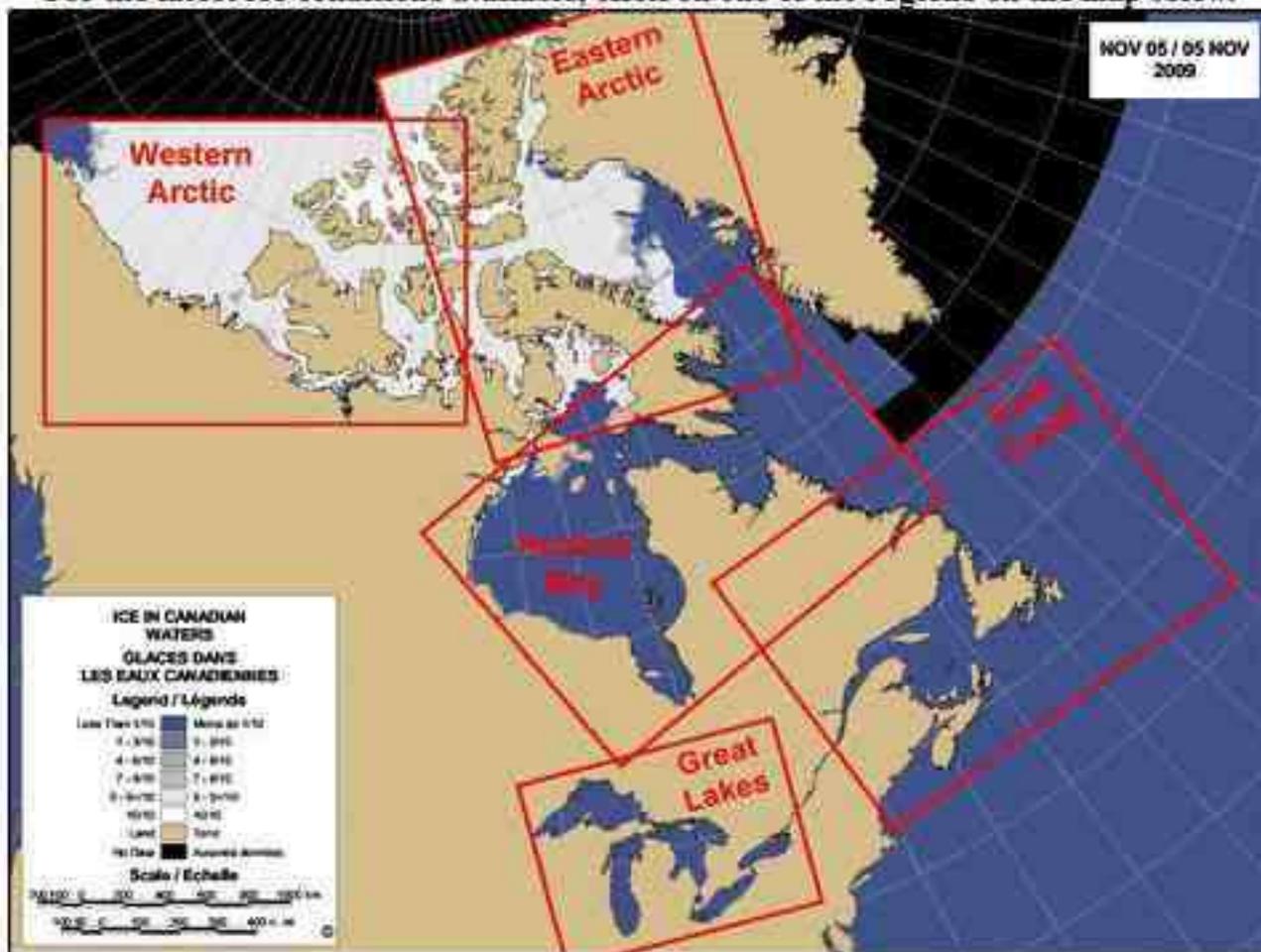
John S. MacDonald

Co-founder MacDonald-Dettwiler Associates /
UNBC Chancellor. 2008-15

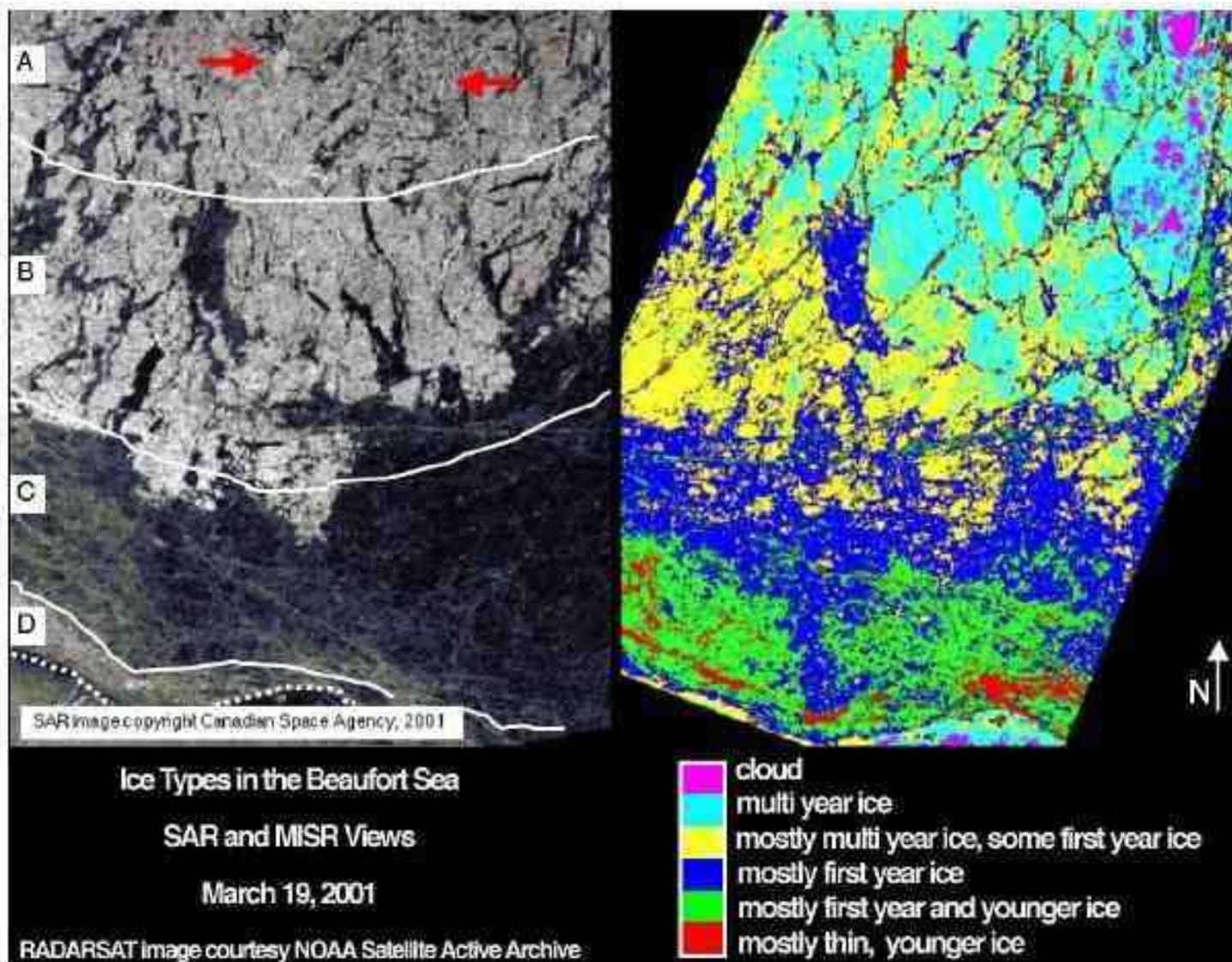


Please click [View](#) to view a full resolution version of "Ice in Canadian Waters" or [Animate](#) to view a recent daily animation.

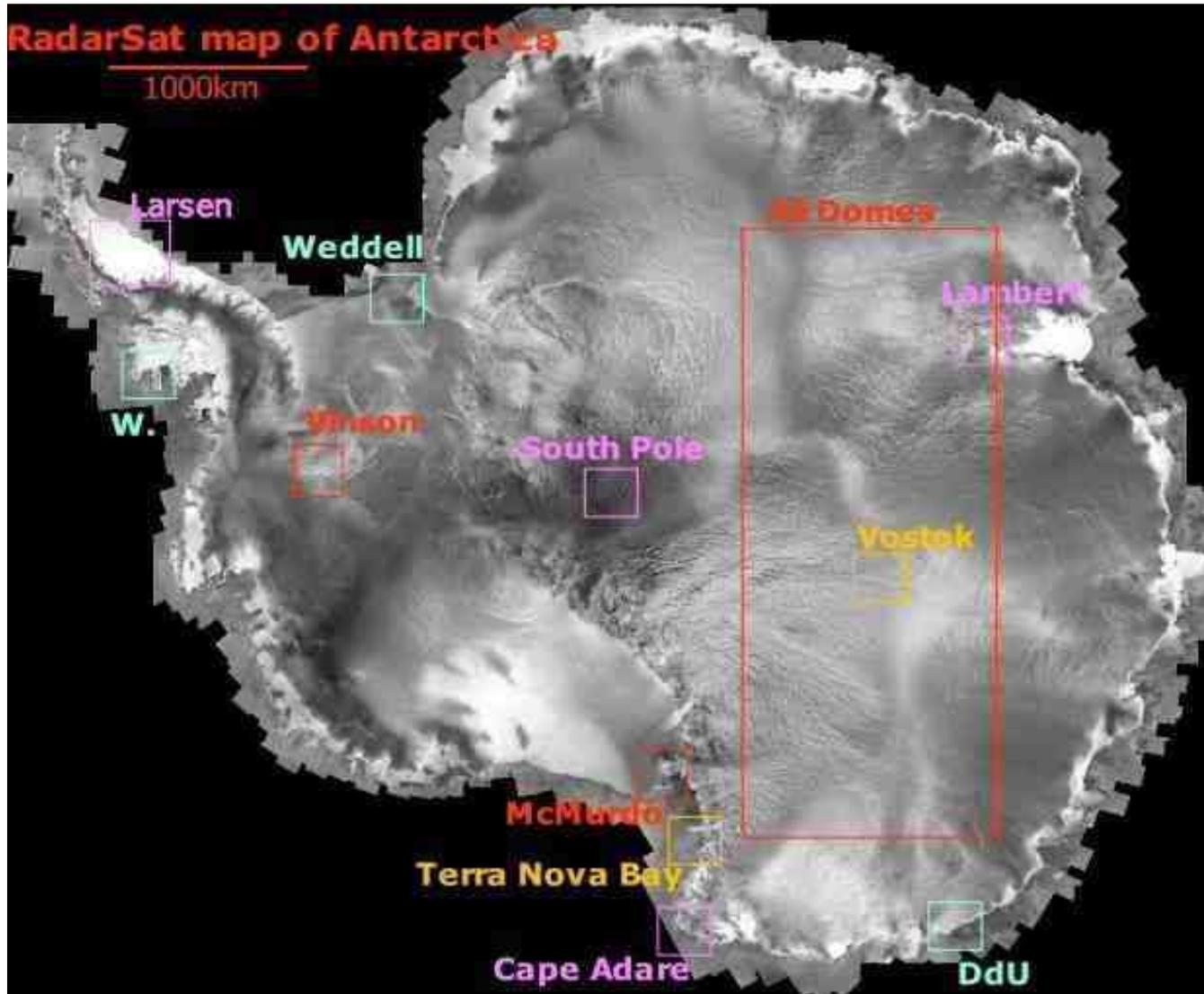
For the latest ice conditions available, click on one of the regions on the map below.



Ice Types in the Beaufort Sea, Alaska

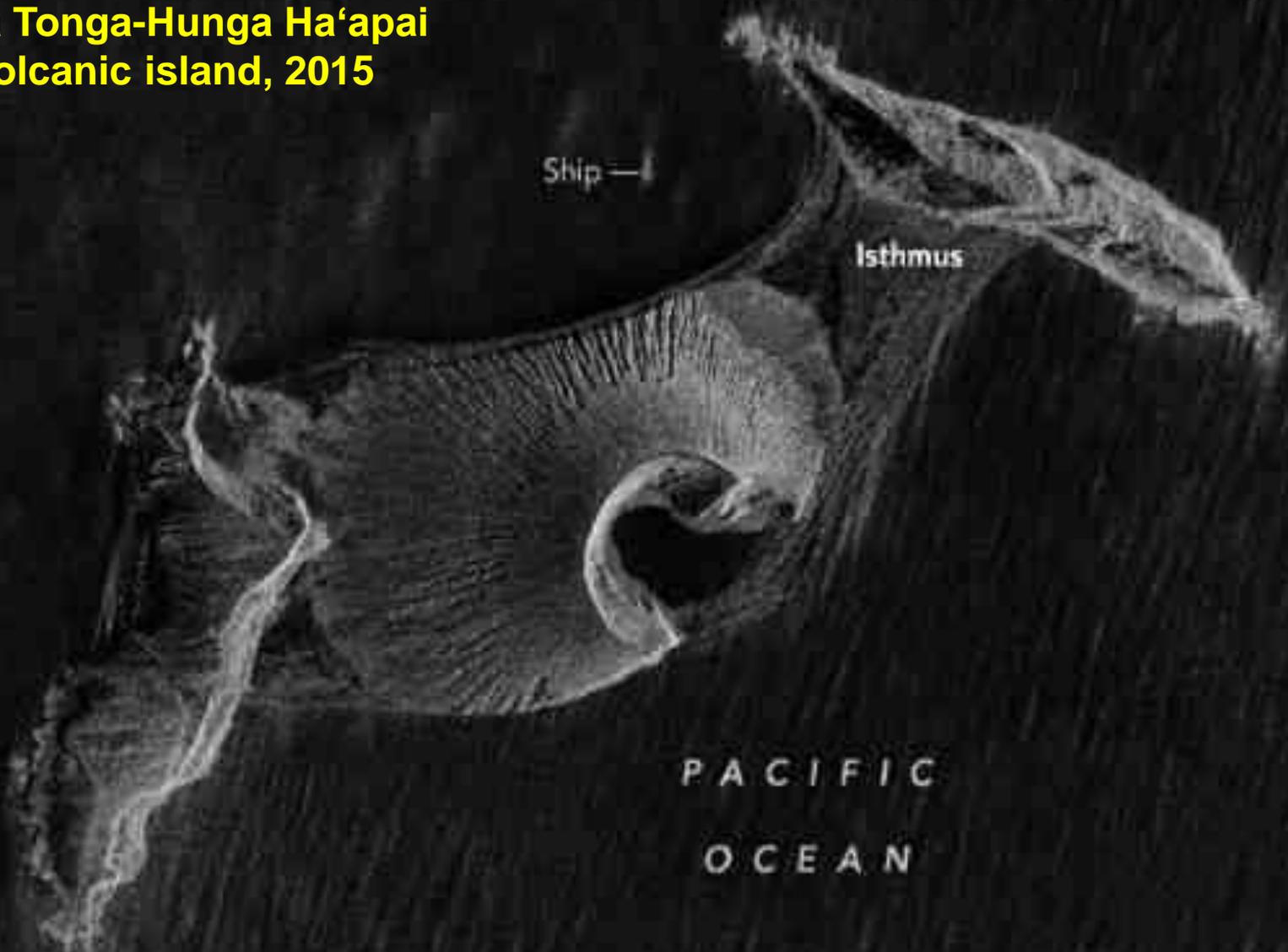


Canada produces the first complete image of Antarctica – we rock !
RADARSAT launched by NASA in exchange for complete map image



<http://ice-glaces.ec.gc.ca/App/WsvPageDsp.cfm?ID=1&Lang=eng>

**Hunga Tonga-Hunga Ha'apai
New volcanic island, 2015**



Ship —

Isthmus

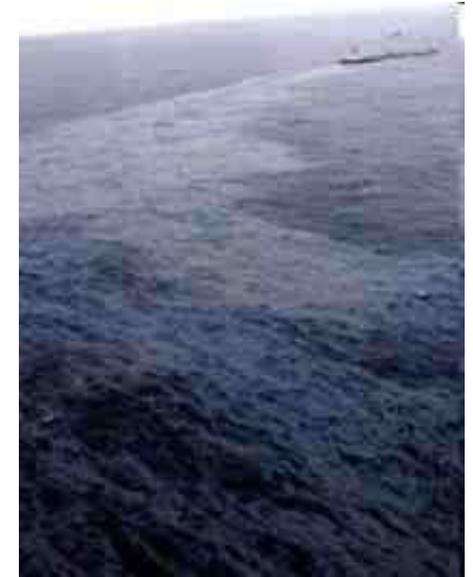
PACIFIC
OCEAN

Radarsat 2, October 7 2019



Oceanography – oil spills

http://earth.esa.int/ew/oil_slicks/wales_gb_96/



<http://www.mms.gov/tarprojectcategories/remote.htm>

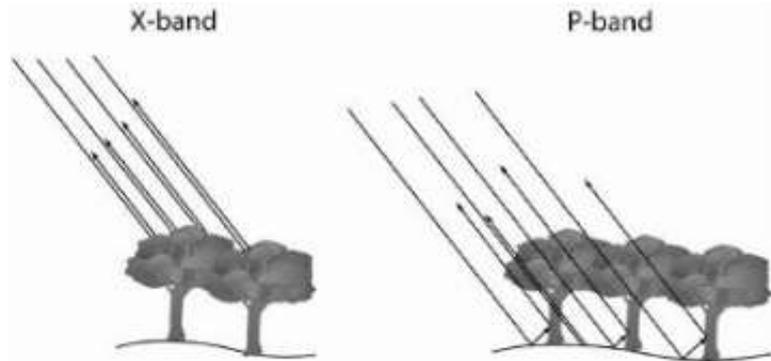
DEMs from RADAR e.g. Shuttle Radar Topographic Mission, 2000



The first 'near-global' high-res DEM (30-90m) – C / X bands used to create Google Earth

SIR-A in November, 1981. The color scene is a Landsat subimage of the Selma Sand Sheet in the Sahara Desert within northwestern Sudan.

Because dry sand has a low dielectric constant, long P radar waves penetrate these small particles by several metres



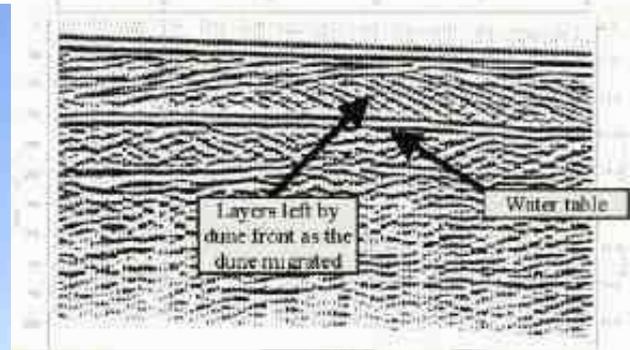
Ground penetrating radar (GPR)

is a tool for analysing underground objects (such as graves), gravel and sand layers, and other underground features e.g. buried tombs and archaeological structures

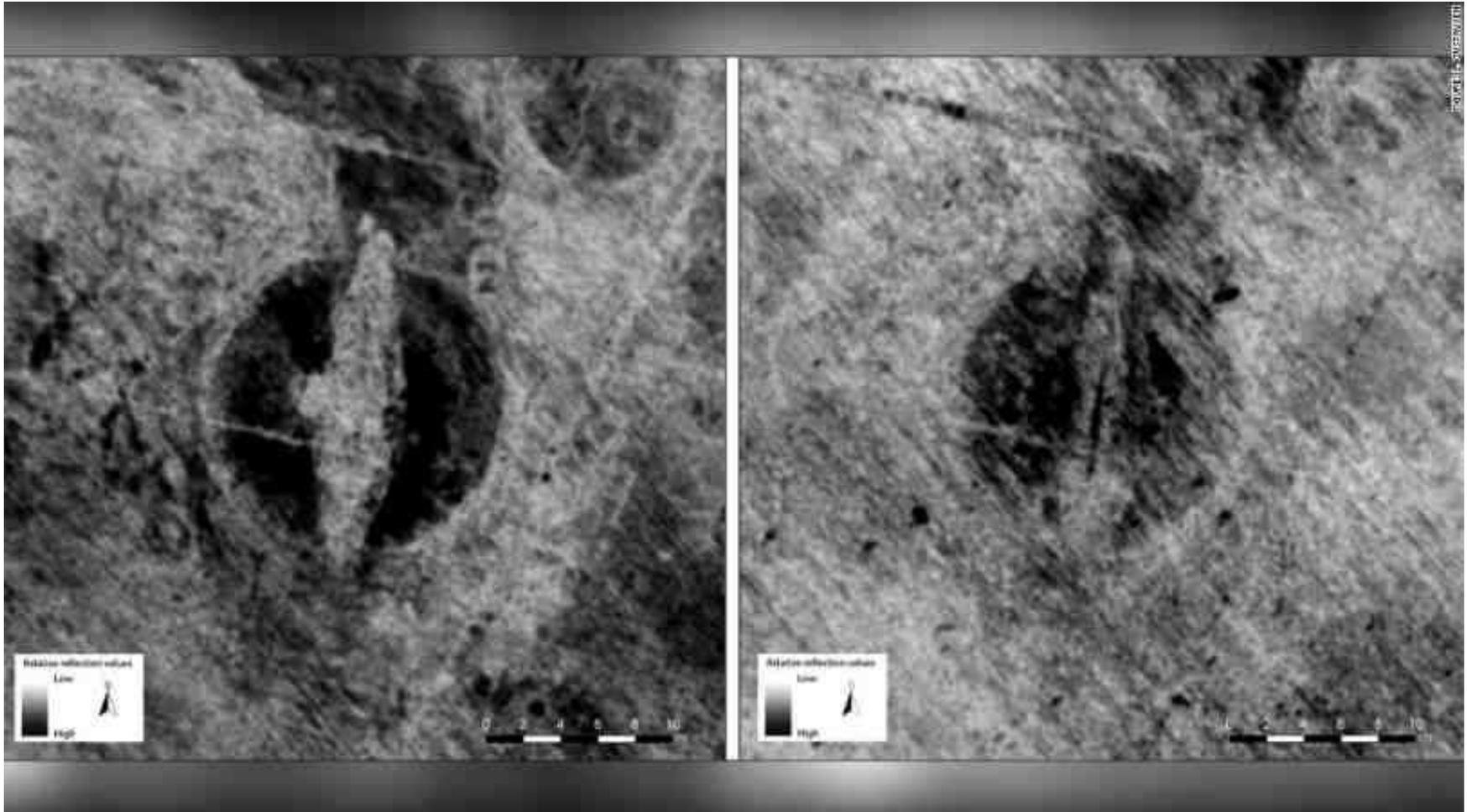
... but is this remote sensing ?

Also now possible from aircraft

https://www.nasa.gov/mission_pages/icebridge/index.html



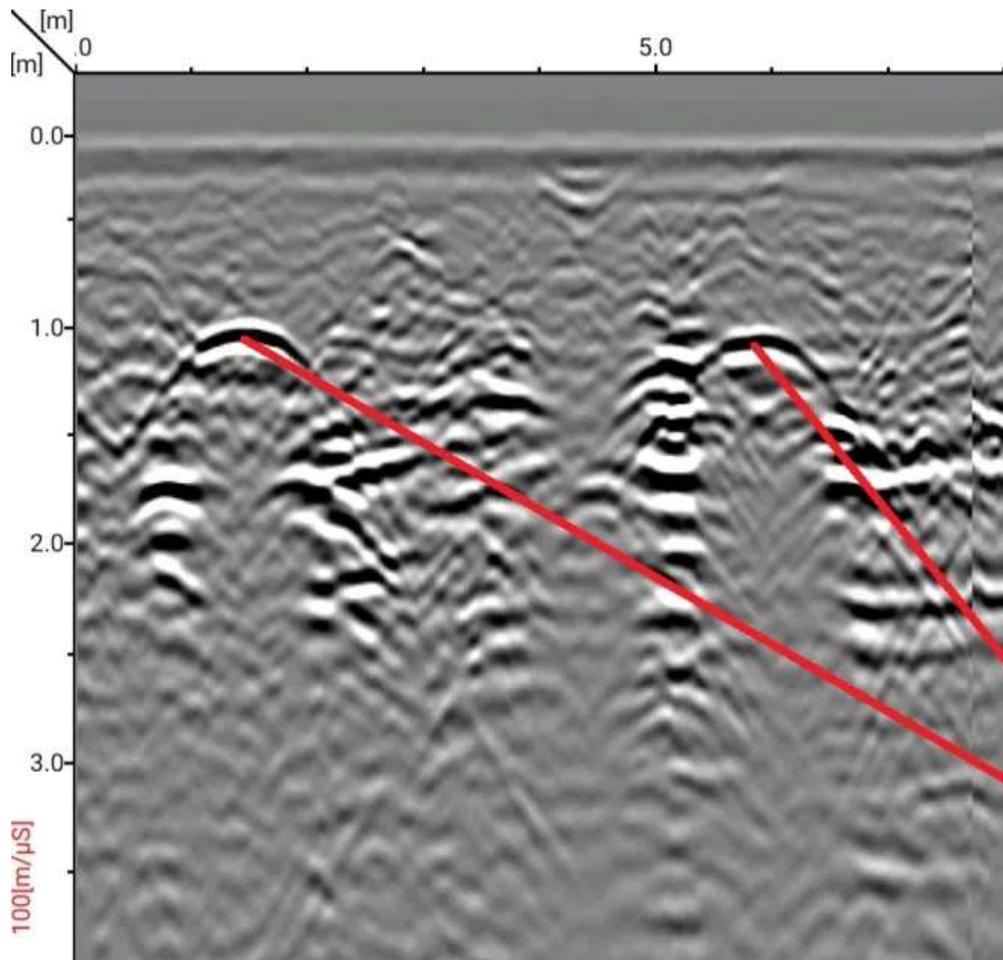
Nov 11, 2020: GPR discovers buried Viking ship Late Nordic Iron Age, 550 to 1050



<https://www.sciencetimes.com/articles/28180/20201112/viking-ship-discovered-norway-using-ground-penetrating-radar.htm>

Ground Penetrating Radar (GPR) discovers unmarked graves in residential schools: Canada 2021-22

<https://www.cbc.ca/news/canada/ground-radar-technology-residential-school-remains-1.6049776>



Reflections from known graves (coffins)